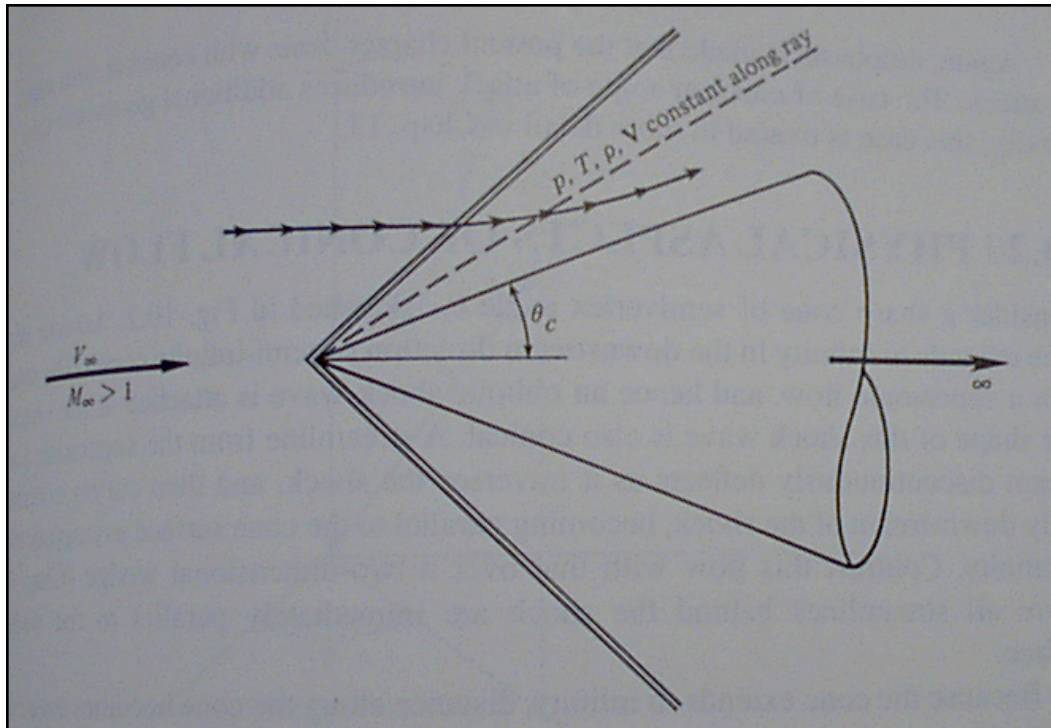


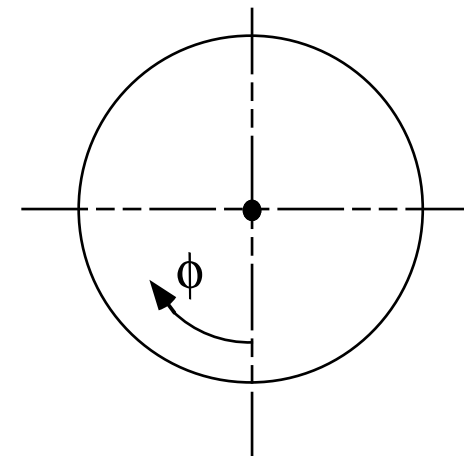
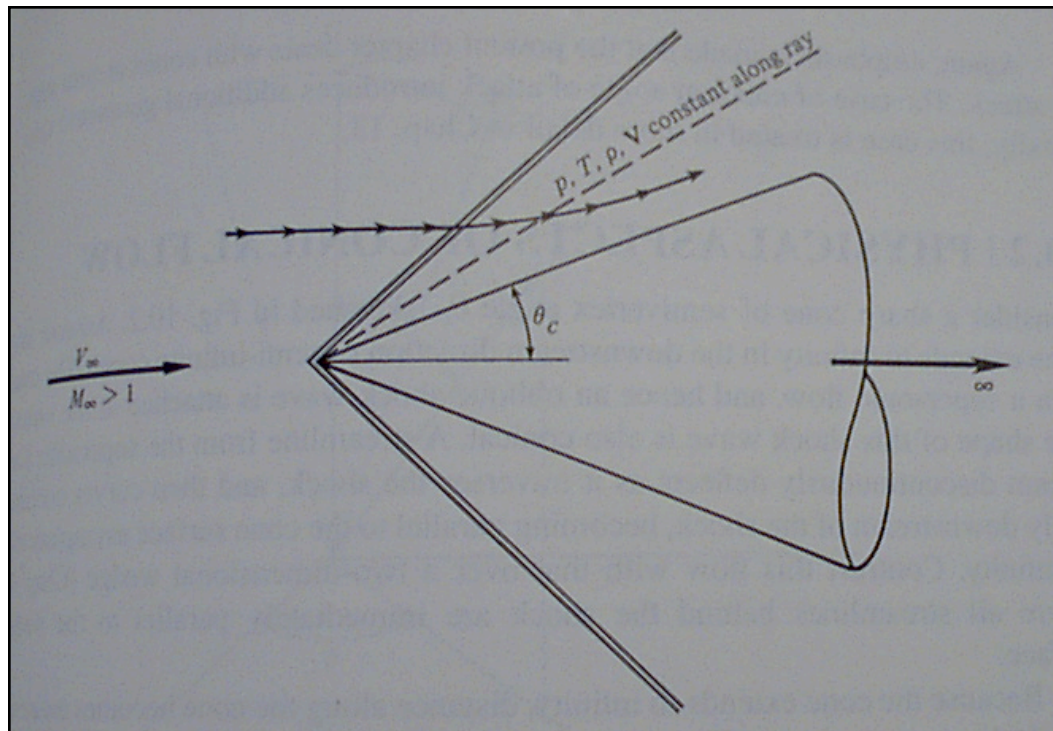
## Section 2.2: Analysis of Supersonic Conical Flows

- Anderson,  
Chapter 10 pp. 363-375



# Physical Aspects of Conical Flow

- Flow is circumferentially symmetric

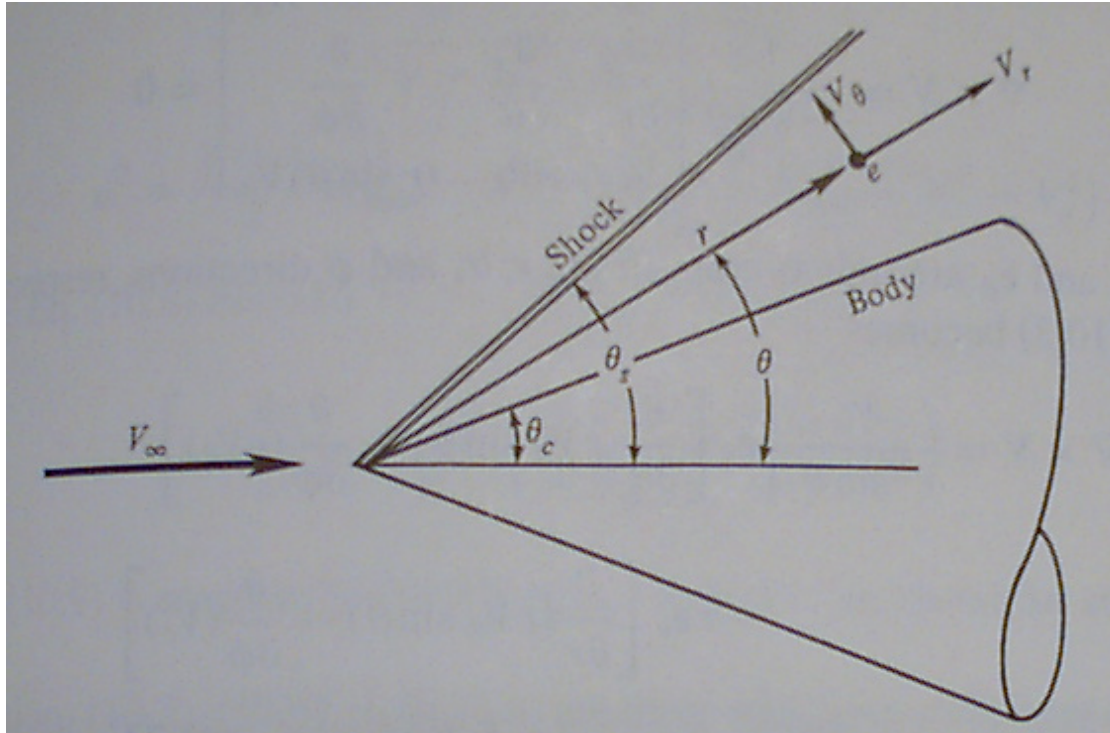


$$\frac{\partial}{\partial \phi} [ \quad ] = 0$$

- “Axi-symmetric flow”

# Physical Aspects of Conical Flow

(cont'd)

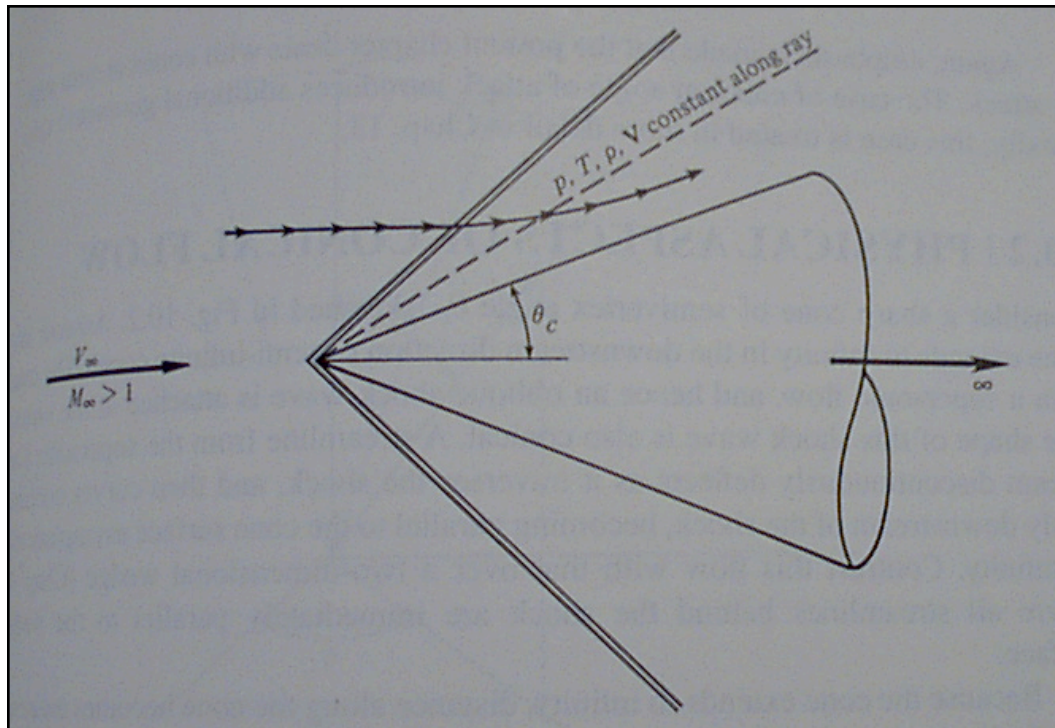


$$\frac{\partial}{\partial r} [V] = 0$$

- Flow Properties are constant along a ray from the vertex

# Physical Aspects of Conical Flow

(cont'd)



- Look at shock wave “straight”

- Shock strength is the same at points 1 and 2

$$[T\nabla s]_1 = [T\nabla s]_2 \rightarrow \left[ \vec{V} \times (\nabla \times \vec{V}) \right]_1 = \left[ \vec{V} \times (\nabla \times \vec{V}) \right]_2 \quad \text{“irrotational flow”}$$

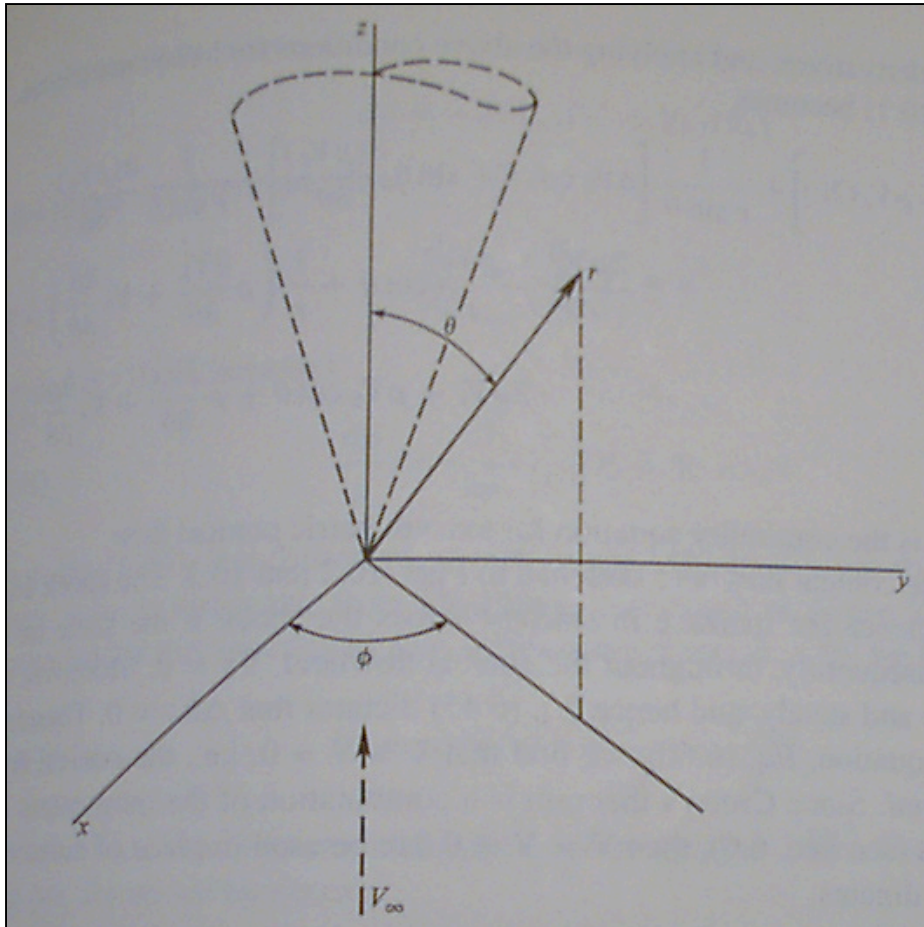
## Rotational and Irrotational Flow

- Condition for Irrotational flow

$$\vec{V} \times (\nabla \times \vec{V}) = 0$$

- At every point in flow field

# Spherical Coordinate System



- Axi-symmetric flow is best represented using spherical coordinate system

$$x = r \sin(\theta) \cos(\phi)$$

$$y = r \sin(\theta) \sin(\phi)$$

$$z = r \cos(\theta)$$

(Anderson conventions)

# Spherical Coordinate System

(cont'd)

- **Velocity vector**

$$\vec{V} = V_r \vec{i}_r + V_\theta \vec{i}_\theta \rightarrow V_\phi = 0$$

- **Gradient vector**

$$\nabla [ ] = \vec{i}_r \frac{\partial}{\partial r} [ ] + \frac{1}{r} \vec{i}_\theta \frac{\partial}{\partial \theta} [ ] + \frac{1}{r \sin \theta} \vec{i}_\phi \frac{\partial}{\partial \phi} [ ]$$

- **Divergence**

$$\nabla \cdot \left( \vec{F} \right) = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 F_r \right) + \frac{1}{r \sin \theta} \frac{\partial \left( \sin \theta F_\theta \right)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi}$$

## Continuity Equation for Conical Flow

- Steady flow

$$\frac{\partial}{\partial t} \rho + \nabla \cdot (\rho \vec{V}) = 0$$

- Axi-symmetric flow -- use spherical coordinates

$$\nabla \cdot (\rho \vec{V}) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \rho V_r) + \frac{1}{r \sin \theta} \frac{\partial (\sin \theta \rho V_\theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial (\rho V_\phi)}{\partial \phi} = 0$$

- Evaluating derivatives and letting  $\frac{\partial}{\partial \phi} [ ] = 0$   $\frac{\partial}{\partial r} [V] = 0$



## Continuity Equation for Conical Flow (concluded)

$$\frac{2\rho V_r}{r} + \frac{\rho V_\theta}{r \sin(\theta)} \cos(\theta) + \frac{1}{r} \left[ \rho \frac{\partial V_\theta}{\partial \theta} + V_\theta \frac{\partial \rho}{\partial \theta} \right] = 0 \rightarrow$$

$$2\rho V_r + \rho V_\theta \cot(\theta) + \rho \frac{\partial V_\theta}{\partial \theta} + V_\theta \frac{\partial \rho}{\partial \theta} = 0$$

- **Continuity Equation for Axi-symmetric Conical Flow**

# Crocco's Relation for Axi-symmetric Conical Flow

- Irrotational flow
- Crocco's relationship solves both momentum and energy equation

... thus for conical flow all we need to satisfy is:

$$\vec{V} \times \left( \nabla \times \vec{V} \right) = 0$$

# Crocco's Relation for Axi-symmetric Conical Flow (cont'd)

- For Arbitrary  $\vec{V}$

$$\nabla \times \vec{V} = 0$$

- Curl Operation in Spherical Coordinates

$$\nabla \times \vec{V} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{i}_r & r \vec{i}_\theta & r \sin \theta \vec{i}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ V_r & r V_\theta & r \sin \theta V_\phi \end{vmatrix} = 0$$

# Crocco's Relation for Axi-symmetric Conical Flow (cont'd)

- For Arbitrary  $\vec{V}$

$$\nabla \times \vec{V} = \vec{0}$$

- Curl Operation in Spherical Coordinates

$$\nabla \times \vec{V} = \frac{1}{r^2 \sin \theta} \begin{bmatrix} \vec{i}_r \left( \frac{\partial}{\partial \theta} [r \sin \theta V_\phi] - \frac{\partial}{\partial \phi} [r V_\theta] \right) - \\ r \vec{i}_\theta \left[ \left( \frac{\partial}{\partial r} [r \sin \theta V_\phi] \right) - \frac{\partial}{\partial \phi} V_r \right] + \\ r \sin \theta \vec{i}_\phi \left( \frac{\partial}{\partial r} r V_\theta - \frac{\partial}{\partial \theta} V_r \right) \end{bmatrix}$$

# Crocco's Relation for Axi-symmetric Conical Flow (cont'd)

- Apply  $\frac{\partial}{\partial \phi} [ ] = 0$

- Crocco Relation reduces to

$$\nabla \times \vec{V} = \vec{i}_\phi \frac{1}{r^2 \sin \theta} \left[ r \sin \theta \left( V_\theta + \frac{\partial V_\theta}{\partial r} - \frac{\partial V_r}{\partial \theta} \right) \right] = 0$$

- Now apply  $\frac{\partial}{\partial r} [V] = 0$

# Crocco's Relation for Axi-symmetric Conical Flow (concluded)

- Crocco Relation reduces to (wow!)

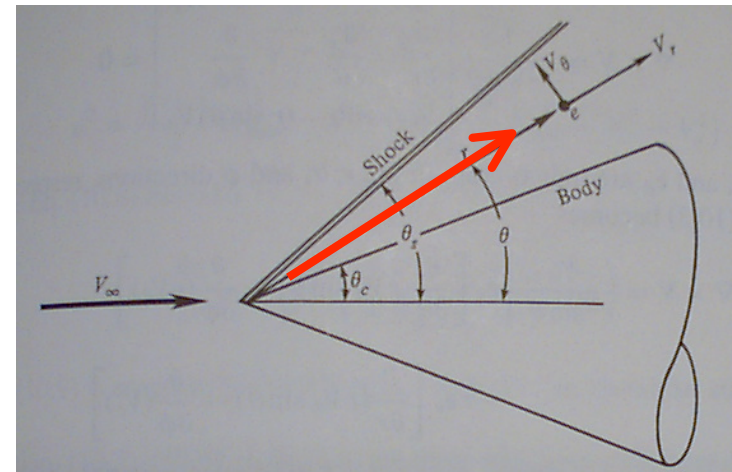
$$V_{\theta} = \frac{\partial V_r}{\partial \theta}$$

- **Irrotationality  
Condition for  
Axi-symmetric conical flow**

# Euler's Equation for Axi-symmetric Conical Flow

- **Steady Axi-symmetric conical flow**

$$\rho \frac{\partial \vec{V}}{\partial t} + \rho \left( \vec{V} \cdot \nabla \right) \vec{V} = -\nabla P$$



- Flow is irrotational ... Apply along stream line direction

$$dP = -\rho V dV \rightarrow V^2 = V_\theta^2 + V_r^2$$

# Euler's Equation for Axi-symmetric Conical Flow (cont'd)

- **Steady Axi-symmetric conical flow**

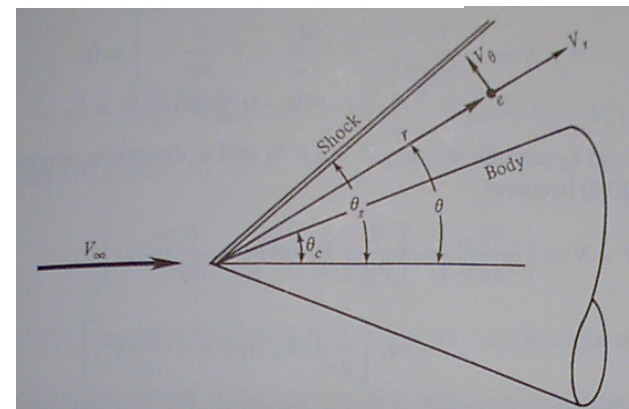
$$dV^2 = d[V_\theta^2 + V_r^2] = 2VdV = 2V_\theta dV_\theta + 2V_r dV_r$$

$$dP = -\rho [V_\theta dV_\theta + V_r dV_r]$$

Divide by  $d\rho$

$$\frac{dP}{d\rho} = -\frac{\rho}{d\rho} [V_\theta dV_\theta + V_r dV_r] \rightarrow$$

for isentropic flow  $\rightarrow \frac{dP}{d\rho} = c^2$



- **Thus behind the shock wave**

$$\frac{d\rho}{\rho} = -\frac{1}{c^2} [V_\theta dV_\theta + V_r dV_r]$$



# Euler's Equation for Axi-symmetric Conical Flow (cont'd)

- But from enthalpy equation

$$h_0 = h + \frac{V^2}{2} = c_p T + \frac{V^2}{2} = \gamma R_g T \frac{c_p}{\gamma R_g} + \frac{V^2}{2} =$$

$$\gamma R_g T \frac{c_p}{\gamma [c_p - c_v]} + \frac{V^2}{2} = \frac{c^2}{\gamma - 1} + \frac{V^2}{2}$$

$$c^2 = \frac{\gamma - 1}{2} (2h_0 - V^2)$$

$$h_0 = \frac{V_{\max}^2}{2} \dots \text{Why?} \dots \text{no idea!}$$

# Euler's Equation for Axi-symmetric Conical Flow (concluded)

- Sub into Euler's equation

$$\frac{d\rho}{\rho} = -\frac{2}{\gamma-1} \frac{[V_\theta dV_\theta + V_r dV_r]}{(2h_0 - V^2)} = \frac{2}{\gamma-1} \frac{[V_\theta dV_\theta + V_r dV_r]}{((V_\theta^2 + V_r^2) - 2h_0)}$$

$$h_0 = \frac{V_{\max}^2}{2} \dots \text{Why?} \dots \text{no idea!}$$

## Collected Equations for for Axi-symmetric Conical Flow

*Continuity*

$$\frac{2\rho V_r}{r} + \frac{\rho V_\theta}{r \sin(\theta)} \cos(\theta) + \frac{1}{r} \left[ \rho \frac{dV_\theta}{d\theta} + V_\theta \frac{d\rho}{d\theta} \right] =$$

$$2V + V_\theta \cot(\theta) + \left[ \frac{dV_\theta}{d\theta} + \frac{V_\theta}{\rho} \frac{d\rho}{d\theta} \right] = 0$$

- Only  $\theta$  is independent variable  
Can re-write partials at total derivatives

*Crocco :*

$$V_\theta = \frac{dV_r}{d\theta}$$

*Euler :*

$$\frac{d\rho}{d\theta} = \frac{2}{\gamma - 1} \frac{\left[ V_\theta \frac{dV_\theta}{d\theta} + V_r \frac{dV_r}{d\theta} \right]}{\left( (V_\theta^2 + V_r^2) - 2h_0 \right)}$$

# Collected Equations for for Axi-symmetric Conical Flow (cont'd)

*Continuity*

$$\frac{2\rho V_r}{r} + \frac{\rho V_\theta}{r \sin(\theta)} \cos(\theta) + \frac{1}{r} \left[ \rho \frac{dV_\theta}{d\theta} + V_\theta \frac{d\rho}{d\theta} \right] =$$

$$2V + V_\theta \cot(\theta) + \left[ \frac{dV_\theta}{d\theta} + \frac{V_\theta}{\rho} \frac{d\rho}{d\theta} \right] = 0$$

*Crocco :*

$$V_\theta = \frac{dV_r}{d\theta}$$

*Euler :*

$$\frac{d\rho}{d\theta} = \frac{2}{\gamma - 1} \frac{\left[ V_\theta \frac{dV_\theta}{d\theta} + V_r \frac{dV_r}{d\theta} \right]}{\left( (V_\theta^2 + V_r^2) - 2h_0 \right)}$$

## Collected Equations for for Axi-symmetric Conical Flow (cont'd)

$$2V_r + V_\theta \cot(\theta) + \left[ \frac{dV_\theta}{d\theta} + V_\theta \frac{2}{\gamma - 1} \frac{\left[ V_\theta \frac{dV_\theta}{d\theta} + V_r \frac{dV_r}{d\theta} \right]}{(V_\theta^2 + V_r^2 - 2h_0)} \right] = 0$$

*But from Crocco :*

• **Substituting in**

$$V_\theta = \frac{dV_r}{d\theta} \rightarrow \frac{dV_\theta}{d\theta} = \frac{d^2V_r}{d\theta^2}$$

## Collected Equations for for Axi-symmetric Conical Flow (cont'd)

$$V_r + \frac{dV_r}{d\theta} \cot(\theta) + \left[ \frac{d^2V_r}{d\theta^2} + \frac{dV_r}{d\theta} \frac{2}{\gamma-1} \frac{\left[ \frac{dV_r}{d\theta} \frac{d^2V_r}{d\theta^2} + V_r \frac{dV_r}{d\theta} \right]}{\left( \frac{dV_r}{d\theta}^2 + V_r^2 - 2h_0 \right)} \right] =$$

$$\frac{\gamma-1}{2} \left( 2h_0 - V_r^2 - \left( \frac{dV_r}{d\theta} \right)^2 \right) \left( 2V_r + \frac{dV_r}{d\theta} \cot(\theta) + \frac{d^2V_r}{d\theta^2} \right) - \frac{dV_r}{d\theta} \left[ V_r \frac{dV_r}{d\theta} + \frac{dV_r}{d\theta} \frac{d^2V_r}{d\theta^2} \right] = 0$$

- CLASSICAL FORM OF TAYLOR-MACCOLL EQUATION  
... BUT DIFFICULT TO SOLVE NUMERICALLY IN THIS FORM

$$h_0 = \frac{V_{\max}^2}{2} \dots \text{Why? ...no idea!} \rightarrow V_{\max} = \sqrt{2h_0}$$

## Taylor-Maccoll Equation

- **O.D.E for  $V_r$  in terms of  $\theta$**

$$\frac{\gamma - 1}{2} \left( 2h_0 - V_r^2 - \left( \frac{dV_r}{d\theta} \right)^2 \right) \left( 2V_r + \frac{dV_r}{d\theta} \cot(\theta) + \frac{d^2V_r}{d\theta^2} \right) - \frac{dV_r}{d\theta} \left[ V_r \frac{dV_r}{d\theta} + \frac{dV_r}{d\theta} \frac{d^2V_r}{d\theta^2} \right] = 0$$

$V_r$  --> dependent variable,  
 $\theta$  --> independent variable

• Solve for  $V_r$  --->  $V_\theta = \frac{\partial V_r}{\partial \theta}$   
Then

# Taylor-Maccoll Equation (cont'd)

- **BETTER SOLUTION ...Nondimensionalize by  $\sqrt{2h_0}$**

$$\frac{\gamma - 1}{2} \left( 1 - \left( \frac{V_r}{\sqrt{2h_0}} \right)^2 - \left( \frac{d(V_r/\sqrt{2h_0})}{d\theta} \right)^2 \right) \left( 2 \frac{V_r}{\sqrt{2h_0}} + \frac{d(V_r/\sqrt{2h_0})}{d\theta} \cot(\theta) + \frac{d^2(V_r/\sqrt{2h_0})}{d\theta^2} \right) - \frac{d(V_r/\sqrt{2h_0})}{d\theta} \left[ \frac{V_r}{\sqrt{2h_0}} \frac{d(V_r/\sqrt{2h_0})}{d\theta} + \frac{d(V_r/\sqrt{2h_0})}{d\theta} \frac{d^2(V_r/\sqrt{2h_0})}{d\theta^2} \right] = 0$$

- let

- and the Taylor-Maccoll equation reduces to

$$\frac{V_r}{\sqrt{2h_0}} = \vartheta_r \rightarrow \text{Anderson} \rightarrow \vartheta = \frac{V_r}{V_{\max}}$$



## Taylor-Maccoll Equation (cont'd)

$$\frac{\gamma - 1}{2} \left( 1 - \vartheta_r^2 - \left( \frac{d\vartheta_r}{d\theta} \right)^2 \right) \left( 2\vartheta_r + \frac{d\vartheta_r}{d\theta} \cot(\theta) + \frac{d^2\vartheta_r}{d\theta^2} \right) - \frac{d\vartheta_r}{d\theta} \left[ \vartheta_r \frac{d\vartheta_r}{d\theta} + \frac{d\vartheta_r}{d\theta} \frac{d^2\vartheta_r}{d\theta^2} \right] = 0$$

$$\frac{V_r}{\sqrt{2h_0}} = \vartheta_r \quad \vartheta_\theta = \frac{\partial\vartheta_r}{\partial\theta} \rightarrow \vartheta = \sqrt{\vartheta_\theta^2 + \vartheta_r^2}$$

## Taylor-Maccoll Equation (cont'd)

- Take a closer look at:  $\frac{V}{\sqrt{2h_0}} = \vartheta$

$$\frac{V}{\sqrt{2h_0}} = \vartheta \rightarrow \vartheta^2 h_0 = \frac{V^2}{2} \rightarrow \vartheta^2 \left[ h + \frac{V^2}{2} \right] = \frac{V^2}{2}$$

$$\vartheta^2 \left[ \frac{c^2}{\gamma - 1} + \frac{V^2}{2} \right] = \frac{V^2}{2} \rightarrow \vartheta^2 \left[ 1 + \frac{\gamma - 1}{2} \frac{V^2}{c^2} \right] = \frac{\gamma - 1}{2} \frac{V^2}{c^2}$$

$$\rightarrow \vartheta = \sqrt{\frac{\frac{\gamma - 1}{2} M^2}{1 + \frac{\gamma - 1}{2} M^2}}$$

- Once we find  $\vartheta$  we can calculate M
- So how do we find  $\vartheta$  ?

## Numerical Procedure for Solving Axi-symmetric Conical Flow Field

- Re-write

$$\frac{\gamma-1}{2} \left( 1 - \vartheta_r^2 - \left( \frac{d\vartheta_r}{d\theta} \right)^2 \right) \left( 2\vartheta_r + \frac{d\vartheta_r}{d\theta} \cot(\theta) + \frac{d^2\vartheta_r}{d\theta^2} \right) - \frac{d\vartheta_r}{d\theta} \left[ \vartheta_r \frac{d\vartheta_r}{d\theta} + \frac{d\vartheta_r}{d\theta} \frac{d^2\vartheta_r}{d\theta^2} \right] = 0$$

- As

$$\frac{\gamma-1}{2} \left( 1 - \vartheta_r^2 - \left( \frac{d\vartheta_r}{d\theta} \right)^2 \right) \left( 2\vartheta_r + \frac{d\vartheta_r}{d\theta} \cot(\theta) + \frac{d}{d\theta} \left( \frac{d\vartheta_r}{d\theta} \right) \right) - \frac{d\vartheta_r}{d\theta} \left[ \vartheta_r \frac{d\vartheta_r}{d\theta} + \frac{d\vartheta_r}{d\theta} \frac{d}{d\theta} \left( \frac{d\vartheta_r}{d\theta} \right) \right] = 0$$

- But  $\vartheta_\theta = \frac{\partial \vartheta_r}{\partial \theta}$
- Substitute in

## Numerical Procedure for Solving Axi-symmetric Conical Flow Field

- Re-write

$$\frac{\gamma-1}{2} \left( 1 - \vartheta_r^2 - \left( \frac{d\vartheta_r}{d\theta} \right)^2 \right) \left( 2\vartheta_r + \frac{d\vartheta_r}{d\theta} \cot(\theta) + \frac{d^2\vartheta_r}{d\theta^2} \right) - \frac{d\vartheta_r}{d\theta} \left[ \vartheta_r \frac{d\vartheta_r}{d\theta} + \frac{d\vartheta_r}{d\theta} \frac{d^2\vartheta_r}{d\theta^2} \right] = 0$$

- As

$$\frac{\gamma-1}{2} \left( 1 - \vartheta_r^2 - \left( \frac{d\vartheta_r}{d\theta} \right)^2 \right) \left( 2\vartheta_r + \frac{d\vartheta_r}{d\theta} \cot(\theta) + \frac{d}{d\theta} \left( \frac{d\vartheta_r}{d\theta} \right) \right) - \frac{d\vartheta_r}{d\theta} \left[ \vartheta_r \frac{d\vartheta_r}{d\theta} + \frac{d\vartheta_r}{d\theta} \frac{d}{d\theta} \left( \frac{d\vartheta_r}{d\theta} \right) \right] = 0$$

- But  $\vartheta_\theta = \frac{\partial \vartheta_r}{\partial \theta}$
- Substitute in

## Numerical Procedure for Solving Axi-symmetric Conical Flow Field (cont'd)

$$\frac{\gamma-1}{2}(1-\vartheta_r^2-\vartheta_\theta^2)\left(2\vartheta_r+\vartheta_\theta\cot(\theta)+\frac{d\vartheta_\theta}{d\theta}\right)-\vartheta_\theta\left[\vartheta_r\vartheta_\theta+\vartheta_\theta\frac{d\vartheta_\theta}{d\theta}\right]=0$$

- Solve for  $\frac{\partial\vartheta_r}{\partial\theta}$

$$\left[\frac{\gamma-1}{2}(1-\vartheta_r^2-\vartheta_\theta^2)-\vartheta_\theta^2\right]\left(\frac{d\vartheta_\theta}{d\theta}\right)+\frac{\gamma-1}{2}(1-\vartheta_r^2-\vartheta_\theta^2)(2\vartheta_r+\vartheta_\theta\cot(\theta))-\vartheta_\theta^2\vartheta_r$$

$$\rightarrow\left(\frac{d\vartheta_\theta}{d\theta}\right)=\frac{\vartheta_\theta^2\vartheta_r-\frac{\gamma-1}{2}(1-\vartheta_r^2-(\vartheta_\theta)^2)(2\vartheta_r+\vartheta_\theta\cot(\theta))}{\left[\frac{\gamma-1}{2}(1-\vartheta_r^2-\vartheta_\theta^2)-\vartheta_\theta^2\right]}$$

## Numerical Procedure for Solving Axi-symmetric Conical Flow Field (cont'd)

- System of first order ordinary differential equations

$$\frac{\partial v_r}{\partial \theta} = v_\theta$$

$$\frac{dv_\theta}{d\theta} = \frac{v_\theta^2 v_r - \frac{\gamma-1}{2} (1 - v_r^2 - v_\theta^2) (2v_r + v_\theta \cot(\theta))}{\left[ \frac{\gamma-1}{2} (1 - v_r^2 - v_\theta^2) - v_\theta^2 \right]}$$

## Numerical Procedure for Solving Axi-symmetric Conical Flow Field (cont'd)

- Can be written in vector form as

$$\begin{bmatrix} \frac{\partial \vartheta_r}{\partial \theta} \\ \frac{d\vartheta_\theta}{d\theta} \end{bmatrix} = \begin{bmatrix} \vartheta_\theta \\ \frac{\vartheta_\theta^2 \vartheta_r - \frac{\gamma-1}{2}(1-\vartheta_r^2-\vartheta_\theta^2)(2\vartheta_r + \vartheta_\theta \cot(\theta))}{\left[ \frac{\gamma-1}{2}(1-\vartheta_r^2-\vartheta_\theta^2) - \vartheta_\theta^2 \right]} \end{bmatrix}$$

## Numerical Procedure for Solving Axi-symmetric Conical Flow Field (cont'd)

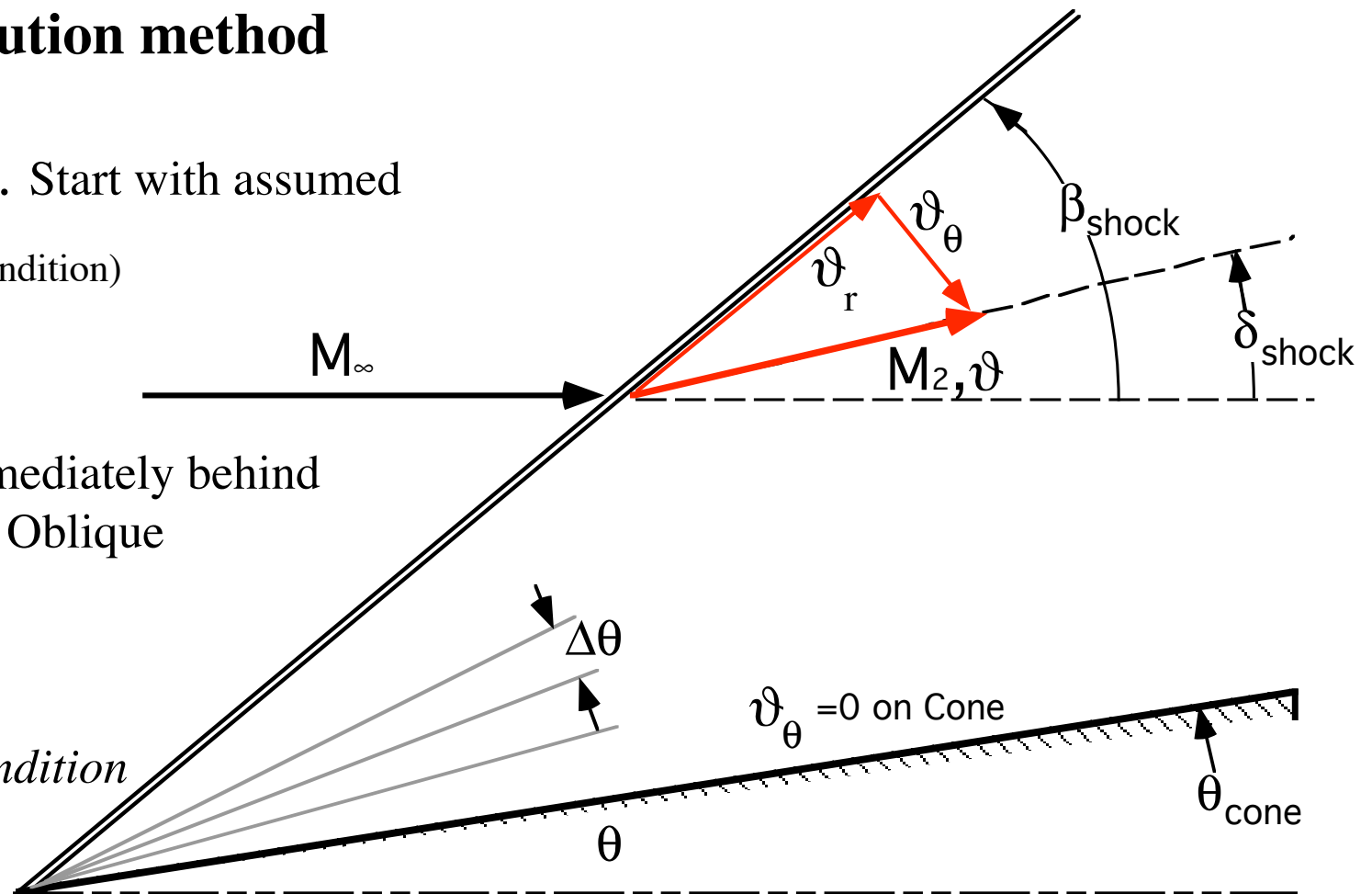
• Or 
$$\frac{d\mathcal{V}}{d\theta} = F[\mathcal{V}] \quad \mathcal{V} = \begin{bmatrix} \mathcal{V}_r \\ \mathcal{V}_\theta \end{bmatrix}$$

$$F[\mathcal{V}] = \begin{bmatrix} \mathcal{V}_\theta \\ \frac{\mathcal{V}_\theta^2 \mathcal{V}_r - \frac{\gamma-1}{2} (1 - \mathcal{V}_r^2 - \mathcal{V}_\theta^2) (2\mathcal{V}_r + \mathcal{V}_\theta \cot(\theta))}{\left[ \frac{\gamma-1}{2} (1 - \mathcal{V}_r^2 - \mathcal{V}_\theta^2) - \mathcal{V}_\theta^2 \right]} \end{bmatrix}$$



# Boundary Value Problem

- Inverse solution method
- Given  $M_\infty$  ... Start with assumed  $\beta_{\text{shock}}$  (initial condition)



- Properties immediately behind Shock given by Oblique Shock relations

- On cone  $\vartheta_\theta = 0$   
*Boundary Condition*

## Boundary Value Problem (cont'd)

- **Starting Conditions**

Given  $M_\infty$  ... Start with assumed  $\beta_{shock}$  (initial condition)

Calculate  $M_2$  (immediately behind shock)

$$M_{n_\infty} = M_\infty \sin \beta_{shock} \rightarrow M_{n_2} = \sqrt{\frac{\left(1 + \frac{(\gamma - 1)}{2} M_{n_\infty}^2\right)}{\left(\gamma M_{n_\infty}^2 - \frac{(\gamma - 1)}{2}\right)}}$$

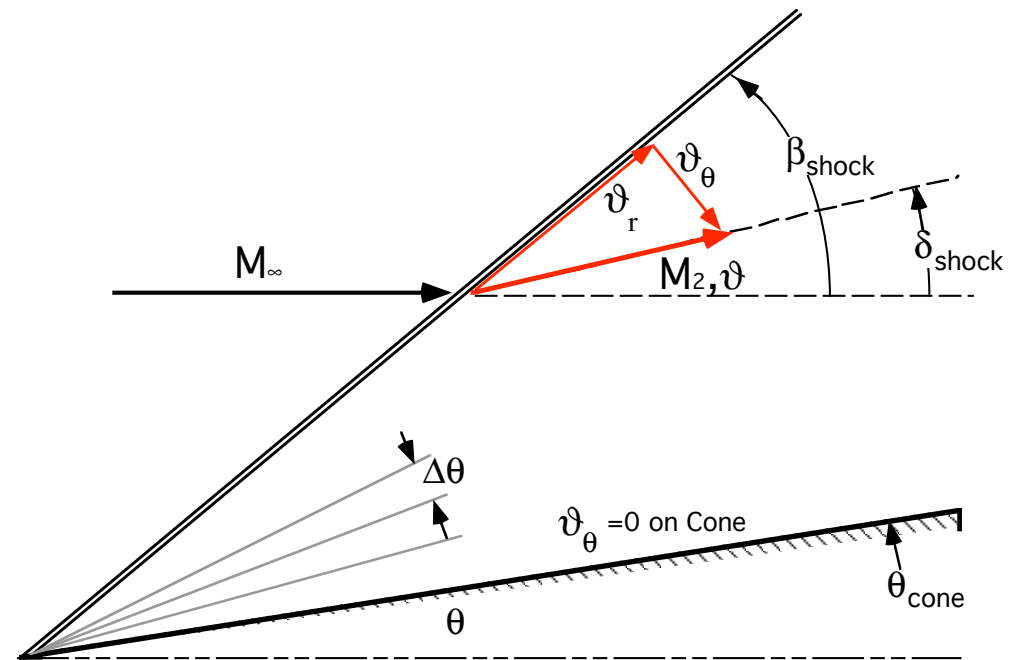
$$M_2 = \frac{M_{n_2}}{\sin(\beta_{shock} - \delta_{shock})}$$

$$\tan(\delta_{shock}) = \frac{2\{M_\infty^2 \sin^2(\beta_{shock}) - 1\}}{\tan(\beta_{shock})[2 + M_\infty^2[\gamma + \cos(2\beta_{shock})]]}$$

# Boundary Value Problem (cont'd)

- Starting Conditions

$$\vartheta = \sqrt{\frac{\frac{\gamma - 1}{2} M_2^2}{1 + \frac{\gamma - 1}{2} M_2^2}}$$



$$\vartheta_r = \vartheta \cos(\beta_{shock} - \delta_{shock})$$

$$\vartheta_\theta = -\vartheta \sin(\beta_{shock} - \delta_{shock})$$

## Boundary Value Problem (cont'd)

- Using Starting  $\vartheta_r, \vartheta_\theta$

Integrate the equations of motion over increments of  $\theta$   
 Until  $\vartheta_\theta = 0$  ... this angle corresponds to the solid  
 Cone boundary corresponding to  $M_\infty$  and the assumed  
 $\beta_{\text{shock}}$ .

$$\frac{d\vartheta}{d\theta} = F[\vartheta]$$

- So How do we integrate  
This?

# Integration of Equations of Motion

- The Integral starts at  $\beta_{shock}$  and proceeds towards the cone where  $\theta = \theta_{cone}$

$$\vartheta(\theta_{cone}) = \vartheta(\beta_{shock}) + \int_{\beta_{shock}}^{\theta_{cone}} F[\vartheta(\theta)] d\theta$$

- Look at small segment  $d\theta$  for the integral

$$\vartheta(\theta_{j+1}) = \vartheta(\theta_j) + \int_{\theta_j}^{\theta_{j+1}} F[\vartheta(\theta)] d\theta$$

$$\theta_{j+1} = \theta_j - \Delta\theta \rightarrow \vartheta_{j+1} = \vartheta_j + \int_{\theta_j}^{\theta_j - \Delta\theta} F[\vartheta(\theta)] d\theta$$

# Integration of Equations of Motion

(cont'd)

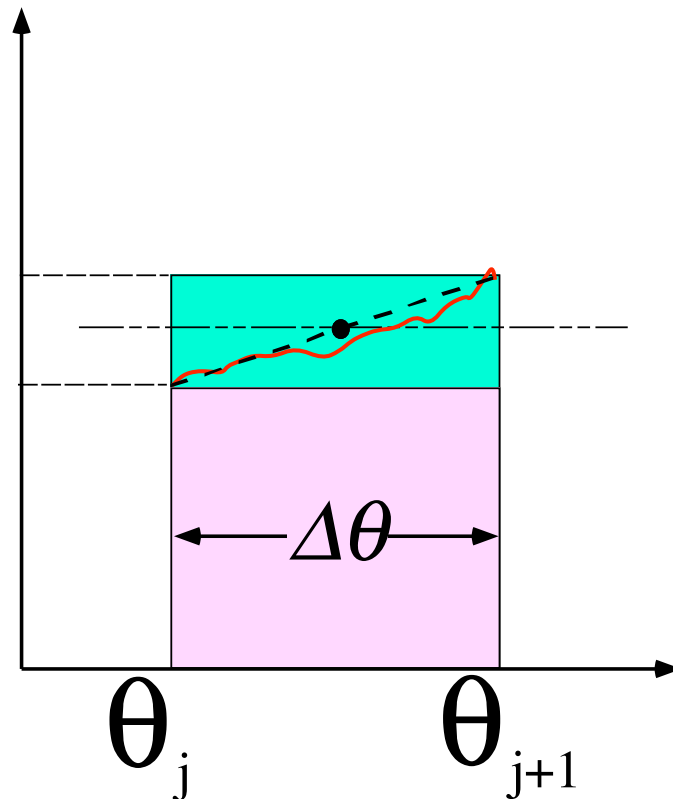
- Look at  $\int_{\theta_j}^{\theta_j - \Delta\theta} F[\vartheta(\theta)] d\theta$

- Approximate area under curve =

$$\left[ \frac{F[\vartheta_j] + F[\vartheta_{j+1}]}{2} \right] \Delta\theta$$

$$F[\vartheta_{j+1}]$$

$$F[\vartheta_j]$$



# Integration of Equations of Motion

(cont'd)

- The the integral is approximated by

$$\int_{\theta_j}^{\theta_j - \Delta\theta} F[\vartheta(\theta)] d\theta \approx - \left[ \frac{F[\vartheta_j] + F[\vartheta_{j+1}]}{2} \right] \Delta\theta$$

- And

**“trapezoidal rule”**

$$\vartheta_{j+1} = \vartheta_j - \left[ \frac{F[\vartheta_{j+1}] + F[\vartheta_j]}{2} \right] \Delta\theta$$

# Integration of Equations of Motion

(cont'd)

- Or we perform the same argument using “finite differences”

$$\frac{d\vartheta}{d\theta} = F[\vartheta] \rightarrow \rightarrow \frac{\Delta\vartheta}{\Delta\theta} = \frac{\vartheta_{j+1} - \vartheta_j}{\theta_{j+1} - \theta_j} \approx \left[ \frac{F[\vartheta_j] + F[\vartheta_{j+1}]}{2} \right]$$

$$\vartheta_{j+1} = \vartheta_j + (\theta_{j+1} - \theta_j) \left[ \frac{F[\vartheta_j] + F[\vartheta_{j+1}]}{2} \right] \rightarrow \vartheta_{j+1} = \vartheta_j + (\theta_j - \Delta\theta - \theta_j) \left[ \frac{F[\vartheta_j] + F[\vartheta_{j+1}]}{2} \right]$$

$$\rightarrow \vartheta_{j+1} = \vartheta_j - \Delta\theta \left[ \frac{F[\vartheta_j] + F[\vartheta_{j+1}]}{2} \right]$$

- **Basic differencing scheme**

$$\vartheta_{j+1} = \vartheta_j - \left[ \frac{F[\vartheta_{j+1}] + F[\vartheta_j]}{2} \right] \Delta\theta$$



## Predictor / Corrector

- But at step ( $j$ ) we don't know  $F\left[\mathcal{V}_{j+1}\right]$

- So we *predict* it ...

$$\rightarrow \tilde{\mathcal{V}}_{j+1} = \hat{\mathcal{V}}_j - (\Delta\theta) F\left[\hat{\mathcal{V}}_j\right]$$

- **Be very careful**  
**About units on  $\Delta\theta$**

- and then *correct* the prediction

$$\rightarrow \hat{\mathcal{V}}_{j+1} = \hat{\mathcal{V}}_j - \frac{(\Delta\theta)}{2} \left( F\left[\hat{\mathcal{V}}_j\right] + F\left[\tilde{\mathcal{V}}_{j+1}\right] \right)$$

# Predictor / Corrector

• Where

$$F \left[ \hat{\vartheta}_j \right] = \frac{\left( \hat{\vartheta}_{\theta_j} \right)^2 \left( \hat{\vartheta}_{r_j} \right) - \frac{\gamma-1}{2} \left( 1 - \left( \hat{\vartheta}_{r_j} \right)^2 - \left( \hat{\vartheta}_{\theta_j} \right)^2 \right) \left( 2 \left( \hat{\vartheta}_{r_j} \right) + \left( \hat{\vartheta}_{\theta_j} \right) \cot(\theta_j) \right)}{\left[ \frac{\gamma-1}{2} \left( 1 - \left( \hat{\vartheta}_{r_j} \right)^2 - \left( \hat{\vartheta}_{\theta_j} \right)^2 \right) - \left( \hat{\vartheta}_{\theta_j} \right)^2 \right]} \hat{\vartheta}_{\theta_j}$$

$$F \left[ \tilde{\vartheta}_{j+1} \right] = \frac{\left( \tilde{\vartheta}_{\theta_{j+1}} \right)^2 \left( \tilde{\vartheta}_{r_{j+1}} \right) - \frac{\gamma-1}{2} \left( 1 - \left( \tilde{\vartheta}_{r_{j+1}} \right)^2 - \left( \tilde{\vartheta}_{\theta_{j+1}} \right)^2 \right) \left( 2 \left( \tilde{\vartheta}_{r_{j+1}} \right) + \left( \tilde{\vartheta}_{\theta_{j+1}} \right) \cot(\theta_{j+1}) \right)}{\left[ \frac{\gamma-1}{2} \left( 1 - \left( \tilde{\vartheta}_{r_{j+1}} \right)^2 - \left( \tilde{\vartheta}_{\theta_{j+1}} \right)^2 \right) - \left( \tilde{\vartheta}_{\theta_{j+1}} \right)^2 \right]} \tilde{\vartheta}_{\theta_{j+1}}$$

## Collected Algorithm

1) *Compute Initial Conditions,*

a) Given  $M_\infty$  ... Start with assumed  $\beta_{shock}$

b) Calculate  $M_2$  (immediately behind shock)

$$M_{n_\infty} = M_\infty \sin \beta_{shock} \rightarrow M_{n_2} = \sqrt{\frac{\left(1 + \frac{(\gamma - 1)}{2} M_{n_\infty}^2\right)}{\left(\gamma M_{n_\infty}^2 - \frac{(\gamma - 1)}{2}\right)}}$$

$$\tan(\delta_{shock}) = \frac{2 \{ M_\infty^2 \sin^2(\beta_{shock}) - 1 \}}{\tan(\beta_{shock}) \left[ 2 + M_\infty^2 \left[ \gamma + \cos(2\beta_{shock}) \right] \right]}$$

$$M_2 = \frac{M_{n_2}}{\sin(\beta_{shock} - \delta_{shock})}$$

## Collected Algorithm

1) *Compute Initial Conditions,*

c) Calculate  $p_2, T_2$  ratios (immediately behind shock)

$$\frac{p_2}{p_\infty} = 1 + \frac{2\gamma}{(\gamma + 1)} \left( (M_\infty \sin \beta_{shock})^2 - 1 \right)$$

$$\frac{T_2}{T_\infty} = \left[ 1 + \frac{2\gamma}{(\gamma + 1)} \left( (M_\infty \sin \beta_{shock})^2 - 1 \right) \right] \left[ \frac{(2 + (\gamma - 1)(M_\infty \sin \beta_{shock})^2)}{(\gamma + 1)(M_\infty \sin \beta_{shock})^2} \right]$$

## Collected Algorithm (cont'd)

1) *Compute Initial Conditions,*

c) Compute starting non-dimensional velocities

$$\vartheta = \sqrt{\frac{\frac{\gamma - 1}{2} M_2^2}{\left[ 1 + \frac{\gamma - 1}{2} M_2^2 \right]}}$$

$$\vartheta_r = \vartheta \cos(\beta_{shock} - \delta_{shock})$$

$$\vartheta_\theta = -\vartheta \sin(\beta_{shock} - \delta_{shock})$$

## Collected Algorithm (cont'd)

2) Compute  $\theta$  decrement

$$\Delta\theta = \frac{\beta_{shock}}{N}$$

$$\mathcal{V} = \begin{bmatrix} \mathcal{V}_r \\ \mathcal{V}_\theta \end{bmatrix}$$

3) Integration Loop,  $j=1, \dots, N$

• **Be very careful**  
**About units on  $\Delta\theta$**

a) Predictor

$$\rightarrow \tilde{\mathcal{V}}_{j+1} = \hat{\mathcal{V}}_j - (\Delta\theta) F \left[ \hat{\mathcal{V}}_j \right] ; \theta_{j+1} = \theta_j - \Delta\theta$$

b) Corrector

$$\rightarrow \hat{\mathcal{V}}_{j+1} = \hat{\mathcal{V}}_j - \frac{(\Delta\theta)}{2} \left( F \left[ \hat{\mathcal{V}}_j \right] + F \left[ \tilde{\mathcal{V}}_{j+1} \right] \right)$$

## Collected Algorithm (cont'd)

3) Integration Loop,  $j=1, \dots, N$  (cont'd)

d) Test for convergence

$$f \left[ \left| \vartheta_{\theta_j} \right| > \varepsilon \right]$$

$$\{ \hat{\vartheta}_j = \hat{\vartheta}_{j+1};$$

$$\theta_j = \theta_{j+1}$$

*return;* }

*else*

{*break;*}

**if  $\vartheta_{\theta} > 0$  you have a problem  
Why?**

## Collected Algorithm (cont'd)

### 4) Post-process data

#### a) Compute total $\vartheta$

$$\hat{\vartheta}_r = \hat{\vartheta}_N(1) \rightarrow \vartheta = \sqrt{\left(\hat{\vartheta}_r\right)^2 + \left(\hat{\vartheta}_\theta\right)^2}$$

$$\hat{\vartheta}_\theta = \hat{\vartheta}_N(2)$$

#### b) Compute $M_{cone}$

$$M_{cone} = \sqrt{\frac{2}{(\gamma - 1)} \left[ \frac{(\vartheta_{cone})^2}{1 - (\vartheta_{cone})^2} \right]}$$

• Why?

$$\vartheta = \sqrt{\frac{\frac{\gamma - 1}{2} M^2}{\left[ 1 + \frac{\gamma - 1}{2} M^2 \right]}}$$



# Collected Algorithm (cont'd)

## 4) Post-process data

c) Calculate  $p_{\text{cone}}, T_{\text{cone}}$  ratios (flow behind shock is isentropic)

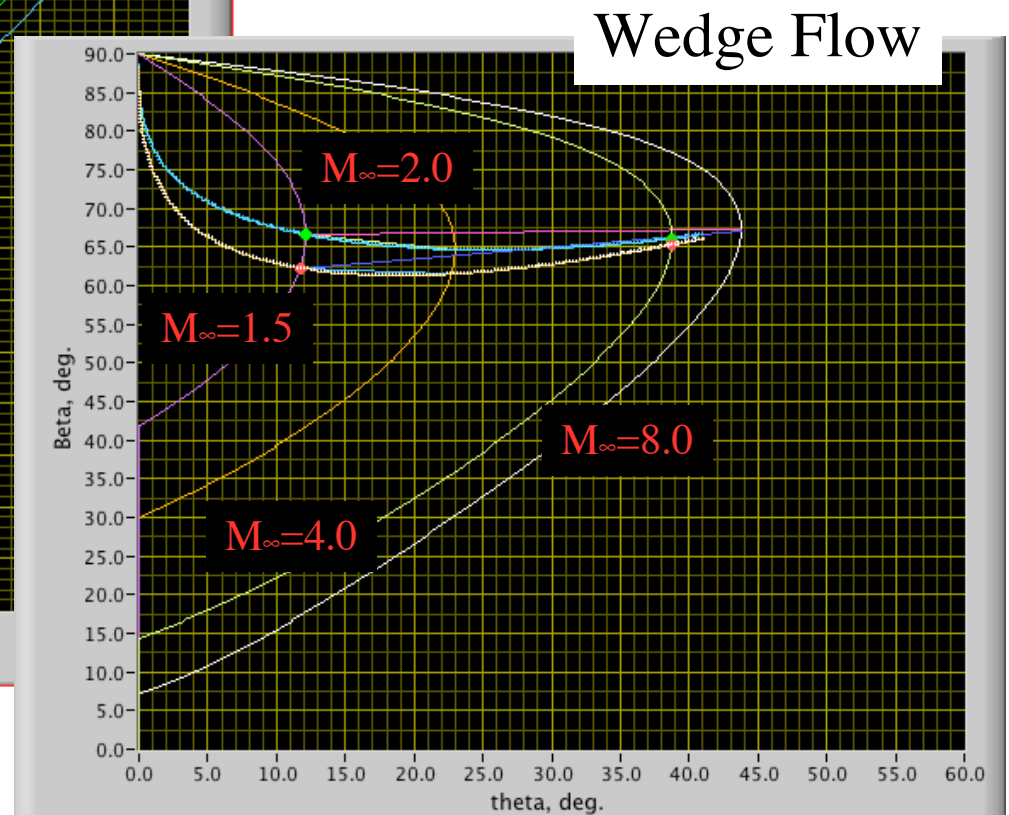
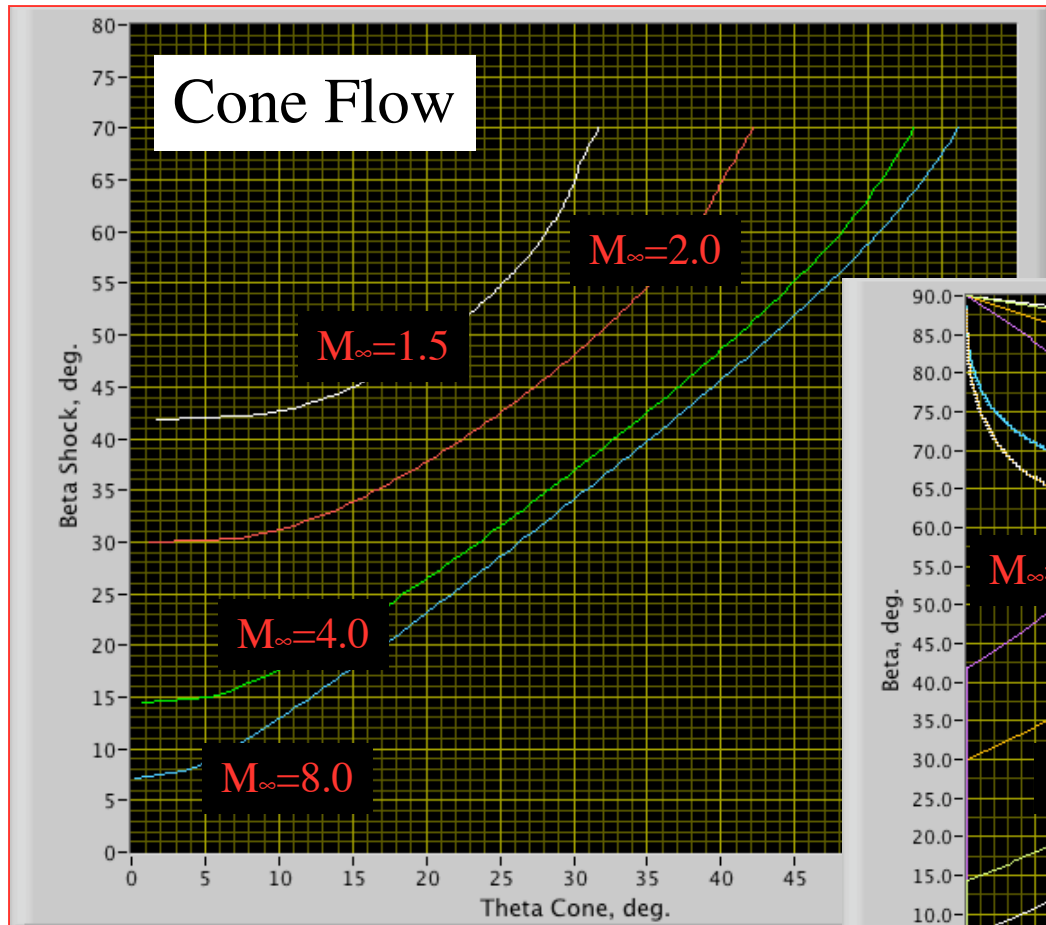
$$\frac{p_{\text{cone}}}{p_{\infty}} = \frac{p_{\text{cone}}}{p_2} \frac{p_2}{p_{\infty}} = \left[ \frac{1 + \frac{(\gamma-1)}{2}(M_2)^2}{1 + \frac{(\gamma-1)}{2}(M_{\text{cone}})^2} \right]^{\frac{\gamma}{\gamma-1}} \left[ 1 + \frac{2\gamma}{(\gamma+1)} \left( (M_{\infty} \sin \beta_{\text{shock}})^2 - 1 \right) \right]$$

$$\frac{T_{\text{cone}}}{T_{\infty}} = \frac{T_{\text{cone}}}{T_2} \frac{T_2}{T_{\infty}} = \left[ \frac{1 + \frac{(\gamma-1)}{2}(M_2)^2}{1 + \frac{(\gamma-1)}{2}(M_{\text{cone}})^2} \right] \left[ 1 + \frac{2\gamma}{(\gamma+1)} \left( (M_{\infty} \sin \beta_{\text{shock}})^2 - 1 \right) \right] \left[ \frac{(2 + (\gamma-1)(M_{\infty} \sin \beta_{\text{shock}})^2)}{(\gamma+1)(M_{\infty} \sin \beta_{\text{shock}})^2} \right]$$

$$\frac{\rho_c}{\rho_{\infty}} = \frac{p_c / T_c}{p_{\infty} / T_{\infty}} = \frac{p_c}{p_{\infty}} \frac{T_{\infty}}{T_c}$$

# Physical Aspects of Cone Flow

- Compare cone flow to wedge
- Cone flow supports a much larger wedge angle before shock wave detaches



# Physical Aspects of Cone Flow (cont'd)

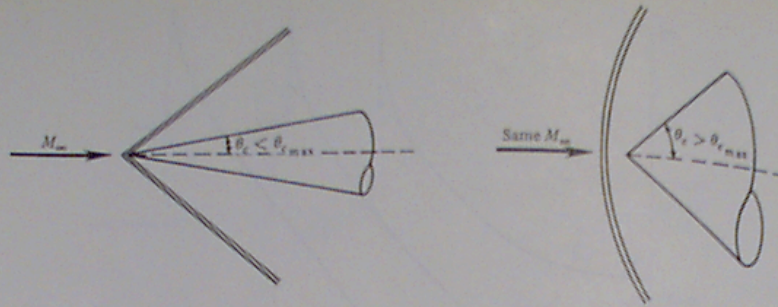
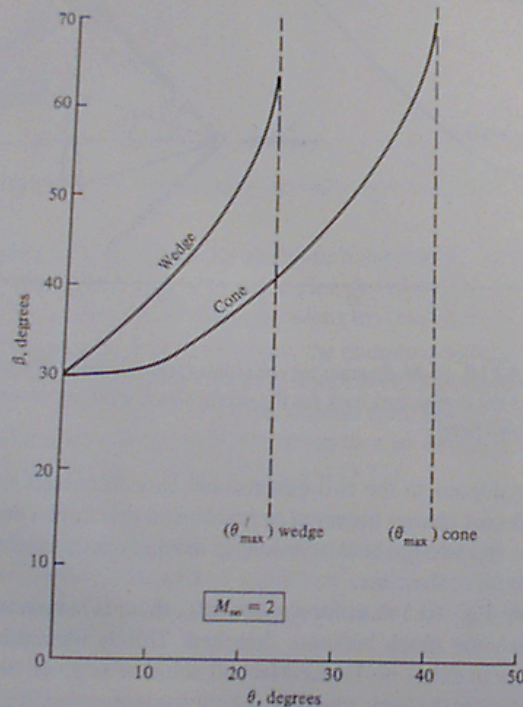


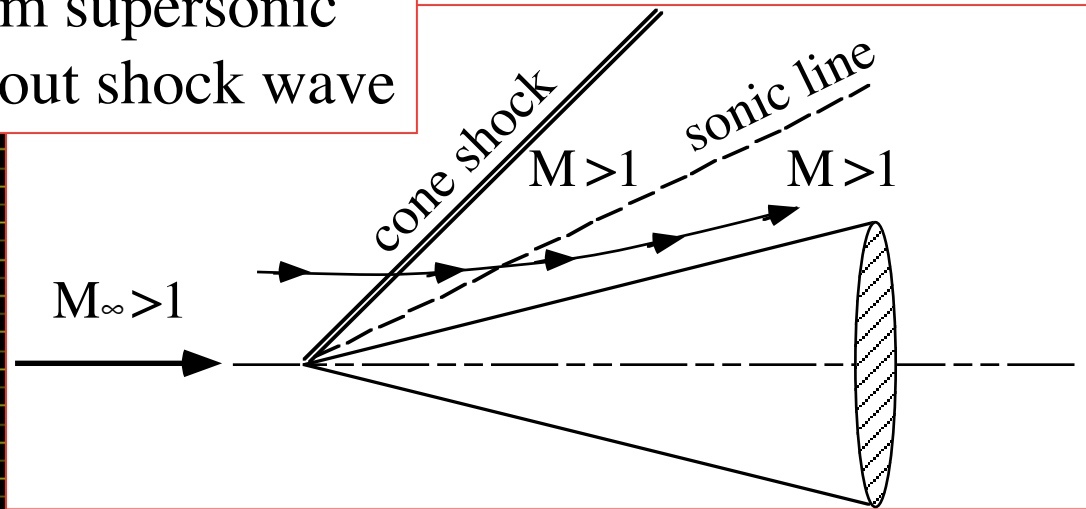
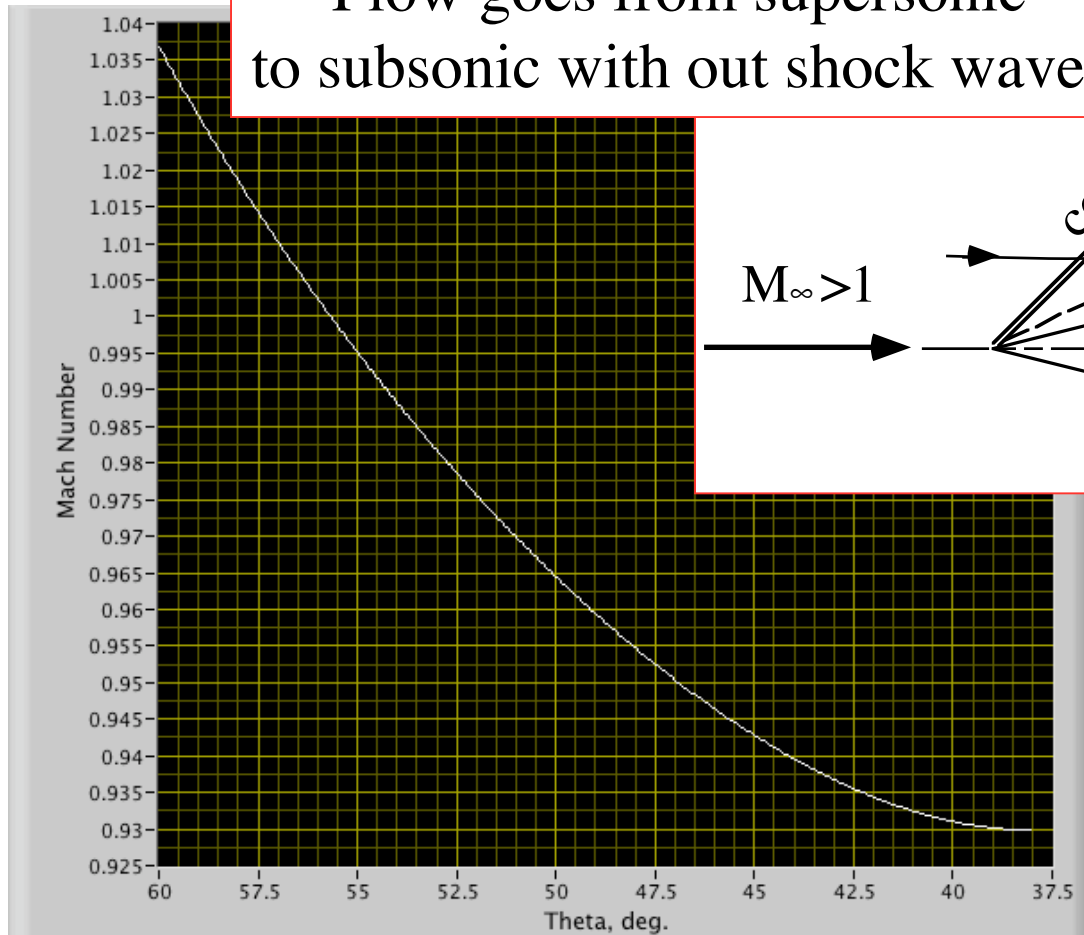
Figure 10.6 | Attached and detached shock waves on cones.



- Three-dimensional “relieving” effect
- Cone shock wave is Effectively weaker Than shock wave for Corresponding wedge angle

# Isentropic Deceleration on Cone with shock wave near detachment angle

- Flow goes from supersonic to subsonic with out shock wave



Input data

Mach  
2.00

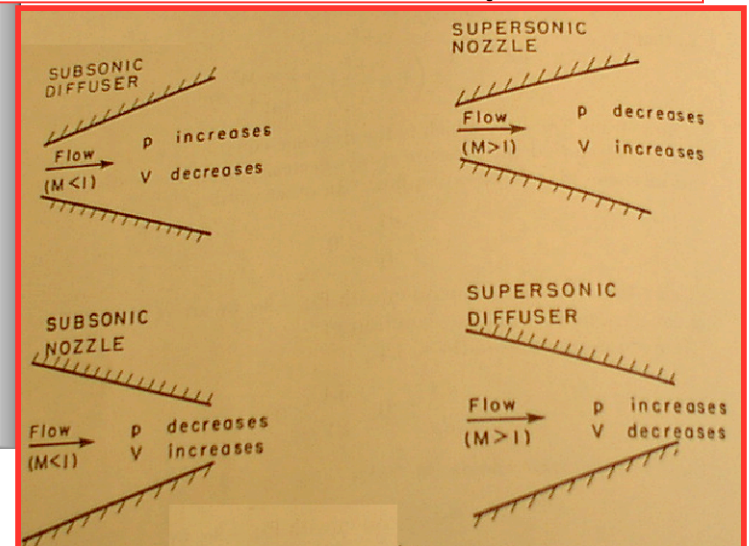
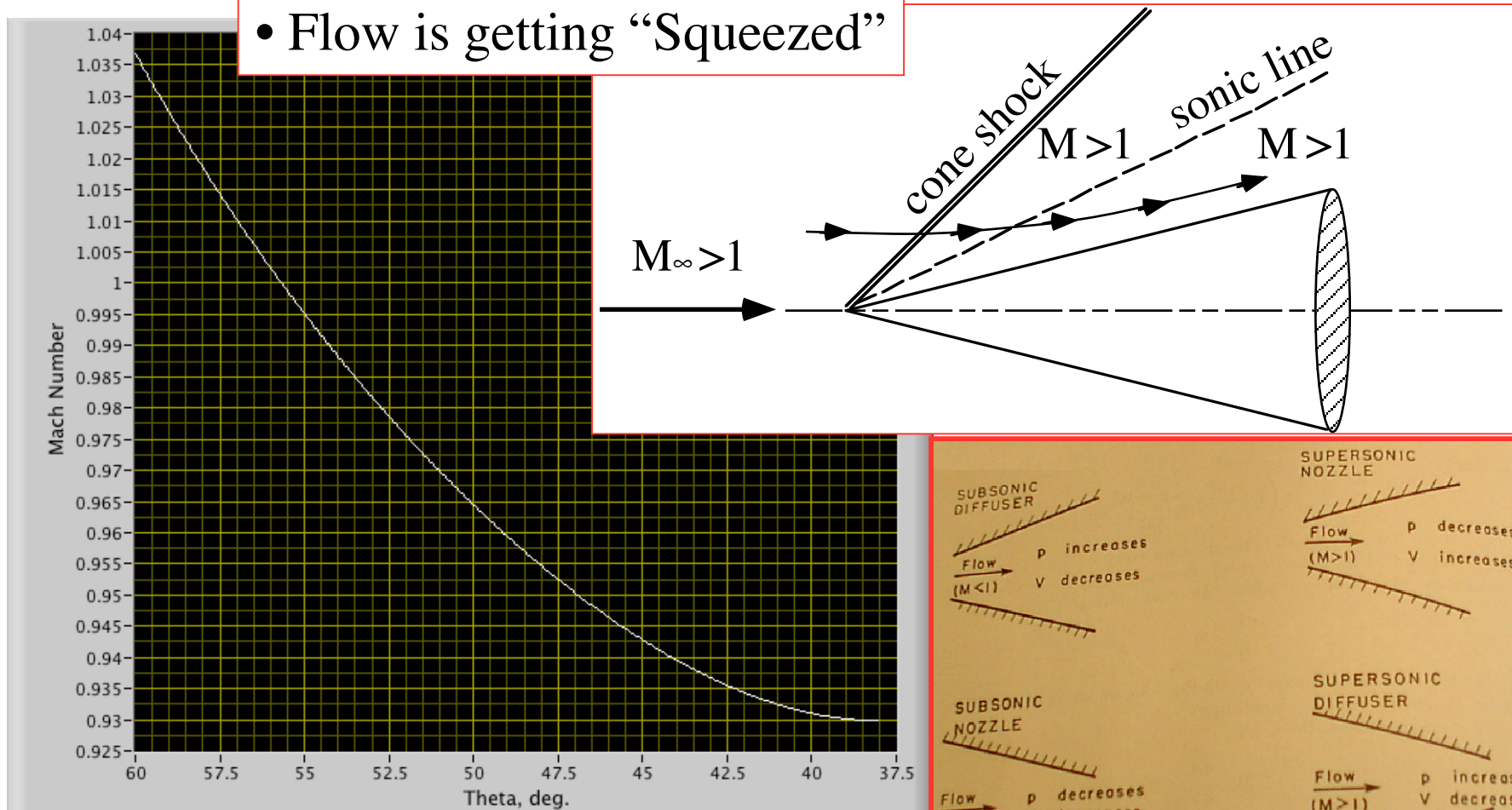
Gamma  
1.40

Assumed Beta (wave angle, deg)  
60.00001

# Isentropic Deceleration on Cone with shock wave near detachment angle

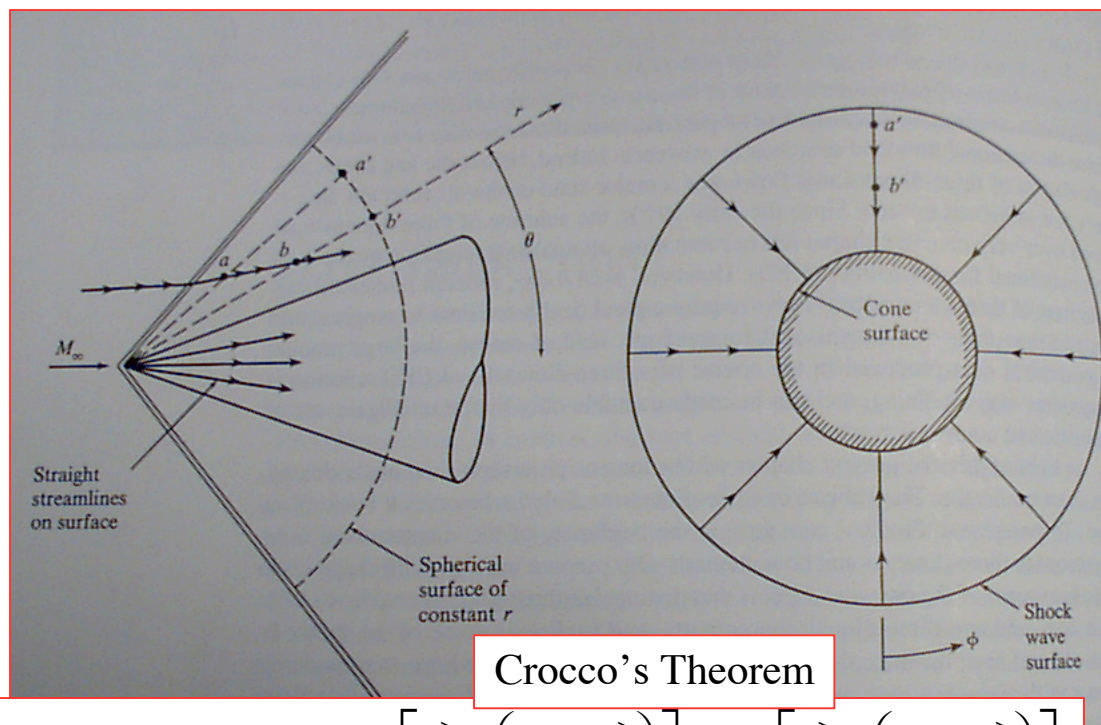
(cont'd)

- Flow is getting "Squeezed"



# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack

- Look at Zero- $\alpha$  conical flow field projected onto spherical surface



Crocco's Theorem

$$[T\nabla s]_1 = [T\nabla s]_2 \rightarrow \left[ \vec{V} \times (\nabla \times \vec{V}) \right]_1 = \left[ \vec{V} \times (\nabla \times \vec{V}) \right]_2$$

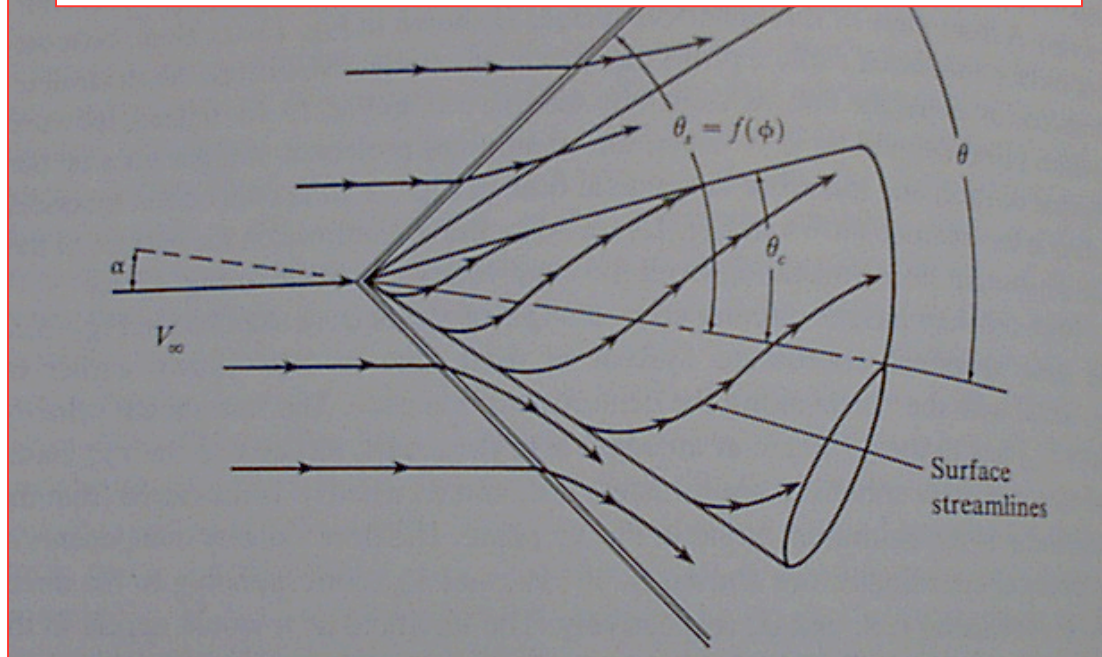
- Really a special case Of a 1-dimensional Flow field
- Shock strength is uniform ... irrotational flow field
- Simplifying conditions result in flow field That is “easy” to solve

$$\nabla \times \vec{V} = 0 \quad 54$$

# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- Look at Non Zero- $\alpha$  conical flow field

$$[T\nabla s]_1 \neq \text{const} \rightarrow \vec{V} \times (\nabla \times \vec{V}) \neq 0$$



- Shock Strength is no longer uniformly strong

- Tds is no longer constant

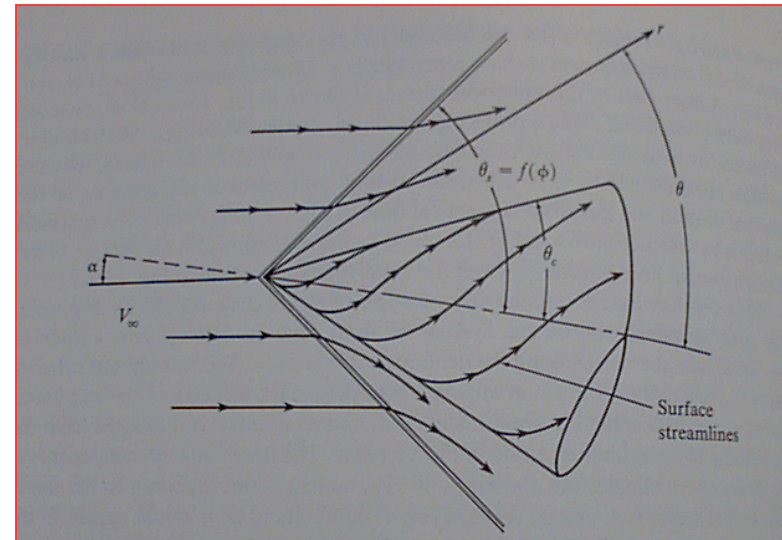
- Flow field is “rotational”

$$\frac{\partial}{\partial \phi} [ ] \neq 0 \rightarrow \frac{\partial}{\partial r} [V] \neq 0$$

# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- Look at Non Zero- $\alpha$  conical flow field

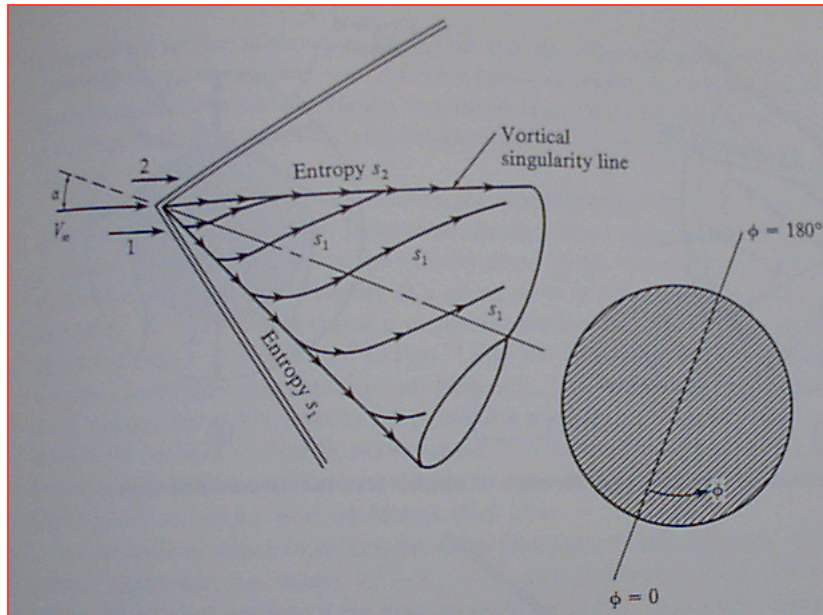
- 1) Flow field is a function of two independent variables  $\theta, \phi$
- 2) Shock wave angle  $\beta_s$  is different for each meridional plane ( $\phi$ )
- 3) Stream lines about body are curved
- 4) From windward to leeward surface
- 5) Stream lines that pass thru different Point on shock wave experience different Entropy changes





## Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

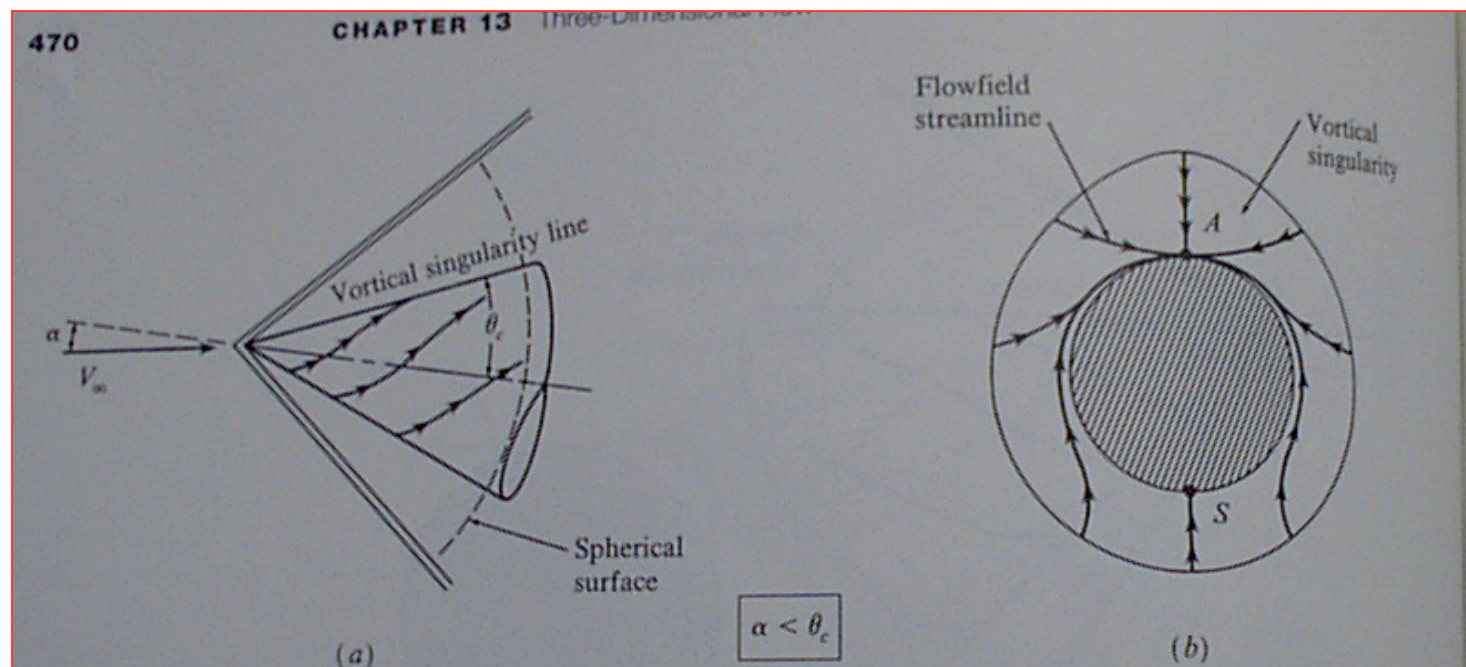
- “Vortical Singularity”



- Stream lines with different entropy levels converge on a single line on leeward side
- Ray along cone surface at  $180^\circ$  degrees to freestream wind has “multi-valued” entropy level
- Referred to as “Vortical Singularity”

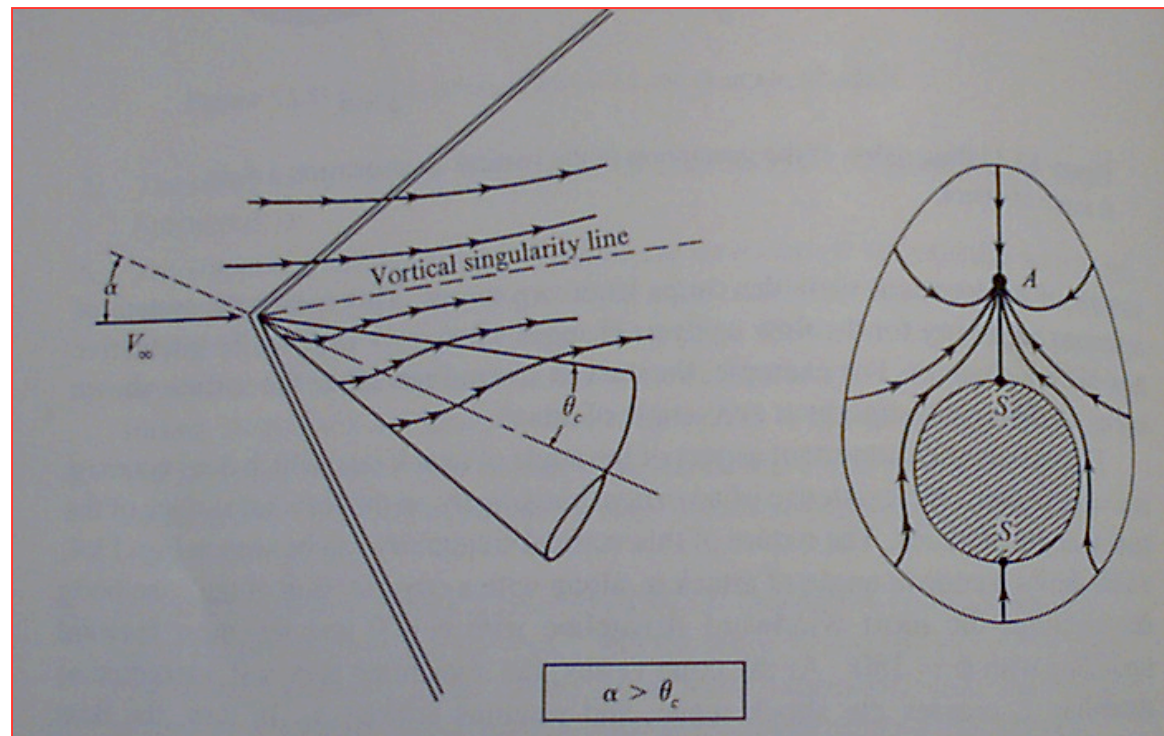
## Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- When  $\alpha < \theta_{\text{cone}}$  ... singularity lies along cone surface



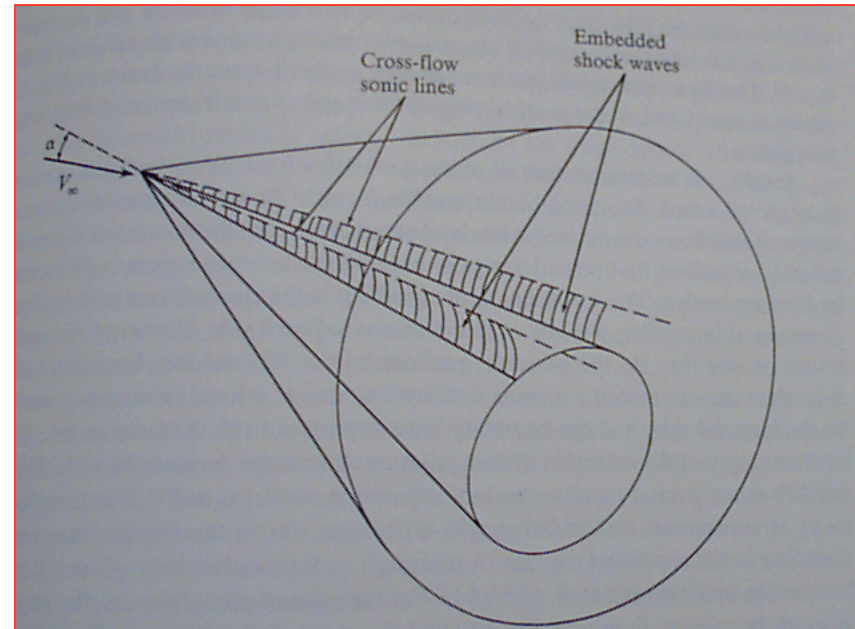
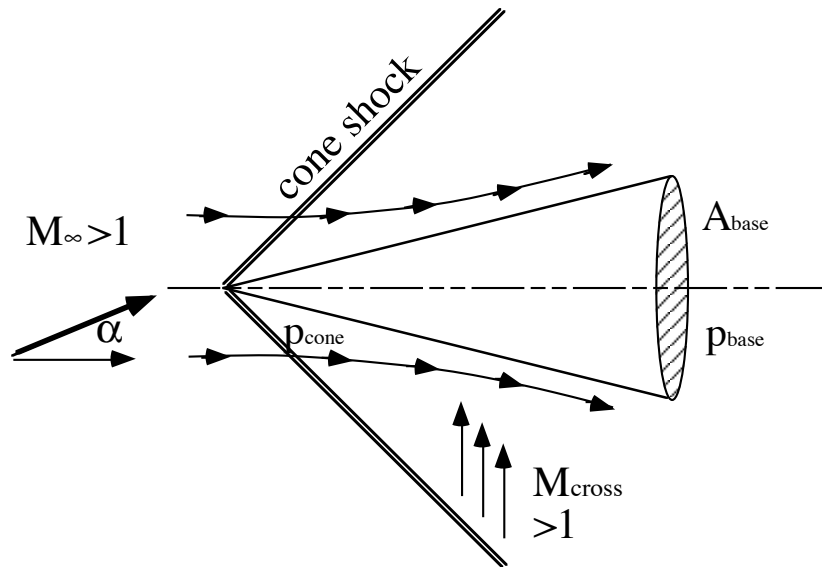
## Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- When  $\alpha > \theta_{\text{cone}}$  ... singularity lies above cone surface



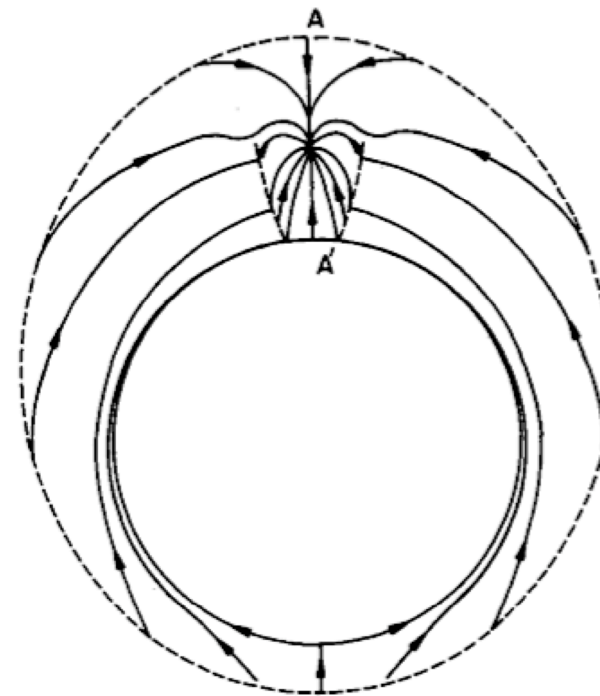
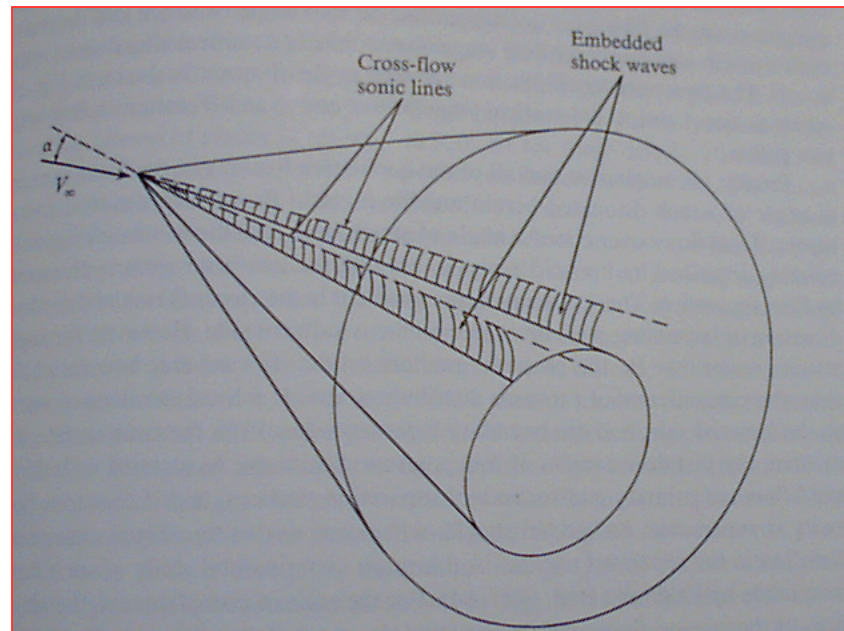
# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- Cross Flow Sonic Lines, cross flow Mach number  $> 1$



# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

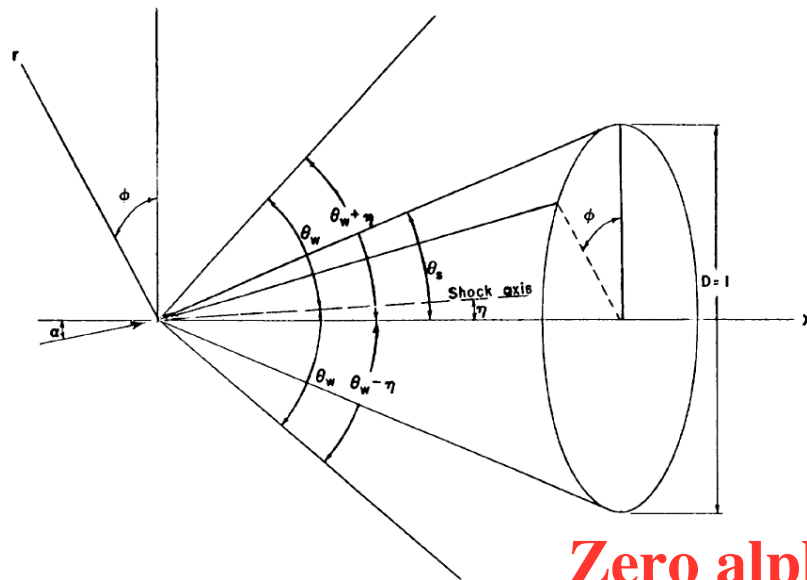
- Cross Flow Sonic Lines, cross flow Mach number  $> 1$



Streamline pattern at  $M_\infty = 7$ , incidence =  $30^\circ$ , and nose angle =  $20^\circ$ .

# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- “Small angle” approximation
- Solution formulated as “corrections” to zero- $\alpha$  solution



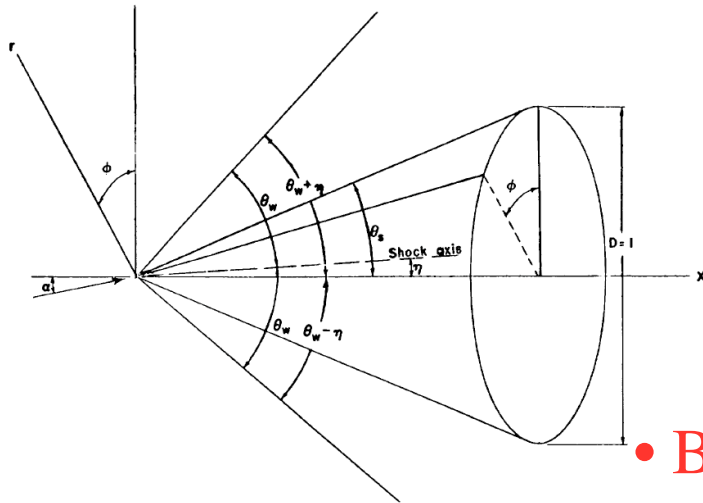
$$\begin{aligned} \vartheta_r &= \vartheta_{r_{\alpha=0}} + \alpha \left[ \vartheta_{r_{\alpha}} \cos \phi \right] \\ \vartheta_{\theta} &= \vartheta_{\theta_{\alpha=0}} + \alpha \left[ \vartheta_{\theta_{\alpha}} \cos \phi \right] \\ \vartheta_{\phi} &= \alpha \left[ \vartheta_{\phi_{\alpha}} \cos \phi \right] \end{aligned}$$

**Zero alpha condition**

**“Correction”**

# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- “Taylor-Maccoll” type of equation for alpha perturbations



$$\frac{1}{f} \frac{d^2 \vartheta_{r\alpha}}{d\theta^2} + \frac{A}{f} \frac{d\vartheta_{r\alpha}}{d\theta} + \frac{B}{f} + C = 0 \rightarrow \frac{d\vartheta_{r\alpha}}{d\theta} = \vartheta_{\theta\alpha}$$

$A, B, C, D = \text{func}(\text{zero alpha solution})$

$$f = \frac{P_{\alpha=0} + \alpha [P_{\alpha} \cos \phi]}{P_{\alpha=0}} - \gamma \frac{\rho_{\alpha=0} + \alpha [\rho_{\alpha} \cos \phi]}{\rho_{\alpha=0}}$$

- **Boundary conditions (behind shock wave)**

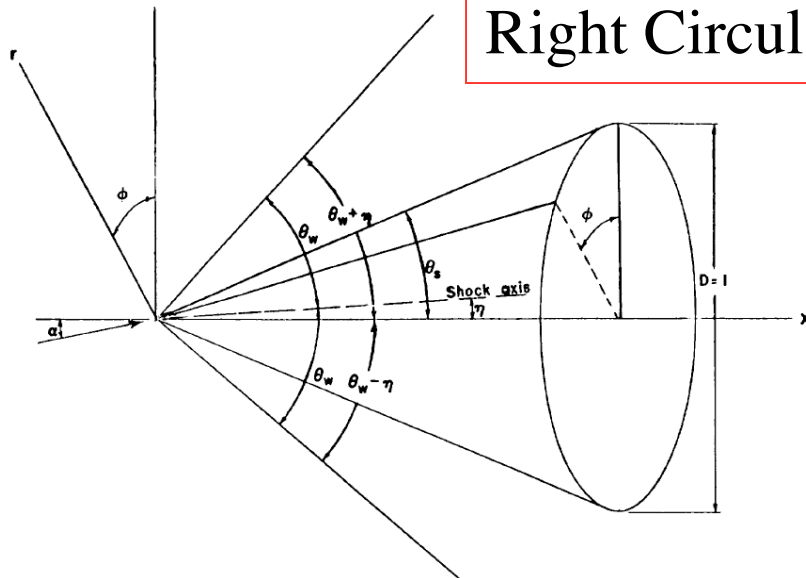
$$\left( \vartheta_{r\alpha} \right)_{shock} = \frac{c^2 f}{\gamma(\gamma - 1)(\vartheta_{r\alpha=0} + \vartheta_{\theta\alpha=0} \cot \beta_{shock})}$$

$$\left( \vartheta_{\theta\alpha} \right)_{shock} = \frac{2c^2 \cot \theta (2\vartheta_{r\alpha=0} - \vartheta_{\theta\alpha=0} \cot \beta_{shock})}{\gamma(\gamma^2 - 1)(\vartheta_{r\alpha=0} + \vartheta_{\theta\alpha=0} \cot \beta_{shock})^2}$$

# Qualitative Aspects of Conical Supersonic Flow Fields at Angles of Attack (cont'd)

- Solution is similar (but more complex) than zero alpha case  
Starts at shock wave and works toward surface
- Solution tables for right cones

NASA SP 3007 "Tables for Flow Around Right Circular Cones at Small Angle of Attack"



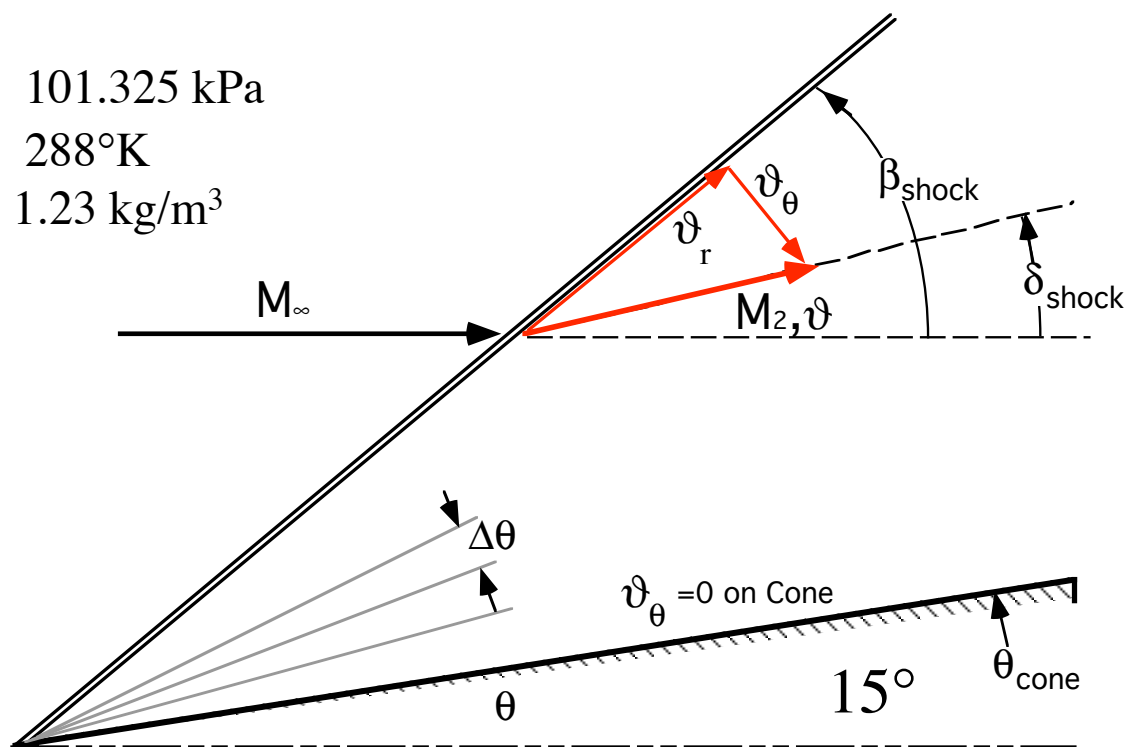
**Link to paper in appendix to this section**



# Homework 12

- Code Taylor-Maccoll algorithm for cone flow
- Solve for flow conditions on surface of Cone at freestream Mach 2.0 with 15° half angle

$$\begin{aligned}
 p_\infty &= 101.325 \text{ kPa} \\
 T_\infty &= 288^\circ\text{K} \\
 \rho_\infty &= 1.23 \text{ kg/m}^3
 \end{aligned}$$



## Part 1 Solution

$$11.1 \text{ (a) } \theta_{\text{shock}} = 0.592 \text{ rad} = \boxed{33.9^\circ}$$

$$\text{(b) } p_s/p_\infty = 1.286 \therefore p_s = 1.286 (1.01 \times 10^5) = \boxed{1.3 \times 10^5 \text{ N/m}^2}$$

$$\rho_s/\rho_\infty = 1.196 \therefore \rho_s = 1.196 (1.23) = \boxed{1.47 \text{ kg/m}^3}$$

$$T_s/T_\infty = 1.075 \therefore T_s = 1.075 (288) = \boxed{310^\circ\text{K}}$$

$$M_s = \boxed{1.835}$$

$$\text{(c) } p_c/p_\infty = 1.566 \qquad \boxed{p_c = 1.58 \times 10^5 \text{ N/m}^2}$$

$$\rho_c/\rho_\infty = 1.377 \qquad \boxed{\rho_c = 1.69 \text{ kg/m}^3}$$

$$T_c/T_\infty = 1.137 \qquad \boxed{T_c = 327^\circ\text{K}}$$

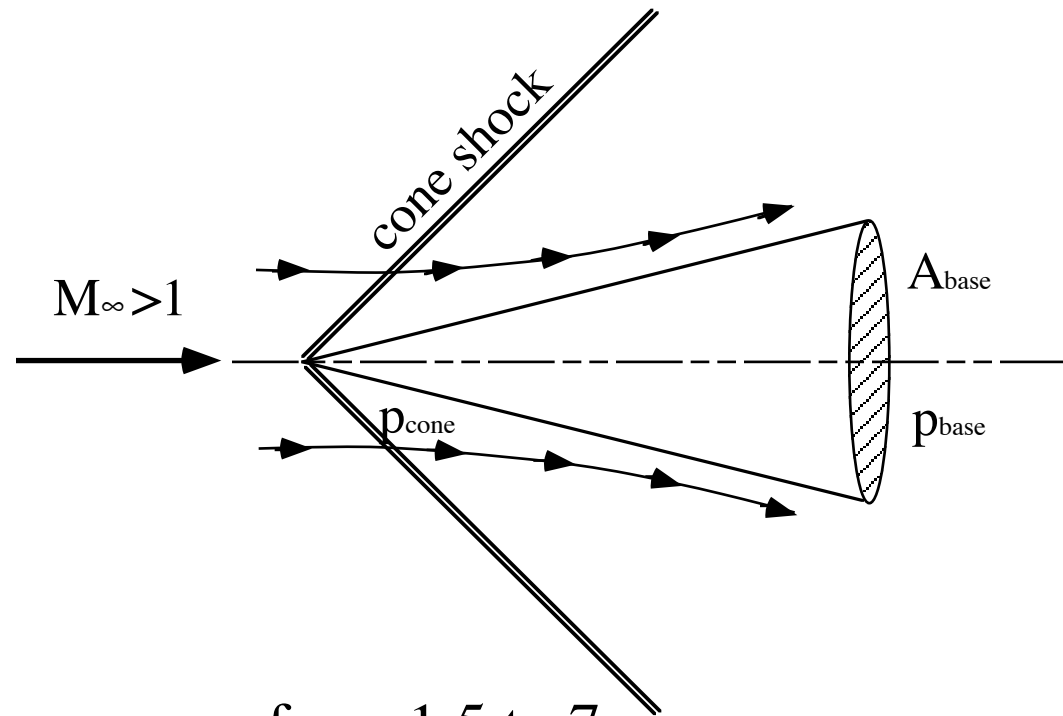
$$\boxed{M_c = 1.707}$$

## Homework 12 (Continued)

- Define  $C_{D_{cone}} = \frac{D_{cone}}{q_{\infty} A_{base}}$

**• Hint: You'll have to do trial  
And error for each mach number to get the  
Shock angle correct**

- Derive an expression for the cone wave drag as a function of the cone surface pressure ( $p_{cone}$ ) and the base pressure ( $p_{base}$ )



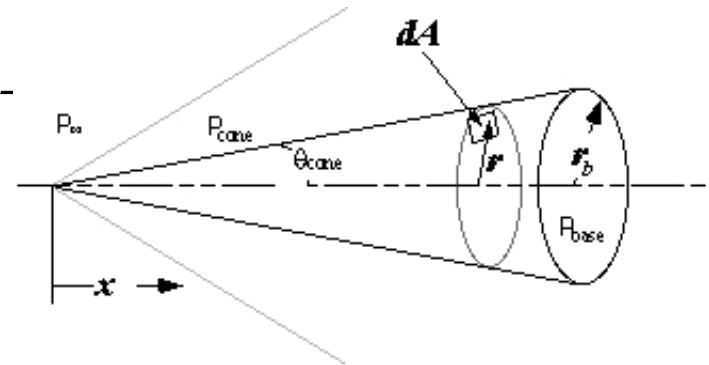
- Assume  $p_{base} = p_{\infty}$   
plot  $C_{D_{cone}}$  versus Mach over range from 1.5 to 7

11.2

Part 2 Solution

$$dA = r d\theta \frac{dx}{\cos\theta} \quad dD = p_{cone} \left( r d\theta \frac{dx}{\cos\theta} \right) \sin\theta -$$

$$dD = p_{cone} (r d\theta dx) \tan\theta - p_{base} r d\theta dr$$



from cone geometry

$$\frac{r}{x} = \tan\theta \therefore x = \frac{r}{\tan\theta} \text{ and } dx = \frac{dr}{\tan\theta} \dots \text{sub in}$$

$$dD = (p_{cone} - p_{base}) r dr d\theta$$

$$C_{D_{cone}} = \frac{D_{cone}}{q_{\infty} A_{base}} = \frac{1}{\frac{\gamma}{2} M_{\infty}^2} \left[ \frac{p_{cone}}{p_{\infty}} - \frac{p_{base}}{p_{\infty}} \right]$$

Integrate around circumference

$$D = \int_0^{r_b} \int_0^{2\pi} dD = 2\pi (p_{cone} - p_{base}) \frac{r_b^2}{2} = \pi (p_{cone} - p_{base}) r_b^2$$

Normalize ...

$$C_D = \frac{D}{q_{\infty} A_b} = \frac{D}{q_{\infty} \pi r_b^2} = \frac{p_{cone} - p_{base}}{q_{\infty}} \rightarrow \text{if } p_{base} = p_{cone} \rightarrow \boxed{C_{D_{cone}} \frac{p_{cone} - p_{\infty}}{q_{\infty}}}$$

## Part 2 Solution (cont'd)

when  $p_b = p_\infty$ , For  $\theta_c = 15^\circ$

$\underline{M_\infty}$	$C_{D_{cone}}$
1.5	0.24
2.0	0.202
3.0	0.173
4.0	0.161
5.0	0.154
6.0	0.150
7.0	0.148

# Part 2 Solution (concluded)

