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## Intro to Astrodynamics

## Introduction to Astrodynamics: Gravitational Fields, Potential and Kinetic Energy, and the Vis-Viva Equation

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#### Kinematics versus Dynamics

• Up to now we have mostly dealt with orbital motions from a kinematics point of view ... I.e. Kepler's laws Were used simply as descriptors of orbital motion

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Kepler

... but there are no Physics (I.e. Isaac Newton) Involved

• Kepler derived his laws of planetary motion by Empirical observation only.





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#### Summary: Kepler's Laws

• Kepler's First Law: In a two body universe, orbit of a satellite is a conic section with the Earth centered at one of the focii











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Kepler's Laws (cont'd)

• **Kepler's Third Law:** In a two body universe, square of the period of any object revolving about the Earth is in the same ratio as the cube of its mean distance



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#### **Time of Flight Graphs (cont'd)**





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#### **Propagation of Orbital Position**





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Velocity Vector, Elliptical Orbit



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## Kepler's third law(corollary)

 In the process of demonstrating Kepler's third law, we have also indirectly demonstrated that, for an elliptical orbit the orbital speed (Magnitude of the Velocity Vector) is

$$\overline{\mathbf{V}}|^2 = \frac{\mathbf{I}^2}{\mathbf{a}[1-\mathbf{e}^2]} \left[\frac{2}{\mathbf{r}} - \frac{1}{\mathbf{a}}\right] = \mathbf{\mu} \left[\frac{2}{\mathbf{r}} - \frac{1}{\mathbf{a}}\right]$$

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### Isaac Newton



Newton

• Sir Isaac Newton used his new calculus and laws of motion and gravitation to show that Kepler was right.

• One day in 1682 he came up to his friend, Edmund Halley, and casually mentioned to him that he'd proved that, with a  $1/r^2$  force law like gravity, planets orbit the sun in the shapes of conic sections.

• This undoubtedly took Halley aback, as Newton had just revealed to him the nature of the Universe (at least the Universe as it was known then).

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Newton ...

•Halley then pressed Newton to publish his findings, but he realized that he'd forgotten the proof.

• After struggling to remember how he had proved the t heorem, he published his work and it later appeared in full form in his classic work: *Philosophiae Naturalis Principia Mathematica* -- commonly known as the Principia -- published in1687.

• OK ... let walk down Newton's path to enlightenment!



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## **Gravitational Physics**

 Now by introducing a bit of "gravitational physics" we can unify the entire mathematical analysis



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You've seen it before .....

# Gravitational Physics

 Constant G appearing in Newton's law of gravitation, known as the universal gravitational constant.

Numerical value of G

$$G = 6.672 \text{ x } 10^{-11} \frac{\text{Nt-m}^2}{\text{kg}^2} = 3.325 \text{ x } 10^{-11} \frac{\text{lbf-ft}^2}{\text{lbm}^2}$$

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#### UNIVERSIT **Gravitational Potential** Energy $\infty$ •Gravitational potential energy equals the amount of energy released when the Big Mass M pulls the small mass *m* at infinity to a location r in the vicinity of a mass M Energy of position m $P_{E_{grav}} \equiv E_{released} = \int_{\infty}^{1} \mathbf{F} \cdot d\mathbf{r} =$ /**r** $\frac{G M m}{r^2} dr = -G M m \left[\frac{1}{r} - \frac{1}{\infty}\right] = \left[-\frac{G M m}{r}\right]$ 19 MAE 5540 - Propulsion Systems

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## "Work and Potential Energy"

#### Work can be loosely defined as the ability of an applied force to do something useful

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### Mechanical "Work"

 Inner product of the applied Force vector and the change in the position vector caused by the applied force







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#### Total (Mechanical) Energy of the Satellite

• For a satellite orbiting in a gravity field outside of the atmosphere (no external drag) there are no dissipative forces acting, thus the total energy of the satellite is constant throughout the orbit







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#### **Total Specific Energy**

#### • First Calculate Radius of Curvature of Ellipse



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#### Total Specific Energy (2)

#### • Next Calculate Radius of Curvature of Ellipse at Perigee



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## UNIVERSI **Total Specific Energy** (3) $\varepsilon_{\rm T} = \left| \frac{V^2}{2} - \frac{\mu}{r} \right|$ $\varepsilon_{\rm T}$ constant everywhere in orbit • Now look at perigee condition force balance $\varepsilon_{\rm T} = {\rm constant}$ Vapogee / perigee $\mathbf{r}_{a}$ $\dot{r}_{perigee} = 0 \rightarrow \text{Centrifugal force} = \text{Gravitational force} @ Apogee$



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### **Total Specific Energy** (4)

- $\varepsilon_{\rm T} = \left| \frac{{\rm V}^2}{2} \frac{\mu}{{\rm r}} \right| \qquad \varepsilon_{\rm T} \text{ constant everywhere in orbit}$
- Now look at perigee condition force balance

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#### **Total Specific Energy** (5)

 $\varepsilon_{\rm T} = \left[\frac{V^2}{2} - \frac{\mu}{r}\right]$ 

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 $\varepsilon_{\rm T}$  constant everywhere in orbit

... at perigee conditions

$$V_{perigee}^{2} = \frac{\mu \cdot (1+e)}{a \cdot (1-e)}$$

• Sub Into Energy Equation

Energy Equation  

$$\frac{V_{perigee}^{2}}{2} - \frac{\mu}{r_{perigee}} = \varepsilon = \frac{\mu \cdot (1+e)}{2 \cdot a \cdot (1-e)} - \frac{\mu}{a \cdot (1-e)} = \frac{\mu}{2a} \cdot \left(\frac{(1+e)}{(1-e)} - \frac{2}{(1-e)}\right) = \frac{\mu}{2a} \cdot \left(\frac{1+e-2}{1-e}\right) = \frac{\mu}{2a} \cdot \left(\frac{e-1}{1-e}\right) = -\frac{\mu}{2a}$$

$$\frac{\mu}{MAE 5540 - Propulsion Systems}$$

$$32$$

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### UtahState UNIVERSIT **Total Specific Energy** (6) $\varepsilon_{\rm T} = \left| \frac{V^2}{2} - \frac{\mu}{r} \right|$

• Similarly @ Apogee condition force balance  $\varepsilon_{\rm T} = {\rm constant}$ Vapogee Vperigee  $\mathbf{r}_{a}$  $\dot{r}_{apogee} = 0 \rightarrow \text{Centrifugal force} = \text{Gravitational force} @ Apogee$  $\rightarrow r_{apogee} = a \cdot (1+e)$  $V_{apogee}^{2} = \frac{\mu \cdot R_{c_{apogee}}}{r_{apogee}^{2}} = \frac{\mu \cdot (1+e)(1-e)}{a \cdot (1+e)^{2}} = \frac{\mu \cdot (1-e)}{a \cdot (1+e)}$ 33 MAE 5540 - Propulsion Systems

 $\varepsilon_{T}$  constant everywhere in orbit

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#### **Total Specific Energy** (5)

 $\varepsilon_{\rm T} = \left[\frac{{\rm V}^2}{2} - \frac{\mu}{{\rm r}}\right]$ 

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 $\varepsilon_{\rm T}$  constant everywhere in orbit

... at perigee conditions  $V_{apogee}^2 = \frac{\mu \cdot (1-e)}{a \cdot (1+e)}$ 

• Sub Into Energy Equation





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#### Orbital Energy Review Total (Mechanical) Energy of the Satellite

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• For a satellite orbiting in a gravity field outside of the atmosphere (no external drag) there are no dissipative forces acting, thus the total energy of the satellite is constant throughout the orbit



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### Total Specific Energy (concluded)

 Solving for V, the elliptical orbit velocity magnitude is:



 Newton referred to this equation as the "vis-viva" equation

.... literally translated ... "it's alive"

• Extremely important relationship shows that orbital speed is inversely proportional to square root of the orbital radius











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#### **Postscript:Escape Velocity**

What happens when  $a \rightarrow \infty$  in an elliptical orbit?







#### **Postscript:Escape Velocity** (cont'd)

• a->∞ implies an "open" parabolic trajectory



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• Orbital Energy is with regard to an escape trajectory!

•Circular, Elliptical Orbit $\rightarrow \varepsilon_T < 0$ •Parabolic (Escape) Trajectory $\rightarrow \varepsilon_T = 0$ •Hyperbolic Trajectory $\rightarrow \varepsilon_T >= 0$ 

See Appendix 2.3.2 for Hyperbolic Trajectory Proof

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Vis-Viva Equation for All the Conic-Sections

Circle: 
$$\mathbf{r} = \mathbf{a} \Rightarrow$$
  
Ellipse:  $\mathbf{r} = \frac{\mathbf{a} \begin{bmatrix} 1 - \mathbf{e}^2 \end{bmatrix}}{\begin{bmatrix} 1 + \mathbf{e} \cos(\mathbf{v}) \end{bmatrix}} \Rightarrow$   
Parabola:  $\mathbf{r} = \frac{2 p}{\begin{bmatrix} 1 + \cos(\mathbf{v}) \end{bmatrix}} \Rightarrow$   
Hyperbola:  $\mathbf{r} = \frac{\mathbf{a} \begin{bmatrix} \mathbf{e}_{hyp}^2 - 1 \end{bmatrix}}{\begin{bmatrix} 1 + \mathbf{e}_{hyp} \cos(\mathbf{v}) \end{bmatrix}} \Rightarrow$   
 $\mathbf{V} = \sqrt{\mu \begin{bmatrix} \frac{2}{r} - \frac{1}{\infty} \end{bmatrix}} = \sqrt{\frac{2\mu}{r}}$   
 $\mathbf{V} = \sqrt{\mu \begin{bmatrix} \frac{2}{r} - \frac{1}{\infty} \end{bmatrix}} = \sqrt{\frac{2\mu}{r}}$ 

See Appendix 2.3.2 for Hyperbolic Trajectory Proof

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## Homework <del>3</del>

#### Parabolic and Hyperbolic Trajectories



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# Homework

Parabolic and Hyperbolic Trajectories (cont'd)

• United Federation of Planets starship Excelsior approaches Klingon outpost Altair 5 on a covert retaliatory bombing mission

• A cloaking device uses enormous energy & *Warp drive* is non-operational with the cloak engaged

• All maneuvering must be done on *impulse power* alone

• The *Excelsior* uses a gravity assisted *parabolic* approach trajectory to *Altair 5* in order to save on waning impulse power and insure a stealthy approach

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#### Parabolic and Hyperbolic Trajectories (cont'd)

- After dropping photo-torpedos, Captain Checkov wants to get out the *sphere of influence* (SOI) of *Altair 5* as fast as possible without being spotted
- The *Excelsior* has enough impulse power left for *one* big burn before, having to recharge the dilithium crystals

• The best way to "get out of town fast" is to fire impulse engines at closest approach to Altair 5 -- taking advantage of the gravity assist to give the highest approach speed without using impulse power and then use impulse power to depart on a hyperbolic trajectory at angle of 45 degrees

• What is the "*Delta-V*" required to depart on a *Hyperbolic* trajectory with an asymptotic departure angle of 45 degrees

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# Homework:

#### **Parabolic and Hyperbolic Trajectories** (cont'd)

• Hint 1: For a Parabolic trajectory

 $\Gamma$  is measured from the parabolic *focus* to the location of the *Excelsior* 

• Hint 2: For a Hyperbolic trajectory

**r** is measured from the *right (perifocus) focus* to the location of the *Excelsior* 

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# Homework:

Parabolic and Hyperbolic Trajectories (concluded)

• Hint 3: For a Parabolic to Hyperbolic trajectory transfer

$$\Delta V'' = V_h - V_p = V_p \left[ \frac{V_h}{V_p} - 1 \right]$$

• Hint 4: At closest apprach, the distance from the *parabolic focus* to the *Excelsior* must equal the distance from the *Hyperbolic right focus* to the *Excelsior* 

• Your answer should be expressed in terms  $\mu$  and  $r_{min}$  (closest approach distance)



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#### Appendix 2.3: Total Specific Orbital Energy Alternate Derivation



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• Solving for  $\omega_p^2$ 

$$\omega_p^2 = 2 \,\mu \left[ \frac{r_a}{r_p} \right]^2 \frac{1}{\left[ r_p + r_a \right]} \left[ \frac{1}{r_a r_p} \right]$$

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#### Appendix 2.3.2: Total Specific Orbital Energy for Hyperbolic Trajectory

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# How about for a hyperbolic trajectory?

• Conservation of Energy and Angular Momentum still hold .... So ....



# Machanical & Flarospace UtahState Engineering UNIVERSITY Hyperbolic Energy • Recall, from the "First Law" derivation $\omega \mathbf{r} = \frac{\mu}{|\mathbf{I}|} [1 + B\cos(\mathbf{v})] \Rightarrow B = \frac{|\mathbf{I}|^2}{\mu} \frac{1}{r_p} - 1$ $\omega \mathbf{r} = \frac{\mu}{|\boldsymbol{I}|} \left[ 1 + \left( \frac{|\boldsymbol{I}|^2}{\mu} \frac{1}{r_p} - 1 \right) \cos(\boldsymbol{v}) \right]$ 59

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#### Hyperbolic Energy (continued)

• At Perigee, V=0

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#### Hyperbolic Energy (continued)

• Substituting into energy equation



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## Hyperbolic Energy (continued)

• But from the General Form for the Conic section



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Hyperbolic Energy (continued)

Evaluating at perigee

 $r_{p}^{(\text{hyp})} = a \begin{bmatrix} e_{hyp} - 1 \end{bmatrix} = \frac{\mu}{\begin{bmatrix} 1 + e_{hyp} \cos(0) \end{bmatrix}}$  $\downarrow \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix}^{2} = \mu a \begin{bmatrix} e_{hyp}^{2} - 1 \end{bmatrix}$ 

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#### Hyperbolic Energy (continued)

• Substituting into the Energy equation



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