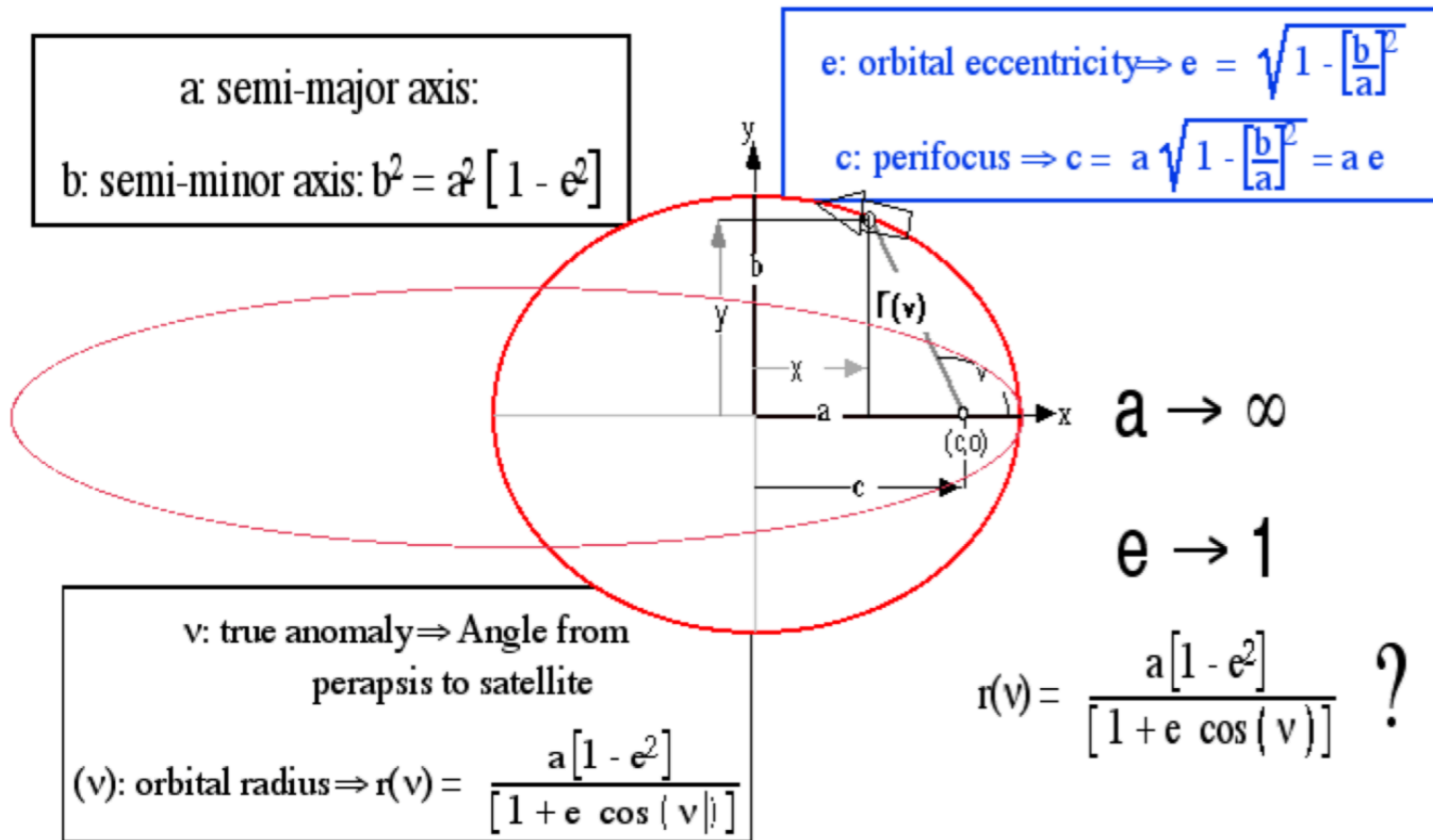


Addendum to Sections 2.1-2.3 The Open Conic Sections

What happens when $a \rightarrow \infty$ in an elliptical orbit?




Addendum to Sections 2.1-2.3 (cont'd)

The Open Conic Sections

What happens when $a \rightarrow \infty$ in an elliptical orbit?

$$R_{a \rightarrow \infty} = \left[\frac{a [1 - e^2]}{1 + e \cos [\nu_i]} \right]_{\substack{\lim \\ a \rightarrow \infty \\ e \rightarrow 1}} \text{ "indeterminant" }$$

• But $a [1 - e^2] = \underline{a [1 - e]} [1 + e_T] = \underline{R_{\text{perigee}}} [1 + e_T]$

$$R_{a \rightarrow \infty} = \left[\frac{a [1 - e^2]}{1 + e \cos [\nu_i]} \right]_{\substack{\lim \\ a \rightarrow \infty \\ e \rightarrow 1}} = \frac{2 R_{\text{perigee}}}{1 + \cos [\nu_i]}$$


Addendum to Sections 2.1-2.3 The Open Conic Sections

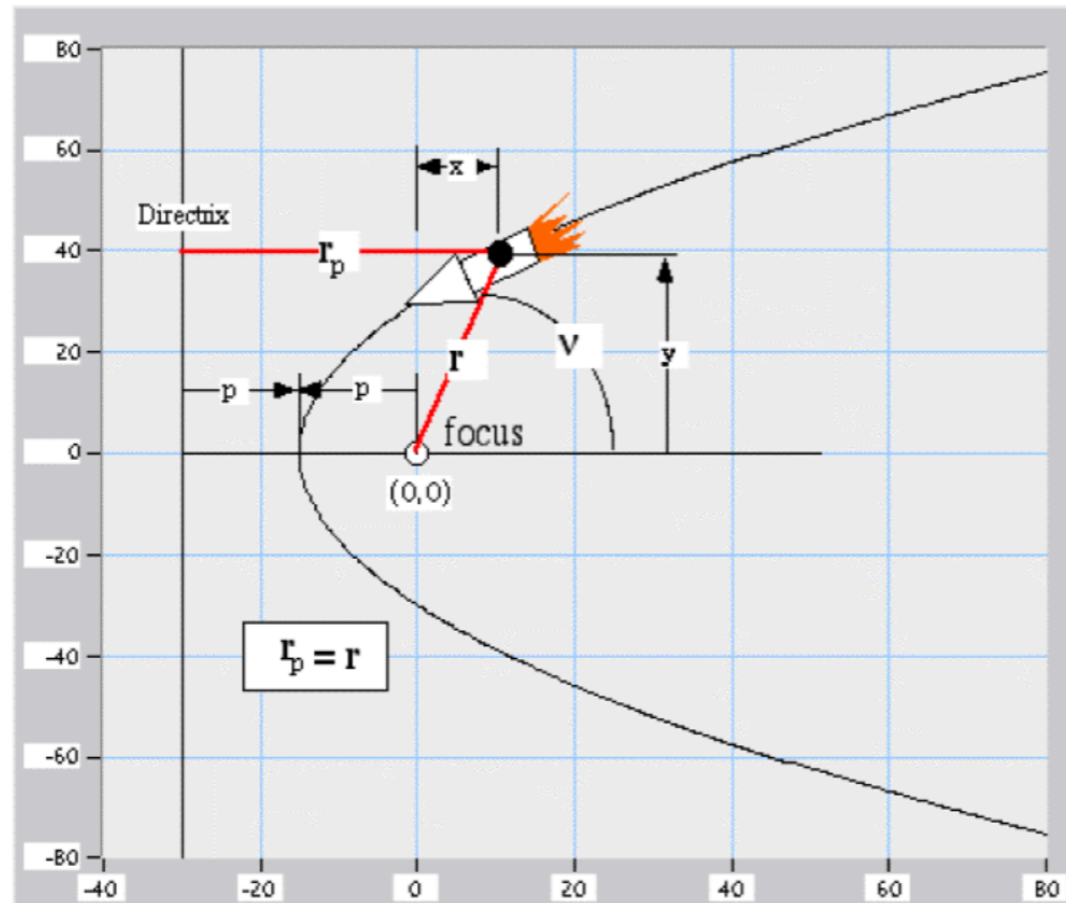
- $a \rightarrow \infty$ implies an "open" parabolic trajectory

$$R_{a \rightarrow \infty} = \frac{2 R_{\text{perigee}}}{1 - \cos [\nu_i]}$$

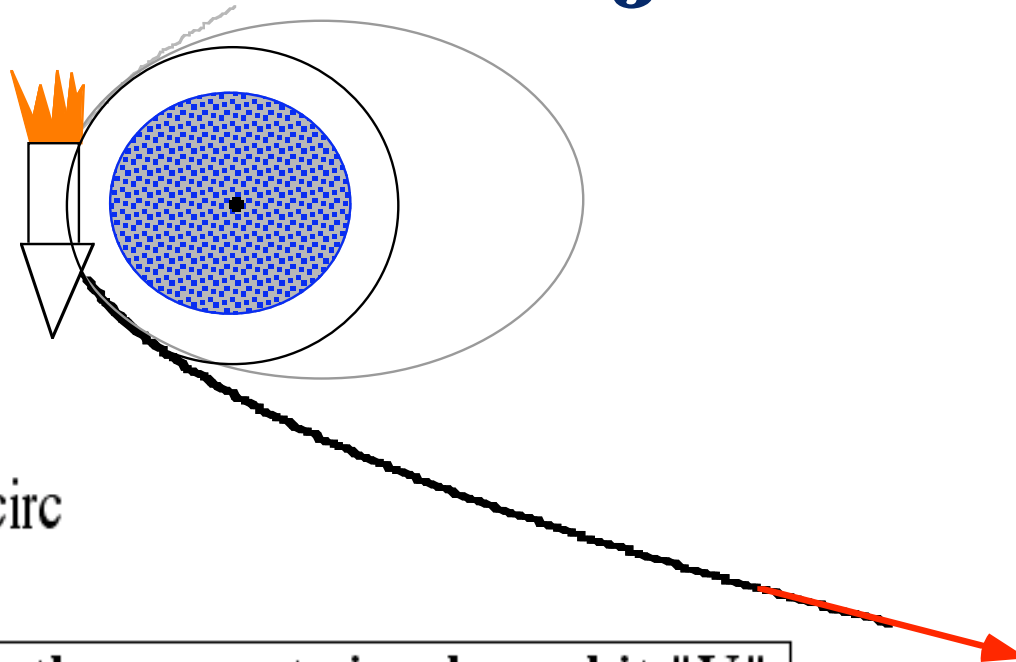
$$|\bar{V}|^2 = \mu \left[\frac{2}{r} - \frac{1}{a} \right]$$

o

$$|\bar{V}_{\text{esc}}| = \sqrt{\frac{2\mu}{r}}$$



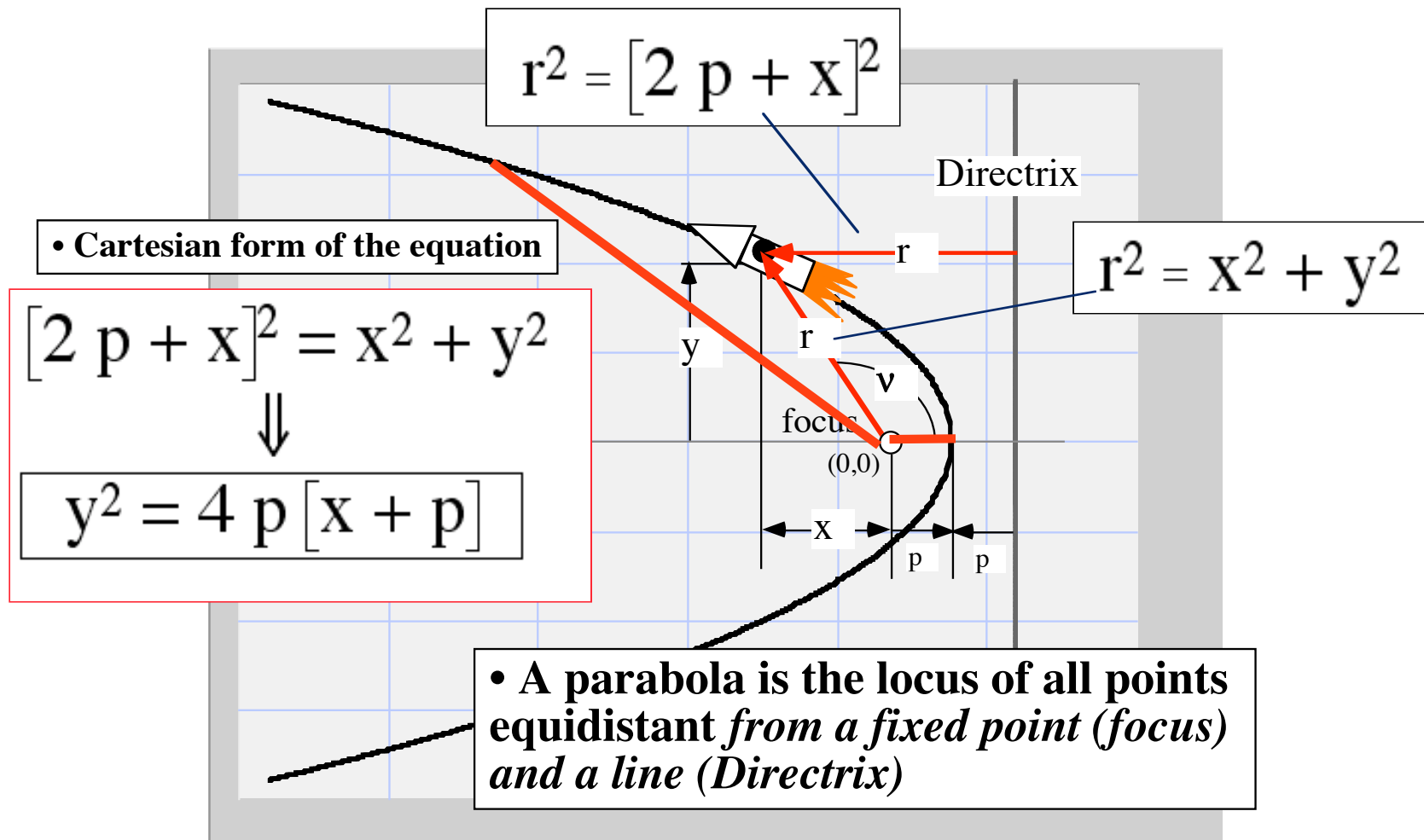
Parabolic Trajectories:



$$\Delta V_{\text{esc}} = [\sqrt{2} - 1] V_{\text{circ}}$$

- If we increase the current circular orbit "V" by a factor of $\sqrt{2}$; then the velocity becomes too great for the planet to contain the orbit
- Satellite *escapes* the planet on a parabolic trajectory

What is a Parabola?



Parabola Equation

Polar Form

$$\begin{array}{c}
 \boxed{\begin{array}{l} y = \mathbf{r} \sin(\nu) \\ x = -\mathbf{r} \cos(\nu) \end{array}} \Rightarrow \boxed{\begin{array}{l} y^2 = 4p[p + x] \\ \Downarrow \\ [\mathbf{r} \sin(\nu)]^2 = 4p[p - \mathbf{r} \cos(\nu)] \end{array}} \\
 \Downarrow \\
 \text{Use quadratic formula to solve} \quad [\sin^2(\nu)] \mathbf{r}^2 + [4p \cos(\nu)] \mathbf{r} - 4p^2 = 0
 \end{array}$$

Parabola Equation

Polar Form (cont'd)

- Solve for r using quadratic formula

$$a r^2 + b r + c = 0 \Rightarrow r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

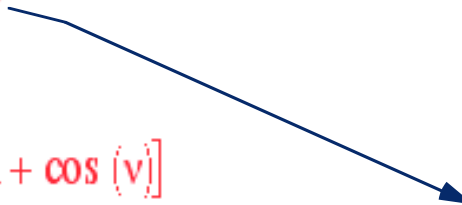


$$r = \frac{-4p \cos(\nu) \pm \sqrt{16p^2 \cos^2(\nu) + 16p^2 \sin^2(\nu)}}{2 \sin^2(\nu)}$$

- Use some trig identities to simplify

$$\cos^2(\nu) + \sin^2(\nu) = 1$$

$$\sin^2(\nu) = 1 - \cos^2(\nu) = [1 - \cos(\nu)][1 + \cos(\nu)]$$



$$r = \frac{-2p[\cos(\nu) \pm 1]}{[1 - \cos(\nu)][1 + \cos(\nu)]}$$

Parabola Equation

Polar Form (concluded)

- r must be ≥ 0 , therefore pick - sign

$$r = \frac{-2p[\cos(v) \pm 1]}{[1 - \cos(v)][1 + \cos(v)]} = \frac{-2p[\cos(v) - 1]}{[1 - \cos(v)][1 + \cos(v)]}$$

$$= \boxed{\frac{2p}{[1 + \cos(v)]}}$$

$$\{r_{\max} @ v = \pi\}, \frac{2p}{[1 + \cos(\pi)]} = \frac{2p}{[1 + (-1)]} = \infty$$

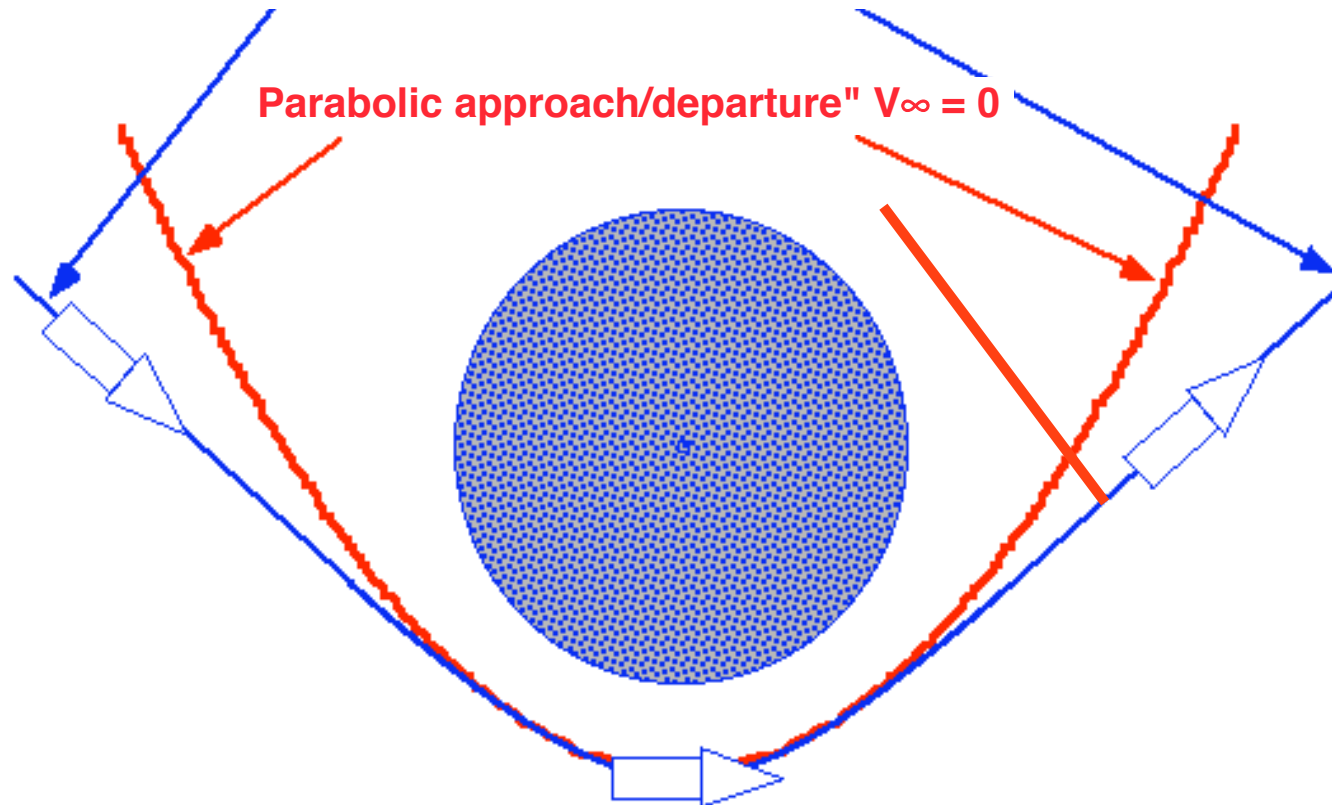
$$\{r_{\min} @ v = 0\}, \frac{2p}{[1 + \cos(0)]} = \frac{2p}{[1 + (1)]} = p$$

$$p = r_{\min}$$

Perigee!

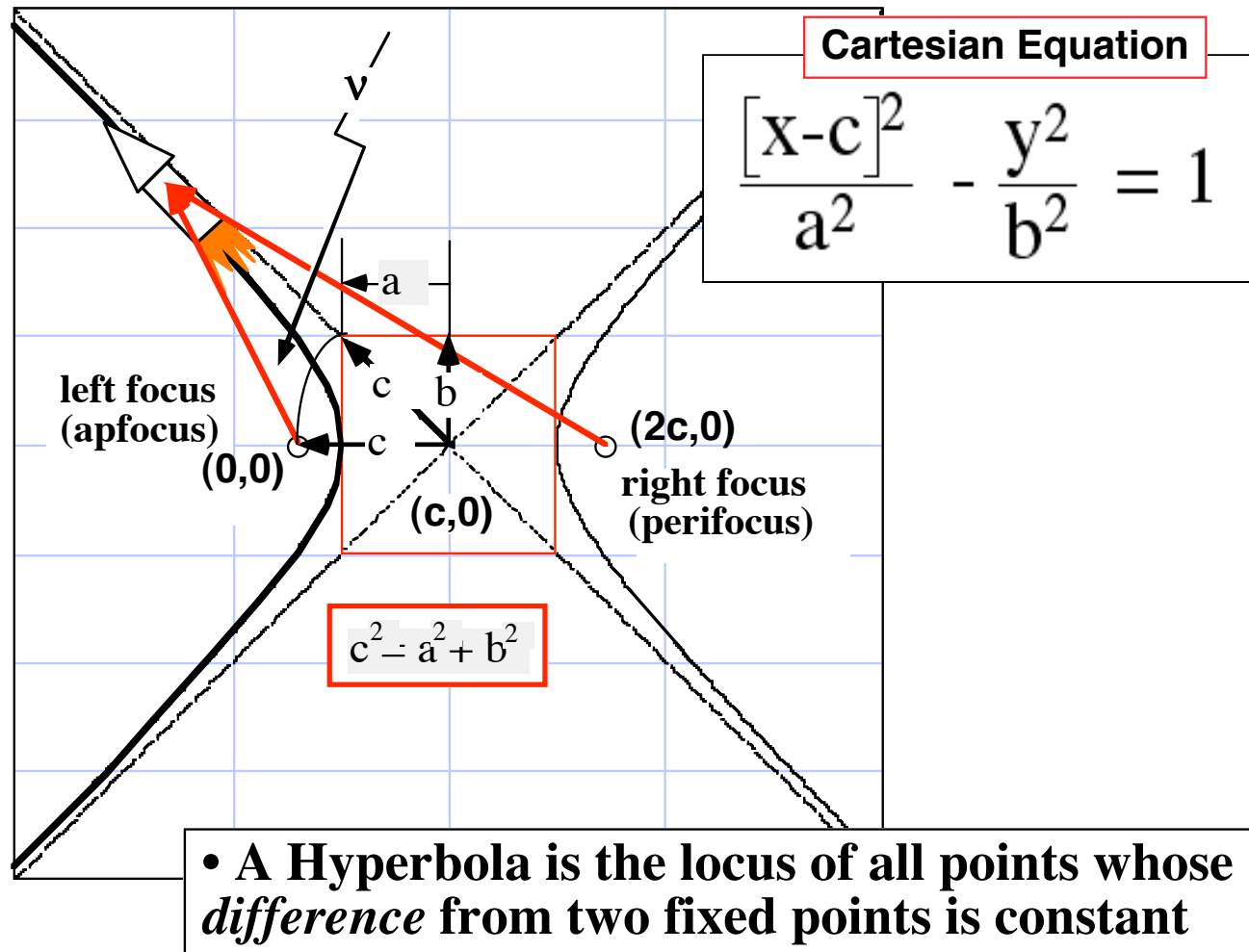
Hyperbolic Trajectories:

"Excess Hyperbolic Velocity" approach/departure" $V_{\infty} > 0$



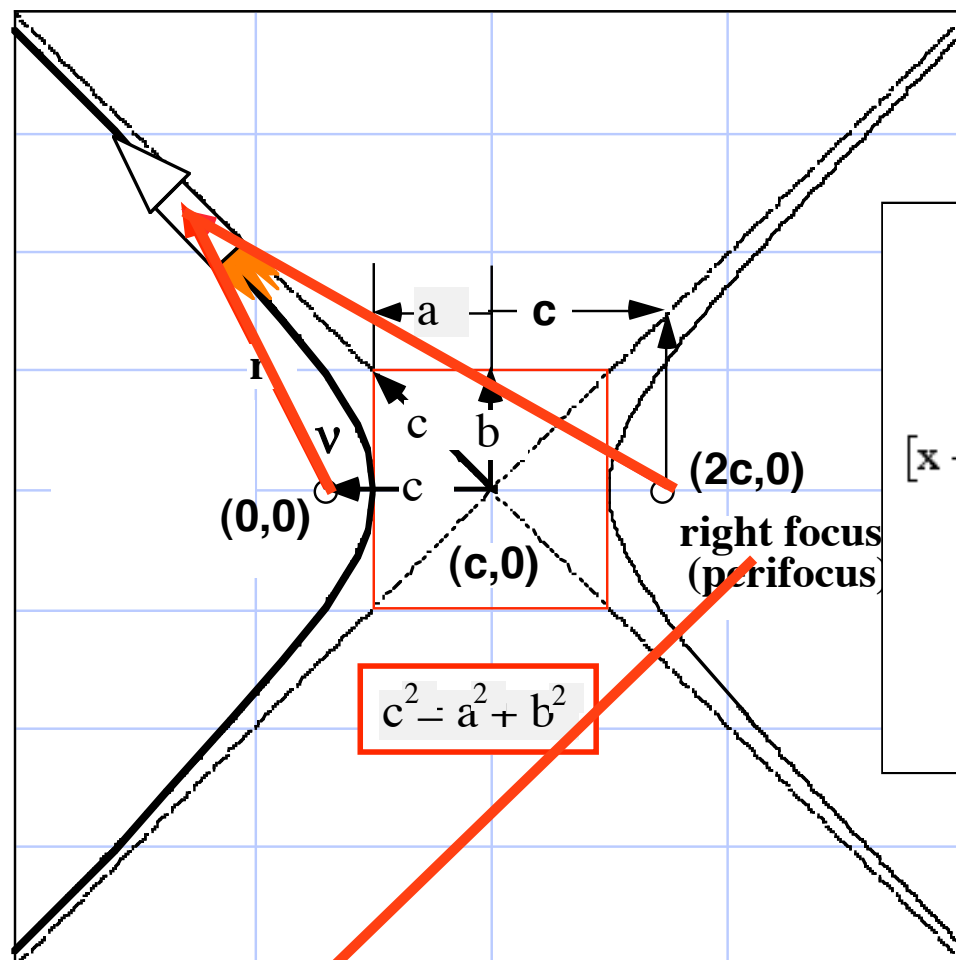
- If " V_{∞} " > 0 , then probe will approach and depart along a hyperbolic trajectory

What is a Hyperbola?



Hyperbolic Equation:

polar form



$$\begin{aligned}
 &\sqrt{[x+2c]^2 + y^2} - \sqrt{x^2 + y^2} = 2a \\
 &\Downarrow \\
 &[x+2c]^2 + y^2 = [2a + \sqrt{x^2 + y^2}]^2 \\
 &\Downarrow \\
 &[x+2c]^2 + y^2 = 4a^2 + 4a\sqrt{x^2 + y^2} + x^2 + y^2 \\
 &\Downarrow \\
 &xc + c^2 = a^2 + a\sqrt{x^2 + y^2} \\
 &\Downarrow \\
 &\boxed{\frac{c}{a}[x+c] - a = \sqrt{x^2 + y^2}}
 \end{aligned}$$

Hyperbolic Equation:

polar form (cont'd)

• From earlier analysis

$$\frac{c}{a} [x+c] - a = \sqrt{x^2 + y^2} = r$$

$$x = -r \cos(\nu)$$

$$\frac{c}{a} [c - r \cos(\nu)] - a = r$$

\Downarrow

$$r \left[1 + \frac{c}{a} \cos(\nu) \right] = \frac{c^2 - a^2}{a}$$

\Downarrow

$$\frac{c^2 - a^2}{a} = \frac{[a^2 + b^2] - a^2}{a} = \frac{b^2}{a}$$

\Downarrow

$$r = \frac{b^2}{a \left[1 + \frac{c}{a} \cos(\nu) \right]}$$

Hyperbolic Equation:

polar form (concluded)

- Defining the "*hyperbolic eccentricity*"

$$e_{\text{hyp}} = \sqrt{1 + \frac{b^2}{a^2}} \Rightarrow \frac{b^2}{a^2} = e_{\text{hyp}}^2 - 1$$

$$e_{\text{hyp}}^2 = \frac{a^2 + b^2}{b^2} = \frac{c^2}{b^2}$$

$$r = \frac{a \left[e_{\text{hyp}}^2 - 1 \right]}{\left[1 + e_{\text{hyp}} \cos(\nu) \right]}$$

Hyperbolic Asymptotes

- What is the behavior of a Hyperbola at "infinity"
i.e. along away from earth

$$\lim_{x, y \rightarrow \infty} \left[\frac{[x-c]^2}{a^2} - \frac{y^2}{b^2} = 1 \right] \Rightarrow \lim_{x, y \rightarrow \infty} \left[[x-c]^2 - \frac{a^2}{b^2} y^2 - a^2 = 0 \right]$$

↓

asymptotes

↓

$$[x-c]^2 = \frac{a^2}{b^2} y^2 \Rightarrow$$

$$y = \pm \frac{b}{a} [x-c]$$

Hyperbolic Behavior at ∞

asymptotes



$$y = \pm \frac{b}{a} [x - c]$$

$$\Rightarrow r \sin(\nu) = \pm \frac{b}{a} [-r \cos(\nu) - c]$$

$$\frac{\sin(\nu) + \left[\pm \frac{b}{a} \cos(\nu) \right]}{\lim \mathbf{r} \rightarrow \infty} = - \pm \frac{b}{a} \frac{c}{\mathbf{r}} = \sin(\nu_\infty) + \left[\pm \frac{b}{a} \cos(\nu_\infty) \right] = 0$$

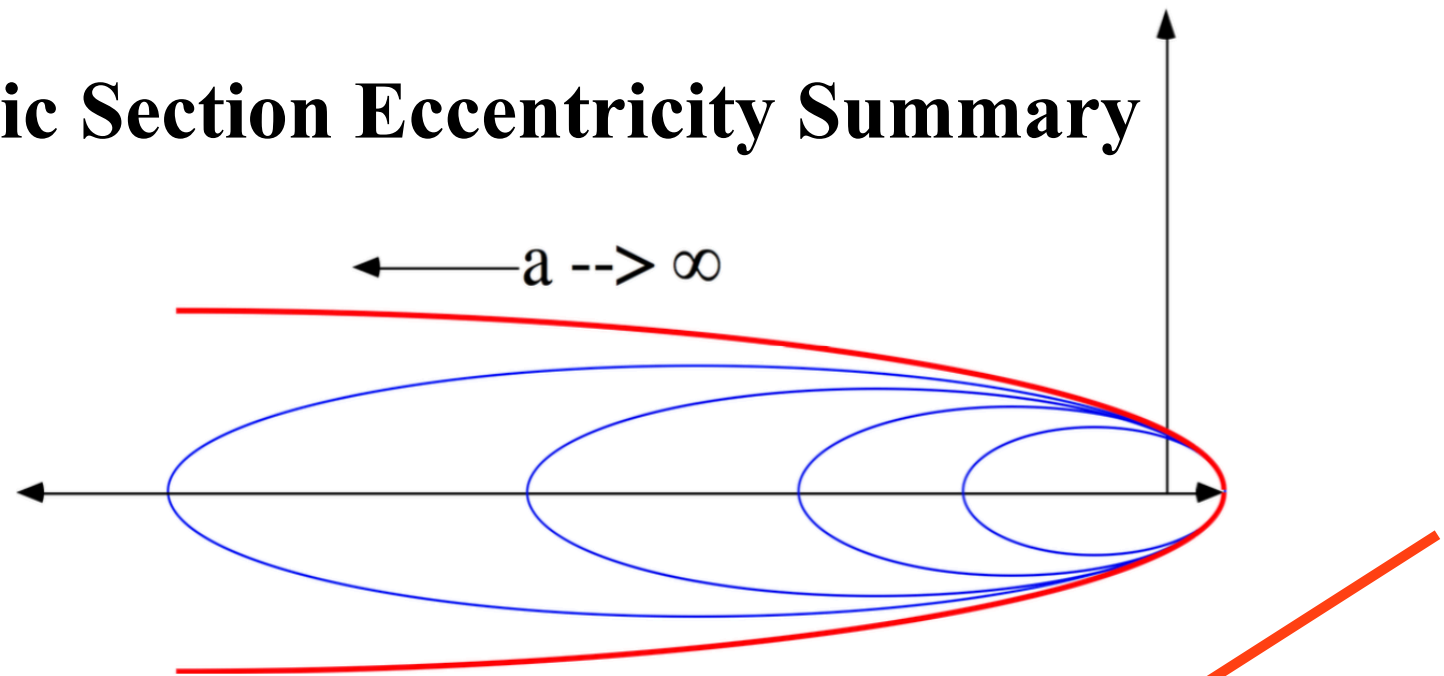


$$\tan(\nu_\infty) = \mp \frac{b}{a} = \mp \sqrt{e_{\text{hyp}}^2 - 1} \Rightarrow$$

departure: $\nu_\infty = \pi - \tan^{-1} \left[\sqrt{e_{\text{hyp}}^2 - 1} \right]$

arrival: $\nu_\infty = \pi + \tan^{-1} \left[\sqrt{e_{\text{hyp}}^2 - 1} \right]$

Conic Section Eccentricity Summary



- Orbital Energy is with regard to an escape trajectory!
- *Circular, Elliptical Orbit* $\rightarrow \epsilon_T < 1$
- *Parabolic (Escape) Trajectory* $\rightarrow \epsilon_T = 1$
- *Hyperbolic Trajectory* $\rightarrow \epsilon_T > 1$

See Appendix 2.3.2 for Hyperbolic Trajectory Proof

Vis-Viva Equation for All the Conic-Sections

Circle: $r = a \Rightarrow$

$$V = \sqrt{\mu \left[\frac{2}{a} - \frac{1}{a} \right]} = \sqrt{\frac{\mu}{a}}$$

Ellipse: $r = \frac{a [1 - e^2]}{[1 + e \cos(v)]} \Rightarrow$

$$V = \sqrt{\mu \left[\frac{2}{r} - \frac{1}{a} \right]}$$

Parabola: $r = \frac{2p}{[1 + \cos(v)]} \Rightarrow$

$$V = \sqrt{\mu \left[\frac{2}{r} - \frac{1}{\infty} \right]} = \sqrt{\frac{2\mu}{r}}$$

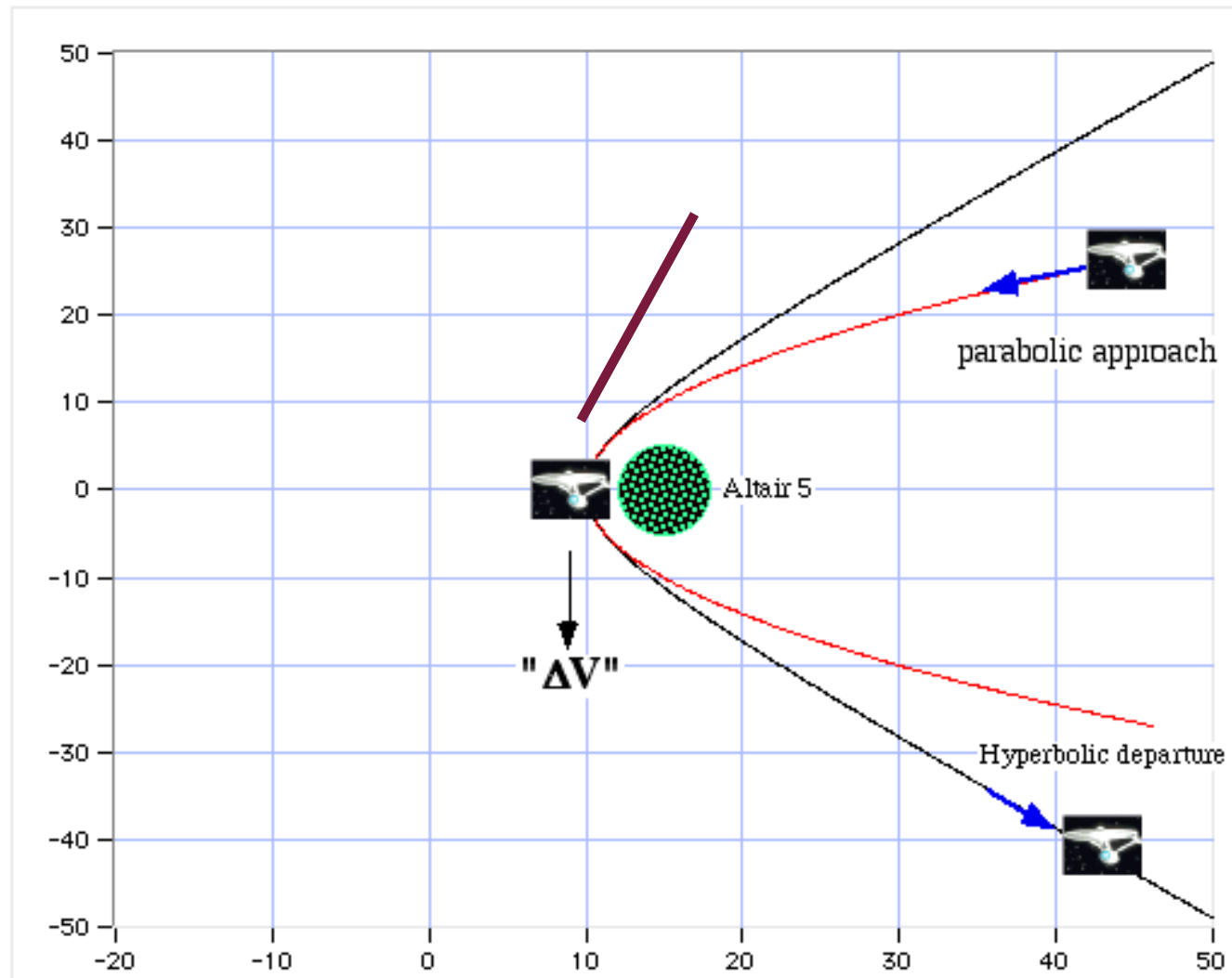
Hyperbola: $r = \frac{a [e_{hyp}^2 - 1]}{[1 + e_{hyp} \cos(v)]} \Rightarrow$

$$V = \sqrt{\mu \left[\frac{2}{r} + \frac{1}{a} \right]}$$

See Appendix 2.3.2 for Hyperbolic Trajectory Proof

Homework ⁴₃

Parabolic and Hyperbolic Trajectories



Homework

Parabolic and Hyperbolic Trajectories (cont'd)

- *United Federation of Planets* starship *Excelsior* approaches *Klingon* outpost *Altair 5* on a covert retaliatory bombing mission
- A cloaking device uses enormous energy & *Warp drive* is non-operational with the cloak engaged
- All maneuvering must be done on *impulse power* alone
- The *Excelsior* uses a gravity assisted *parabolic* approach trajectory to *Altair 5* in order to save on waning impulse power and insure a stealthy approach

Parabolic and Hyperbolic Trajectories (cont'd)

- After dropping photo-torpedos, Captain Checkov wants to get out the *sphere of influence* (SOI) of Altair 5 as fast as possible without being spotted
- The *Excelsior* has enough impulse power left for *one big burn* before, having to recharge the *dilithium crystals*
- The best way to "get out of town fast" is to fire impulse engines at closest approach to Altair 5 -- taking advantage of the gravity assist to give the highest approach speed without using impulse power and then use impulse power to depart on a hyperbolic trajectory at angle of 45 degrees
- What is the "*Delta-V*" required to depart on a *Hyperbolic* trajectory with an asymptotic departure angle of 45 degrees

Homework:

Parabolic and Hyperbolic Trajectories (cont'd)

- **Hint 1: For a Parabolic trajectory**

r is measured from the parabolic *focus* to the location of the *Excelsior*

- **Hint 2: For a Hyperbolic trajectory**

r is measured from the *right (perifocus) focus* to the location of the *Excelsior*

Homework:

Parabolic and Hyperbolic Trajectories (concluded)

- **Hint 3: For a Parabolic to Hyperbolic trajectory transfer**

$$|\Delta V| = V_h - V_p = V_p \left[\frac{V_h}{V_p} - 1 \right]$$

- **Hint 4: At closest approach, the distance from the *parabolic focus* to the *Excelsior* must equal the distance from the *Hyperbolic right focus* to the *Excelsior***
- **Your answer should be expressed in terms μ and r_{\min} (closest approach distance)**

