

Section 7.3 Supplement

Rocket Science Review 103: Estimating the Launch Vehicle Drag Coefficient

**Newton's Laws as
Applied to
"Rocket Science"**

**... its not just a job ... its an
adventure**

Newtonian Flow Analysis



Fin Leading Edge Drag

- Stagnation Pressure Coefficient calculated based on Mach number Normal to leading edge of fins
- Scaled by leading edge area, $W \cdot t$
- Assumed fin thickness, t

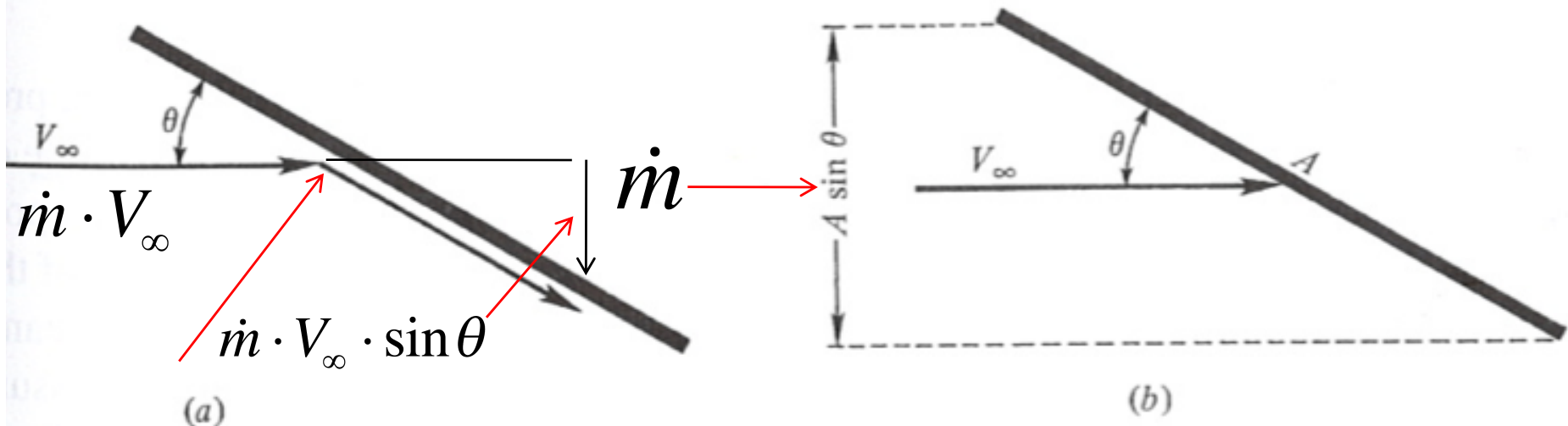
$$C_{P_{\max}} = \frac{q_c - p_\infty}{\bar{q}} = \frac{p_\infty \cdot \left(1 + \frac{\gamma-1}{2} M_\perp^2\right)^{\frac{\gamma}{\gamma-1}} - p_\infty}{\frac{\gamma}{2} p_\infty M_\perp^2} = \frac{\left(1 + \frac{\gamma-1}{2} \cdot (M_\infty \cdot \cos \theta_{L.E.})^2\right)^{\frac{\gamma}{\gamma-1}} - 1}{\frac{\gamma}{2} \cdot (M_\infty \cdot \cos \theta_{L.E.})^2}$$

$$\left(C_{D_{L.E.}}\right)_{total\ fins} = \sum_{i=1}^{N_{fins}} \left(\frac{W_i \cdot t_i}{A_{ref}}\right) \cdot \left\{ \left(C_{P_{\max}}\right)_{subsonic} \right\}_i = \sum_{i=1}^{N_{fins}} \left(\frac{W_i \cdot t_i}{A_{ref}}\right) \cdot \left\{ \frac{\left(1 + \frac{\gamma-1}{2} \cdot (M_\infty \cdot \cos \theta_{L.E.})_i^2\right)^{\frac{\gamma}{\gamma-1}} - 1}{\frac{\gamma}{2} \cdot (M_\infty \cdot \cos \theta_{L.E.})_i^2} \right\}_i$$

Tends to Over-predict drag, Model can be refined using Newtonian Flow Theory

Newtonian Flow Analysis

- Newton had an Often unrecognized original contribution to Fluid Mechanics Propositions 34 and 35 in “*Principia...*”
- “*Impact Theory*”

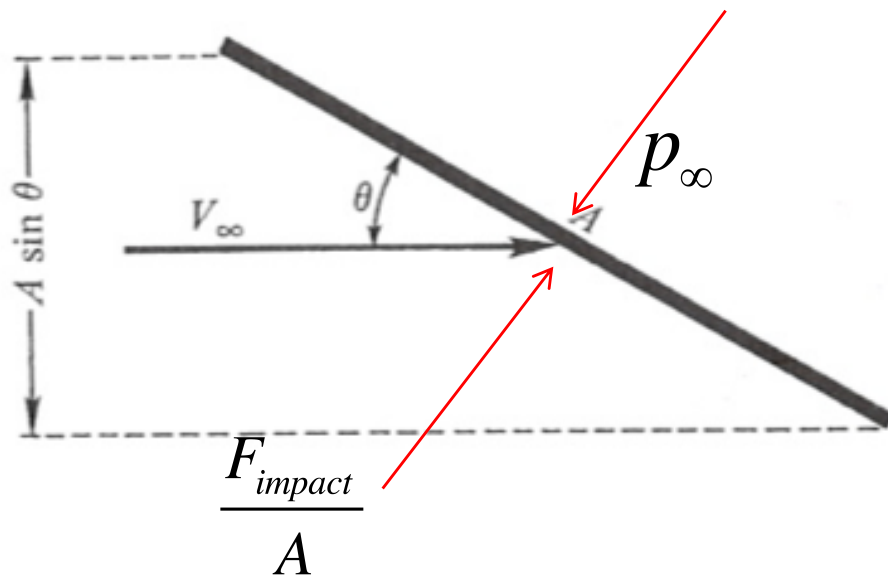


$$F_{impact} = \text{change in momentum} = \dot{m} \cdot V_{\infty} \cdot \sin \theta$$

$$\rightarrow F_{impact} = \rho_{\infty} \cdot V_{\infty} \cdot (A \sin \theta) \cdot V_{\infty} \cdot \sin \theta = \rho_{\infty} \cdot V_{\infty}^2 \cdot A \cdot \sin^2 \theta$$

Newtonian Flow Analysis (2)

$$F_{impact} = \rho_{\infty} \cdot V_{\infty}^2 \cdot A \cdot \sin^2 \theta \rightarrow p(\theta) = \frac{F_{impact}}{A} + p_{\infty} = \rho_{\infty} \cdot V_{\infty}^2 \cdot \sin^2 \theta + p_{\infty}$$

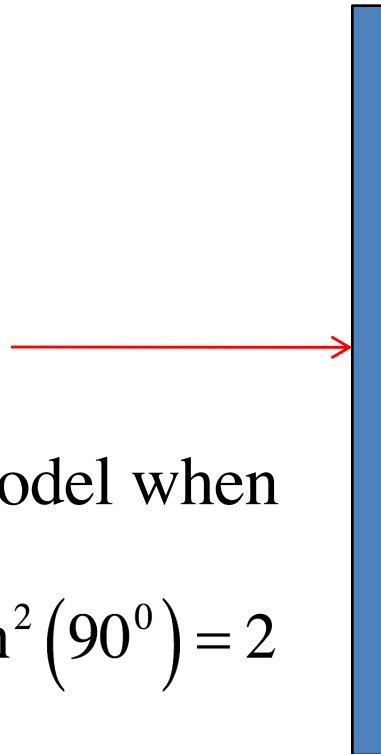


Newton Ignores the random motion of the molecules and
Considers only the linear or translational motion

$$C_p(\theta) = \frac{p(\theta) - p_{\infty}}{\frac{1}{2} \rho_{\infty} \cdot V_{\infty}^2} = \frac{\rho_{\infty} \cdot V_{\infty}^2 \cdot \sin^2 \theta + p_{\infty} - p_{\infty}}{\frac{1}{2} \rho_{\infty} \cdot V_{\infty}^2} = 2 \cdot \sin^2 \theta$$

Newtonian Flow Analysis (3)

$$C_p(\theta) = \frac{p(\theta) - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} = 2 \cdot \sin^2 \theta$$



What happens in Newtonian Model when

$$\theta = 90^0 \quad ? \quad C_p(90^0) = 2 \cdot \sin^2(90^0) = 2$$

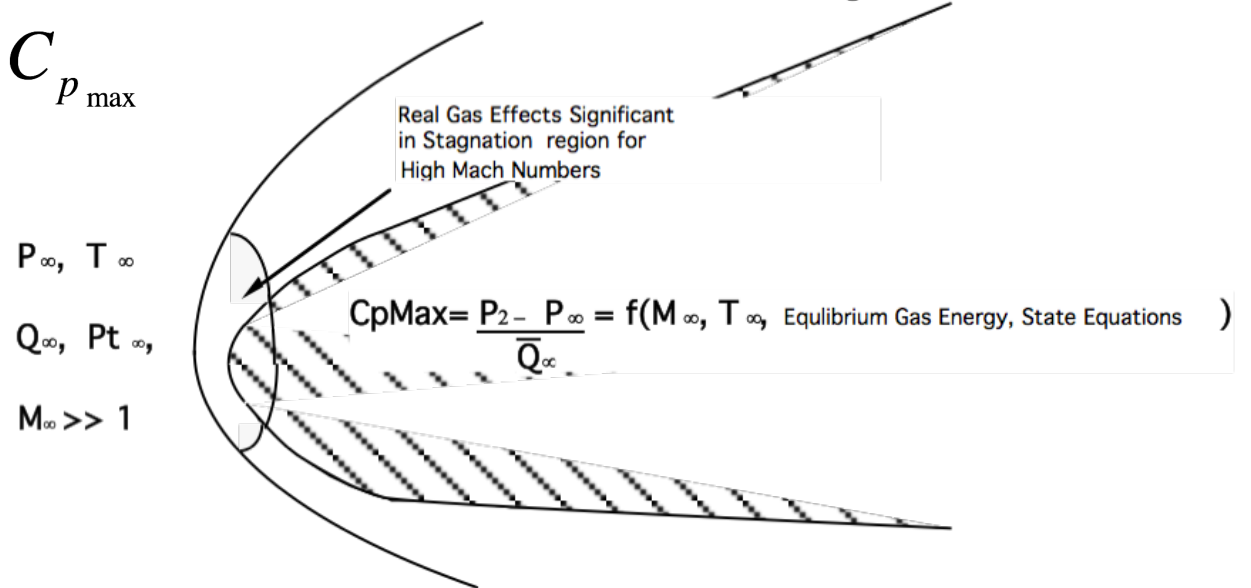
But for direct impact ...

$$p(90^0) = P_0 \rightarrow C_p(90^0) = \frac{P_0 - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} \equiv C_{p_{\max}} !$$

Newtonian Flow Analysis (4)

$$C_p(90^\circ) = \frac{P_0 - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} \equiv C_{p_{\max}}$$

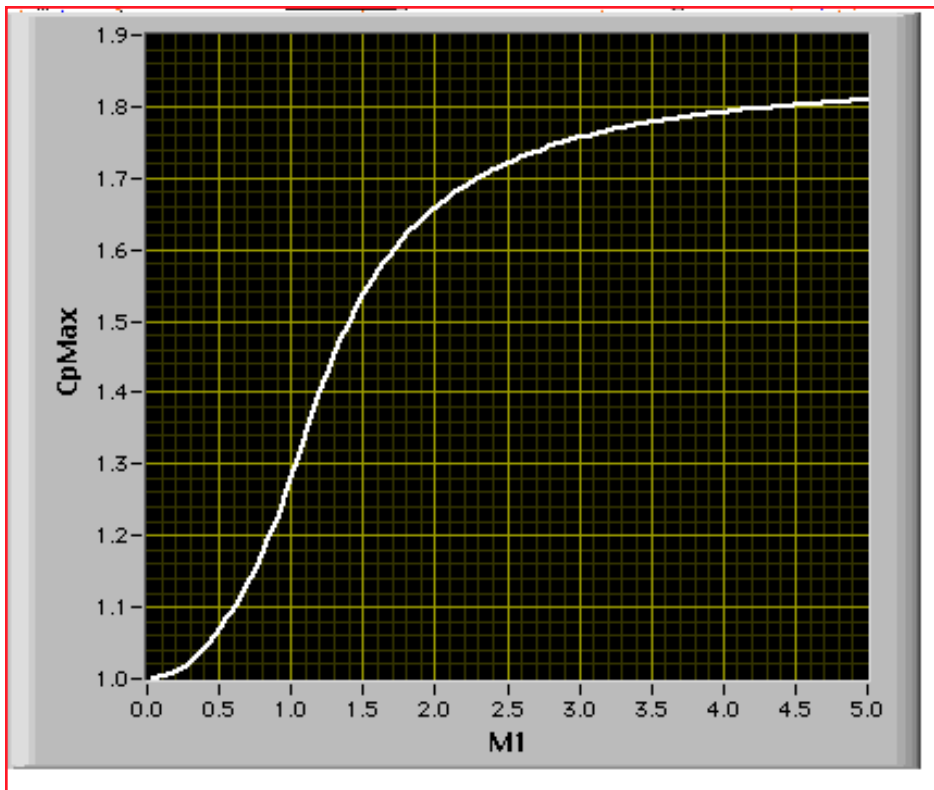
Schematic of the Bow Shock near the Stagnation Point



$$C_{p_{\max}} = \left[\frac{(P_{02} - p_\infty)}{\frac{1}{2} \rho_\infty V_\infty^2} \right] = \frac{(P_{02} - p_\infty)}{\frac{\gamma}{2} p_\infty M_\infty^2} = \frac{1}{\frac{\gamma}{2} M_\infty^2} \left\{ \frac{\left(\frac{\gamma + 1}{2} M_\infty^2 \right)^{\left(\frac{\gamma}{\gamma - 1} \right)}}{\left(\frac{2\gamma}{(\gamma + 1)} M_\infty^2 - \frac{(\gamma - 1)}{(\gamma + 1)} \right)^{\left(\frac{1}{\gamma - 1} \right)}} - 1 \right\}$$

Newtonian Flow Analysis (5)

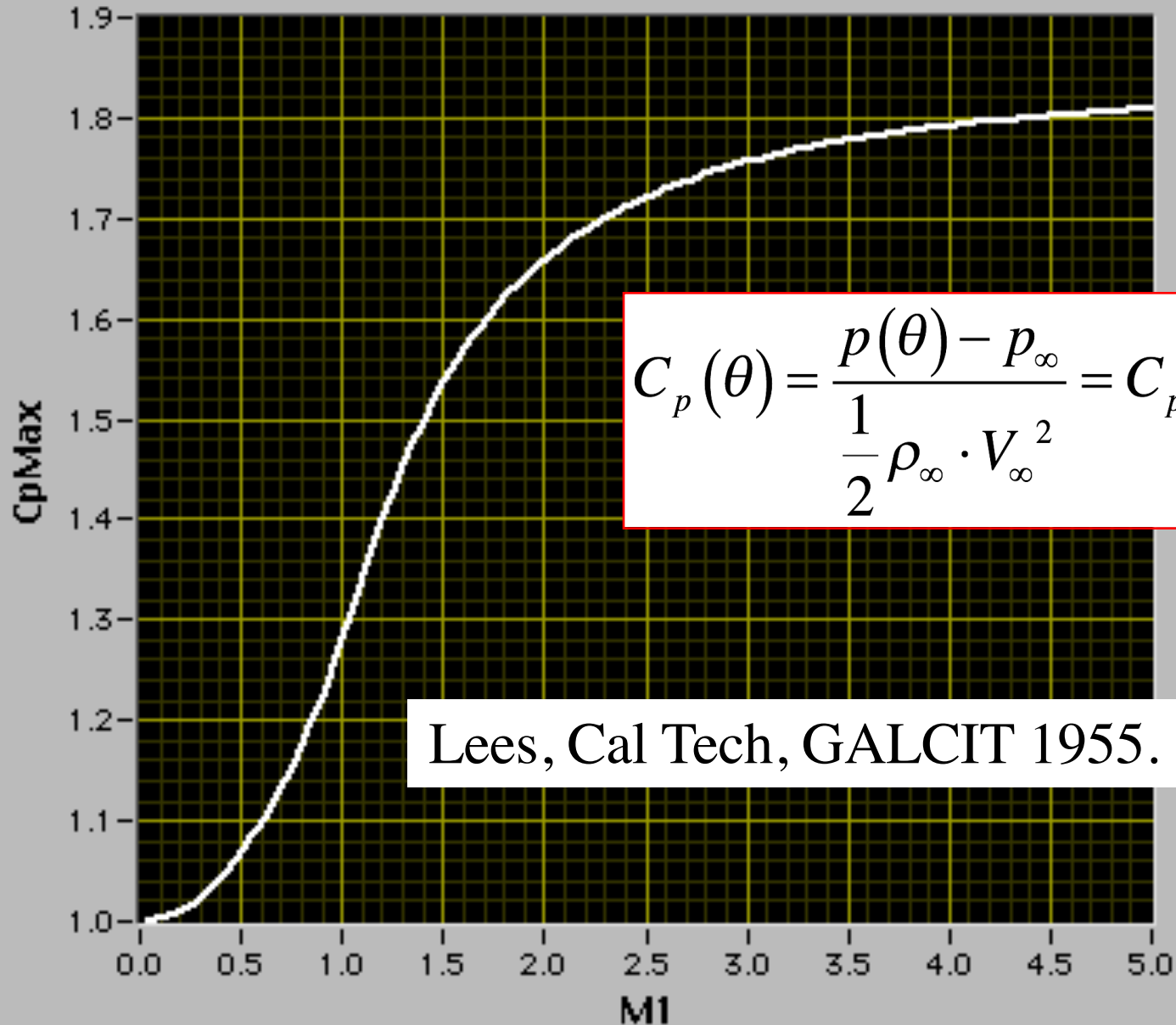
$$C_{p_{\max}} = \frac{1}{\frac{\gamma}{2} M_{\infty}^2} \left\{ \frac{\left(\frac{\gamma+1}{2} M_{\infty}^2 \right)^{\left(\frac{\gamma}{\gamma-1} \right)}}{\left(\frac{2\gamma}{\gamma+1} M_{\infty}^2 - \frac{\gamma-1}{\gamma+1} \right)^{\left(\frac{1}{\gamma-1} \right)}} - 1 \right\}$$



$$C_p(90^\circ) = \frac{P_0 - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} \equiv C_{p_{\max}}$$

< 2 always for $\gamma = 1.4$

“Modified Newtonian Flow”



$$C_p(\theta) = \frac{p(\theta) - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} = C_{p_{max}} \cdot \sin^2 \theta$$

Lees, Cal Tech, GALCIT 1955.

Modified Newtonian Flow (2)

$$C_p(\theta) = \frac{p(\theta) - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} = C_{p_{\max}} \cdot \sin^2 \theta$$

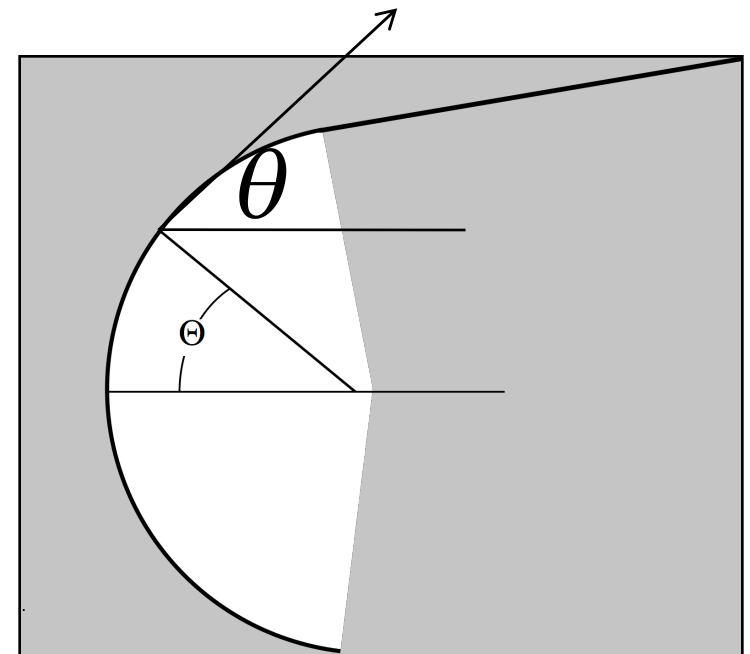
Often convenient to express model in terms of a Polar surface coordinate

$$\Theta = 90^\circ - \theta$$

$$C_p(\Theta) = \frac{p(\Theta) - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} = C_{p_{\max}} \cdot \sin^2(90^\circ - \Theta) =$$

$$C_{p_{\max}} \cdot \left[\sin(90^\circ) \cdot \cos(\Theta) - \sin(\Theta) \cdot \cos(90^\circ) \right]^2$$

$$\Rightarrow C_p(\Theta) = \frac{p(\Theta) - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} = C_{p_{\max}} \cdot \cos^2(\Theta)$$

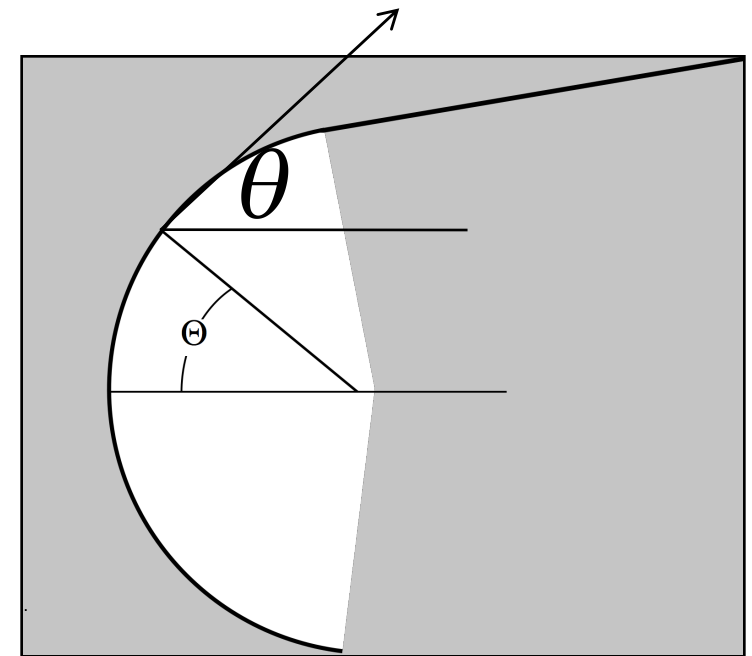


Modified Newtonian Flow (3)

Expressed in terms of pressure ratio

$$C_p(\Theta) = \frac{p(\Theta) - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} = C_{p_{\max}} \cdot \cos^2(\Theta) \Rightarrow \frac{p(\Theta) - p_\infty}{\frac{\gamma}{2} p_\infty \cdot M_\infty^2} = C_{p_{\max}} \cdot \cos^2(\Theta)$$

$$\frac{p(\Theta)}{p_\infty} = 1 + \frac{\gamma}{2} \cdot M_\infty^2 \cdot C_{p_{\max}} \cdot \cos^2(\Theta)$$



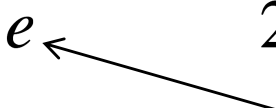
$$\Theta = 90^\circ - \theta$$

Modified Newtonian Flow (4)

$$\Rightarrow C_p(\Theta) = \frac{p(\Theta) - p_\infty}{\frac{1}{2} \rho_\infty \cdot V_\infty^2} = C_{p_{\max}} \cdot \cos^2(\Theta)$$

“equivalent to infinite Mach number assumption”

- As derived in section 3

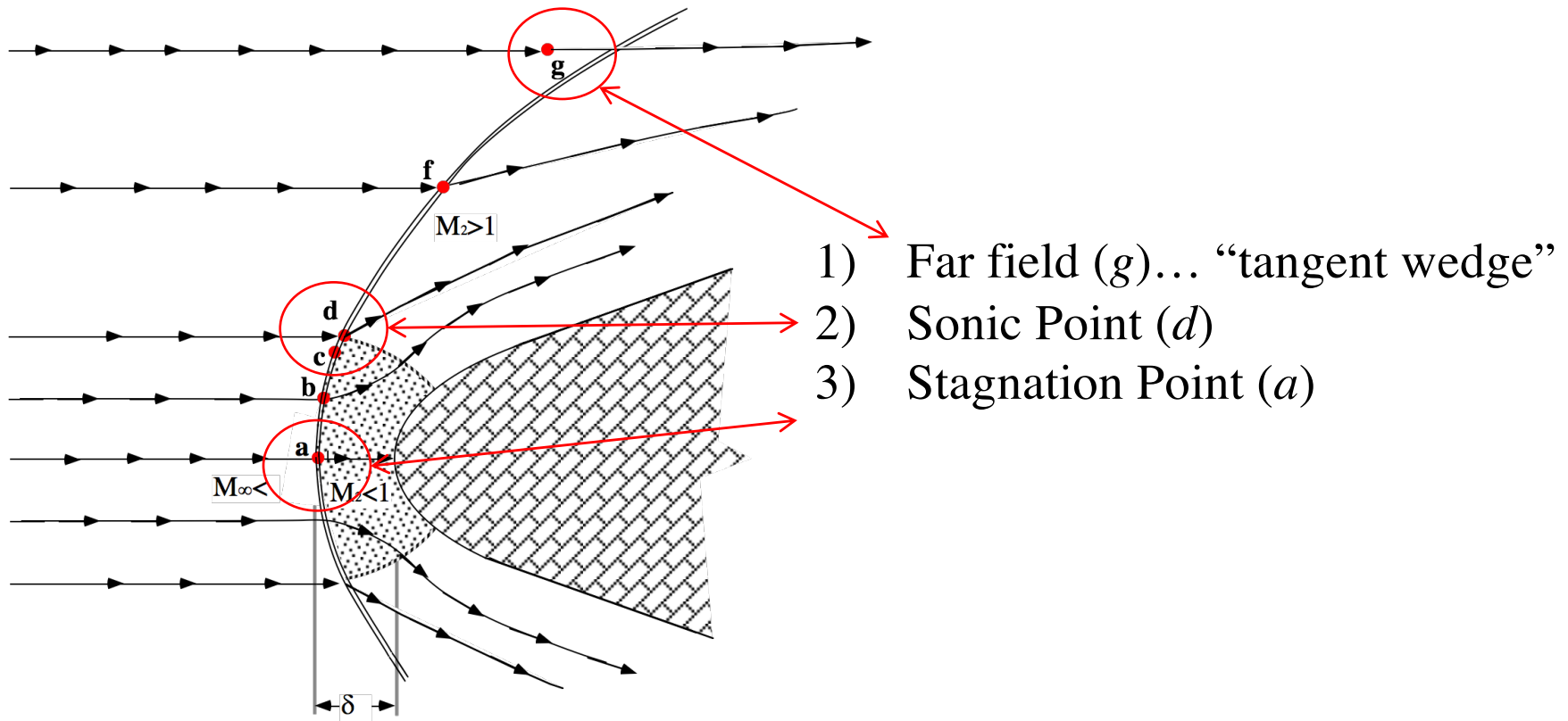
$$\frac{V^2/2}{e} = \frac{\gamma(\gamma-1)}{2} M^2$$


For Newtonian model ... Newton Ignores the random motion of the molecules and Considers only the linear or translational motion

Mach number is a measure of the ratio of the fluid Kinetic energy to the fluid internal energy (direct motion To random thermal motion of gas molecules) -- **Fundamental Parameter of Compressible Flow** --

Example 3

- Example: Cylindrically Blunted 2-D wedge, $M_\infty=10.0$, 1-cm Radius
- *Map conditions at three points along shock*



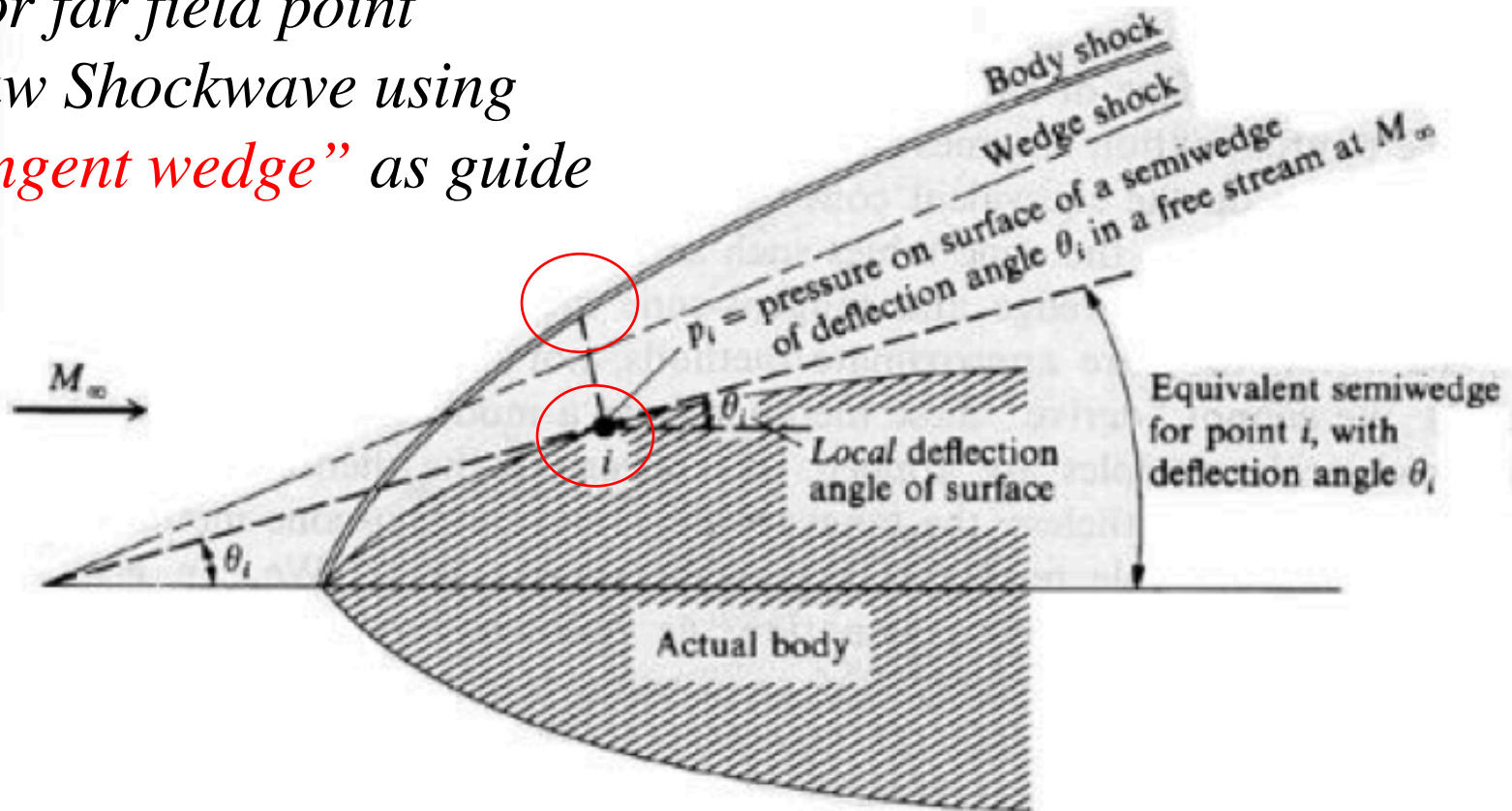
Example 3 (2)

- Example Cylindrically Blunted 2-D wedge, $M_\infty=10.0$ 1-cm Radius

- *For far field point*

Draw Shockwave using

“tangent wedge” as guide

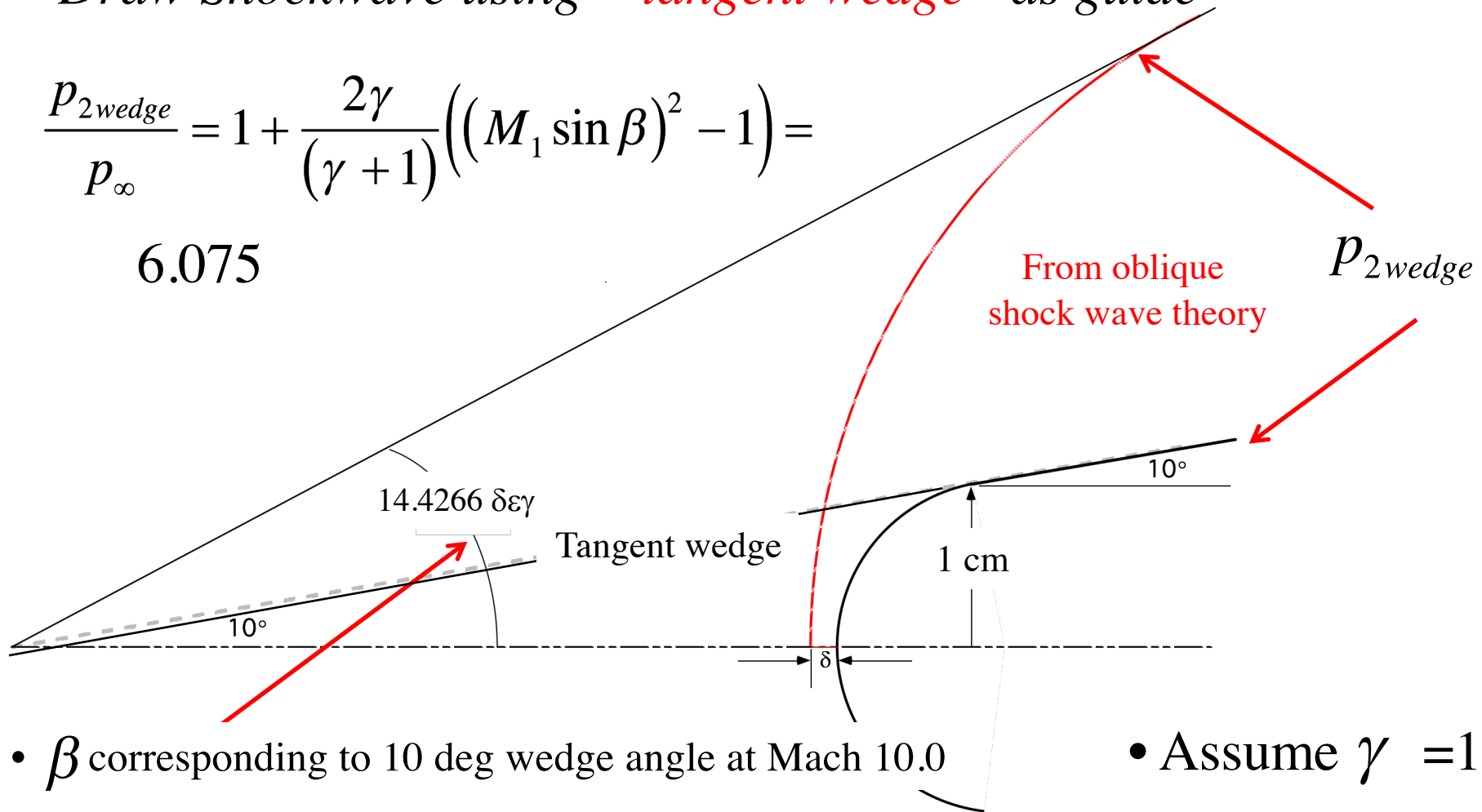


Example 3 (3)

- Example Cylindrically Blunted 2-D wedge, $M_\infty=10.0$ 1-cm Radius
- Draw Shockwave using *“tangent wedge”* as guide

$$\frac{P_{2wedge}}{P_\infty} = 1 + \frac{2\gamma}{(\gamma + 1)} \left((M_1 \sin \beta)^2 - 1 \right) =$$

6.075

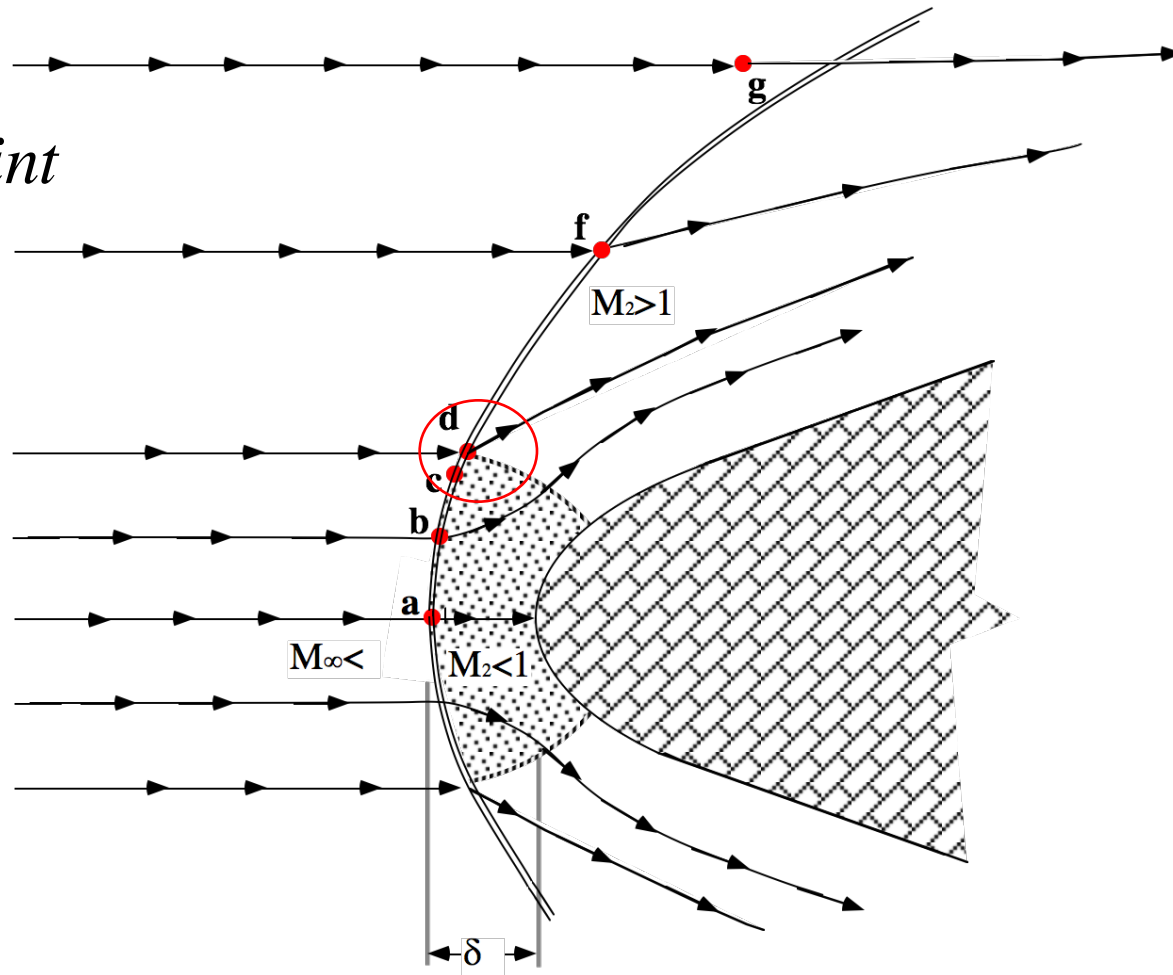


- β corresponding to 10 deg wedge angle at Mach 10.0

- Assume $\gamma = 1.4$

Example 3: Sonic Point Surface Conditions behind detached shock wave: (5)

Sonic Point



Example 3 (6)

- Compute Standoff Distance

$$\frac{\delta}{D} = 0.193 \cdot e^{\frac{4.67}{M_\infty^2}} = 2 \cdot 1 \cdot 0.193 \exp\left(\frac{4.67}{1.75^2}\right) = 0.4044 \text{ cm}$$

- Compute Sonic Point on Shock

$$\beta_{sonic} = \frac{180}{\pi} \sin^{-1} \sqrt{\frac{(\gamma - 3)M_1^2 + (\gamma + 1)M_1^4 + \sqrt{16\gamma M_1^4 + [(\gamma - 3)M_1^2 + (\gamma + 1)M_1^4]^2}}{4\gamma M_1^4}} = 67.335 \text{ deg.}$$

- Compute Sonic Point on Surface

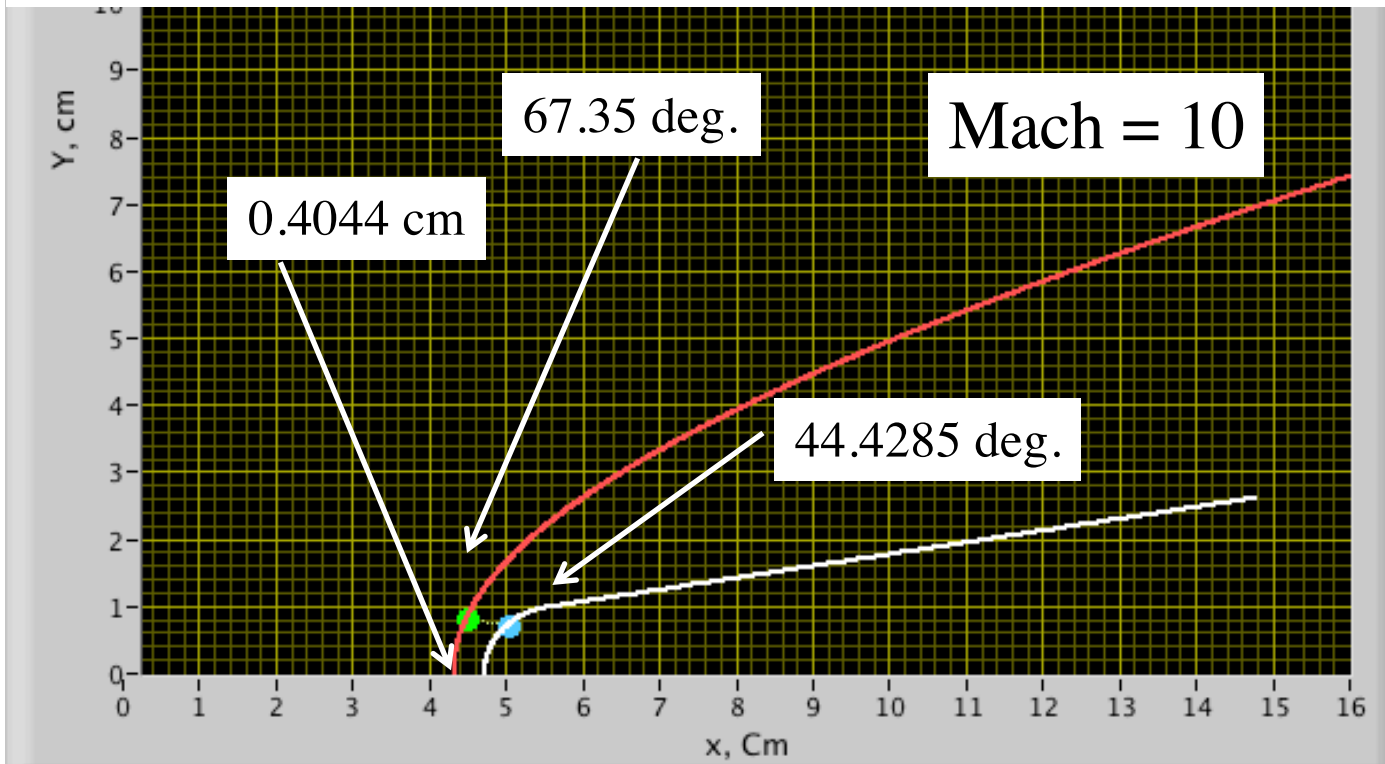
$$\tan(\theta_{sonic}) = \frac{2\{M_1^2 \sin^2(\beta_{sonic}) - 1\}}{\tan(\beta_{sonic})[2 + M_1^2[\gamma + \cos(2\beta_{sonic})]]} = 44.428 \text{ deg.}$$

See for derivation: http://mae-nas.eng.usu.edu/MAE_5420_Web/section8/section8.3.pdf

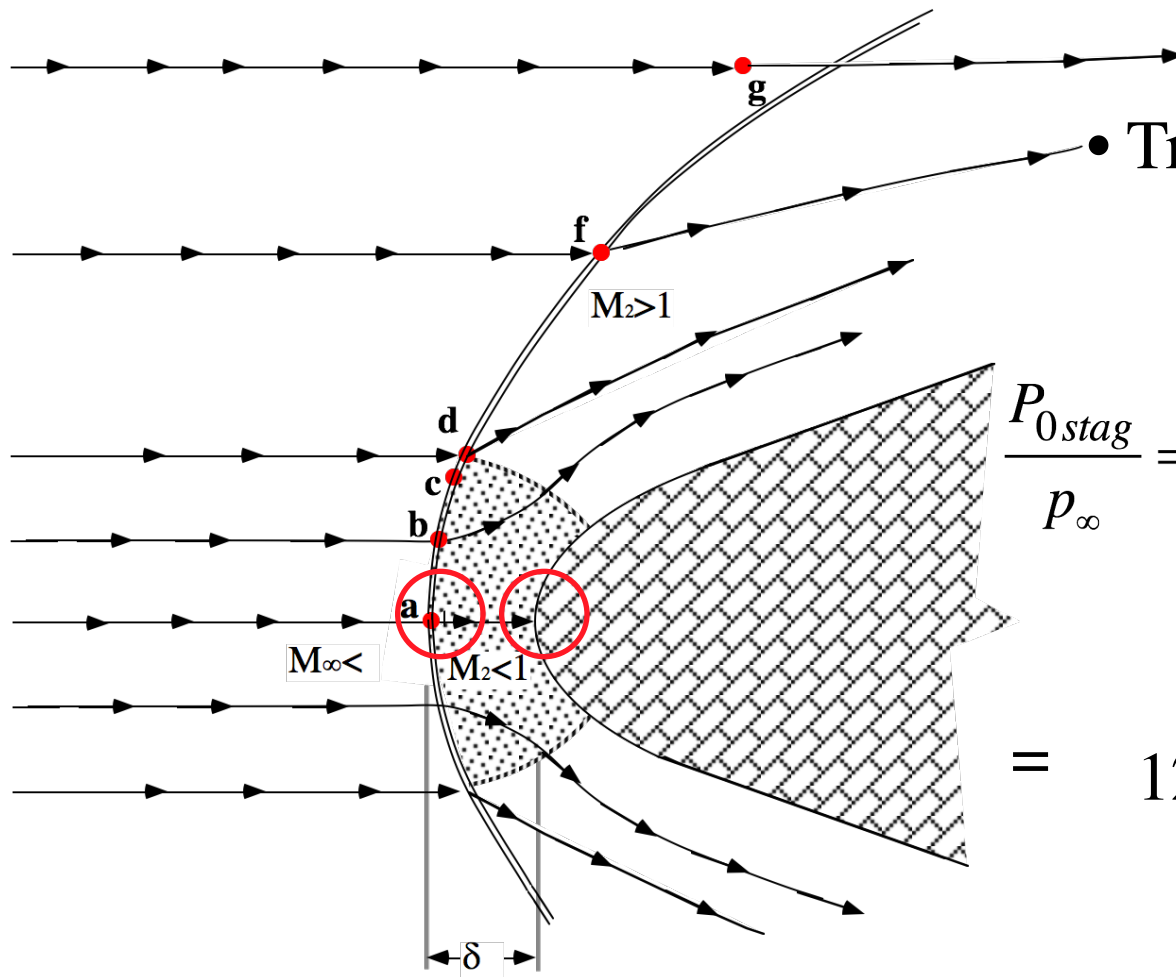
Example 3 (cont'd)

$$\frac{P_{sonic}}{P_{\infty}} = \frac{P_{sonic}}{P_{0sonic}} \frac{P_{0sonic}}{P_{\infty}} = \frac{1}{\left(1 + \frac{\gamma + 1}{2}\right)^{\left(\frac{\gamma}{\gamma - 1}\right)}} \left\{ \frac{\left(\frac{\gamma + 1}{2} [M_{\infty} \sin(\beta_{sonic})]^2\right)^{\left(\frac{\gamma}{\gamma - 1}\right)}}{\left(\frac{2\gamma}{\gamma + 1} [M_{\infty} \sin(\beta_{sonic})]^2 - \frac{\gamma - 1}{\gamma + 1}\right)^{\left(\frac{1}{\gamma - 1}\right)}} \right\} =$$

$$0.52828 \times 110.098512 = 64.16$$



Surface Conditions behind detached shock wave: *stagnation point* (cont'd)



• Treat as normal shockwave

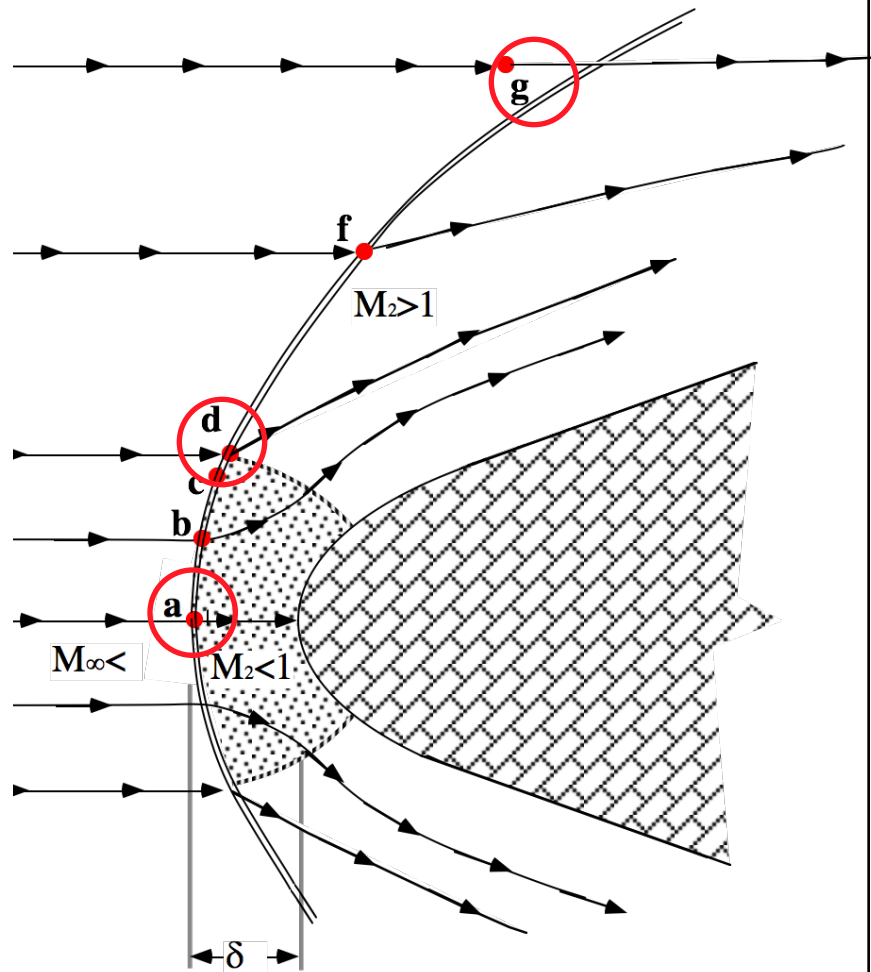
$$\frac{P_{0stagn}}{P_\infty} = \left\{ \frac{\left(\frac{\gamma + 1}{2} M_\infty^2 \right)^{\left(\frac{\gamma}{\gamma - 1} \right)}}{\left(\frac{2\gamma}{(\gamma + 1)} M_\infty^2 - \frac{(\gamma - 1)}{(\gamma + 1)} \right)^{\left(\frac{1}{\gamma - 1} \right)}} \right\}$$

$$= 129.21$$

• $M_\infty = 10.0$

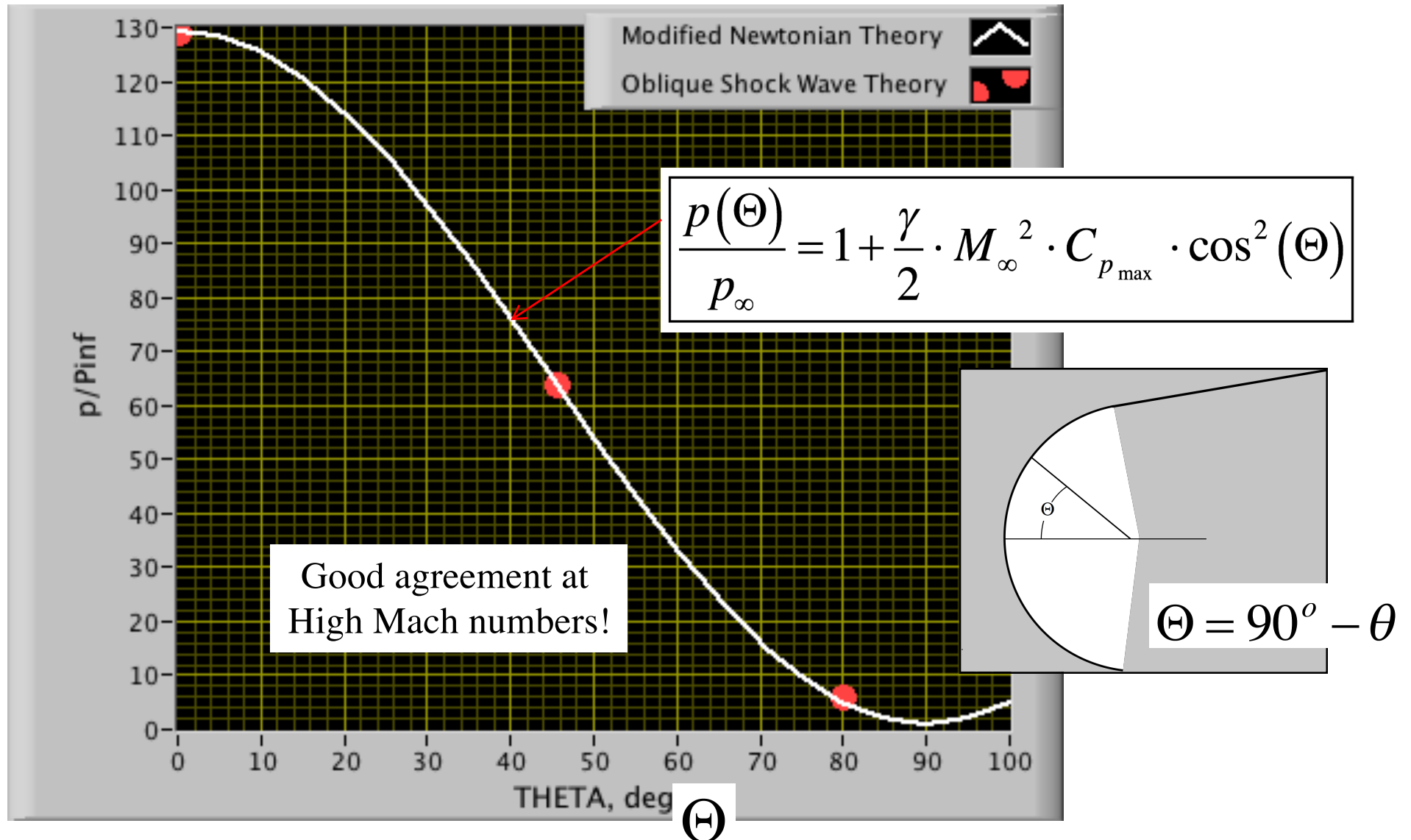
Plot Conditions along detached shock

summary $M_\infty = 10.0$



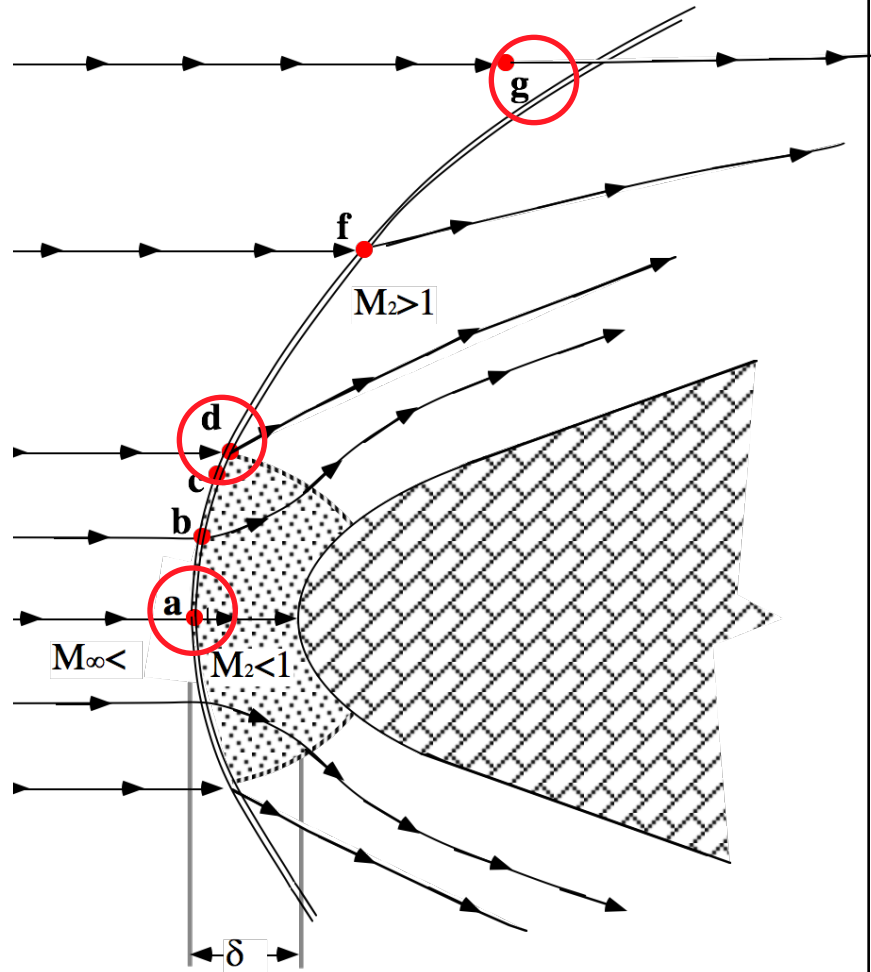
Point on Shock	beta, deg β	theta, deg θ	90°-theta Θ	$\frac{p_\theta}{p_\infty}$
a	90°	90°	0°	129.21
d	67.34°	44.43°	45.57°	64.16
g	14.43°	10°	80°	6.075

Surface Conditions behind detached shock wave: Mach 10.0



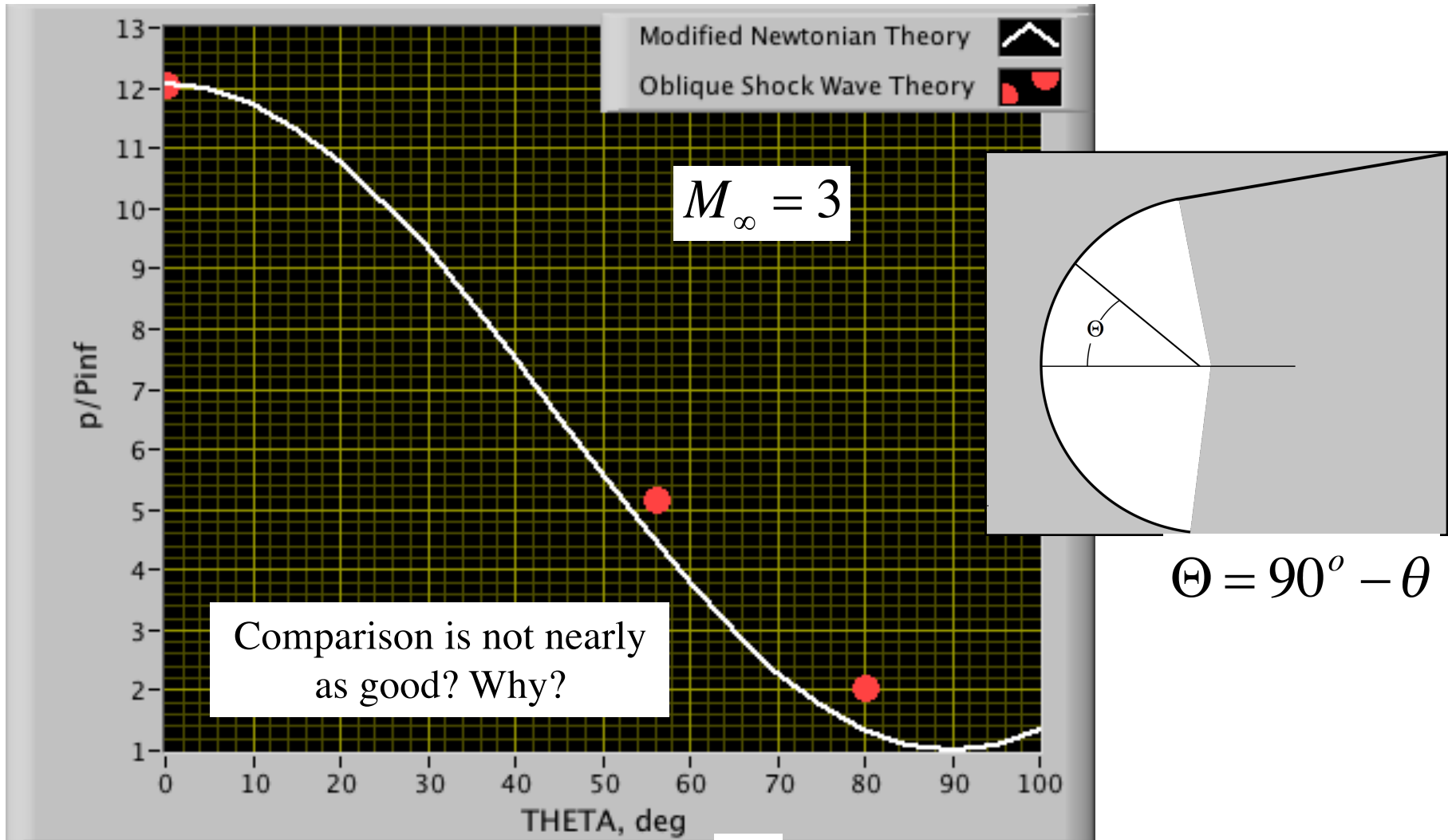
Repeat Oblique Shock Calculations at

$$M_\infty = 3$$

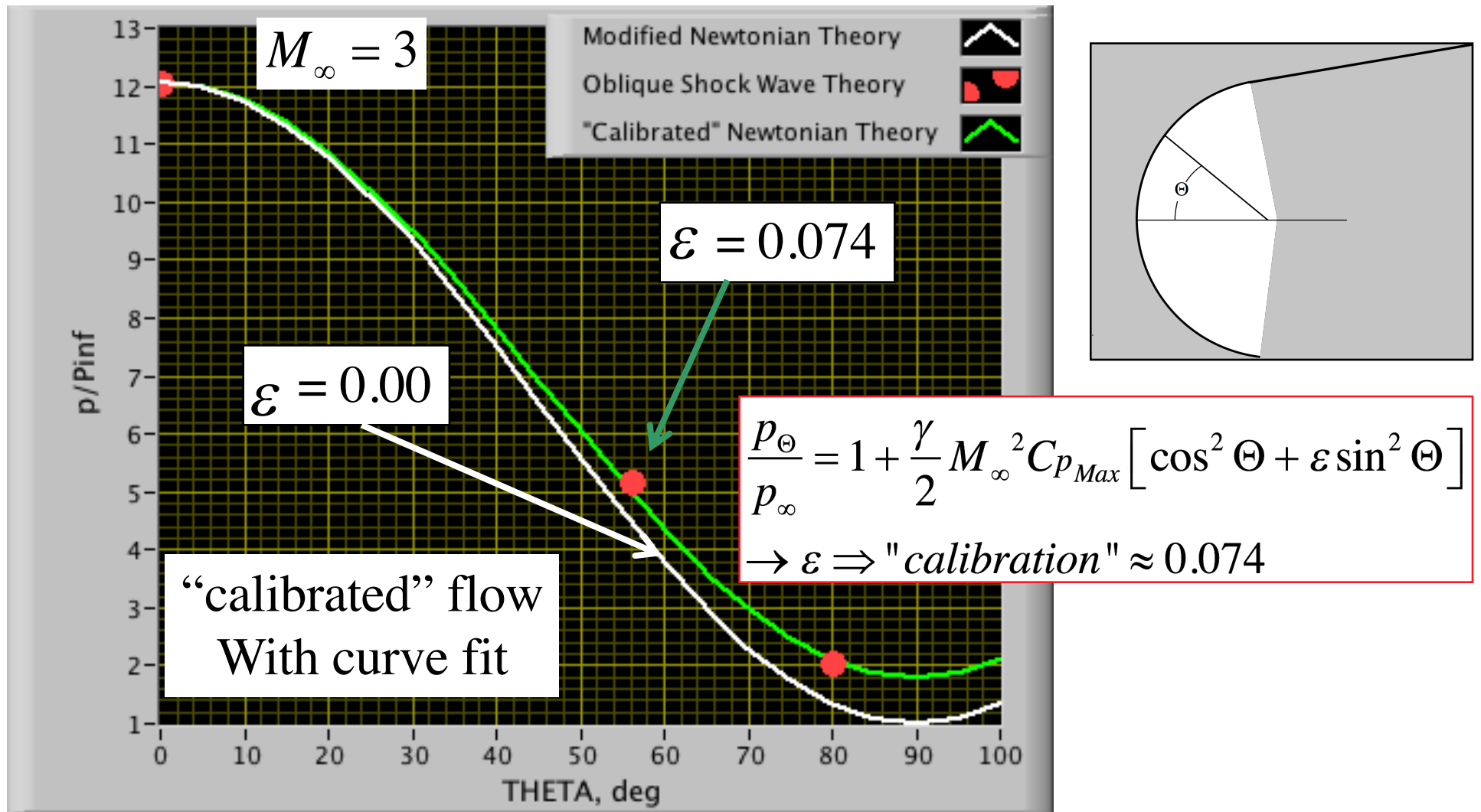


Point on Shock	beta, deg β	theta, deg θ	90°-theta Θ	$\frac{p_\theta}{p_\infty}$
a	90°	90°	0°	12.06
d	63.77°	34.01°	55.99°	5.18
g	27.38°	10°	80°	2.05

Surface Conditions behind detached shock wave: *Mach 3.0*



Surface Conditions behind detached shock wave: *Mach 3*



Surface Conditions behind detached shock wave: *Surface plot*

- In limit as $M \rightarrow \infty$ Modified Newtonian flow model is
A good descriptor of the local surface pressures

$$\frac{p_{\Theta}}{p_{\infty}} = 1 + \frac{\gamma}{2} M_{\infty}^2 C_{p_{Max}} \cos^2 \Theta$$

- At lower Mach numbers we include a “calibration” term

$$\frac{p(\Theta)}{p_{\infty}} = 1 + \frac{\gamma}{2} \cdot M_{\infty}^2 \cdot C_{p_{max}} \cdot \left[\cos^2(\Theta) + \varepsilon \cdot \sin^2(\Theta) \right]$$

Modified Newtonian Flow, Concluded

- Writing in terms of pressure coefficient

$$C_p(\Theta) = \frac{p(\Theta) - p_\infty}{\frac{\gamma}{2} \cdot p_\infty \cdot M_\infty^2} = C_{p_{\max}} \cdot \left[\cos^2(\Theta) + \varepsilon \cdot \sin^2(\Theta) \right]$$

$$C_{p_{\max}} \cdot \left[\cos^2 \Theta + \varepsilon \cdot (1 - \cos^2 \Theta) \right] = C_{p_{\max}} \cdot \left[(1 - \varepsilon) \cdot \cos^2 \Theta + \varepsilon \right]$$

or...

$$C_p(\theta) = \frac{p(\theta) - p_\infty}{\frac{\gamma}{2} \cdot p_\infty \cdot M_\infty^2} = C_{p_{\max}} \cdot \left[\sin^2(\theta) + \varepsilon \cdot \cos^2(\theta) \right] = C_{p_{\max}} \cdot \left[(1 - \varepsilon) \cdot \sin^2(\theta) + \varepsilon \right]$$

- “Calibrated Newtonian Flow”

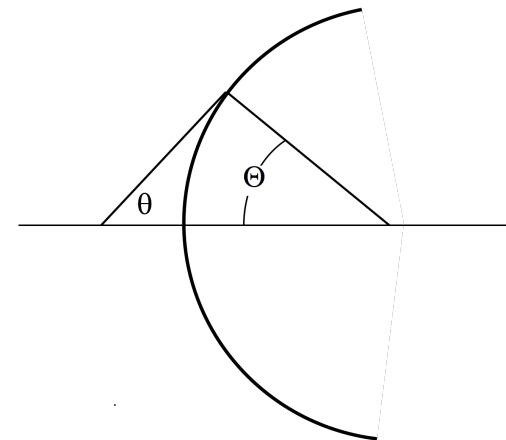
Semi-empirical model

Valid for very high speeds, 3-D

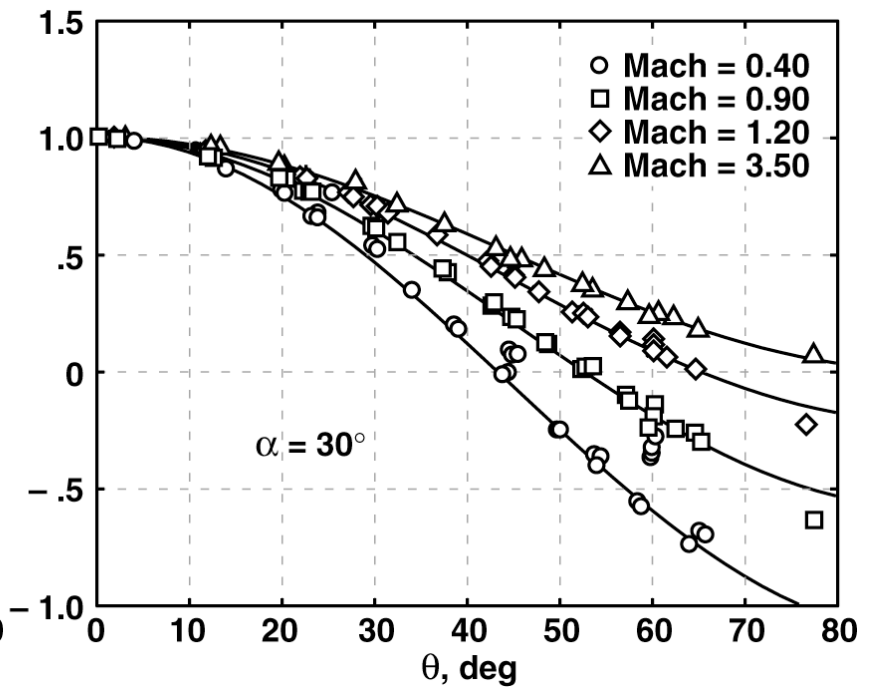
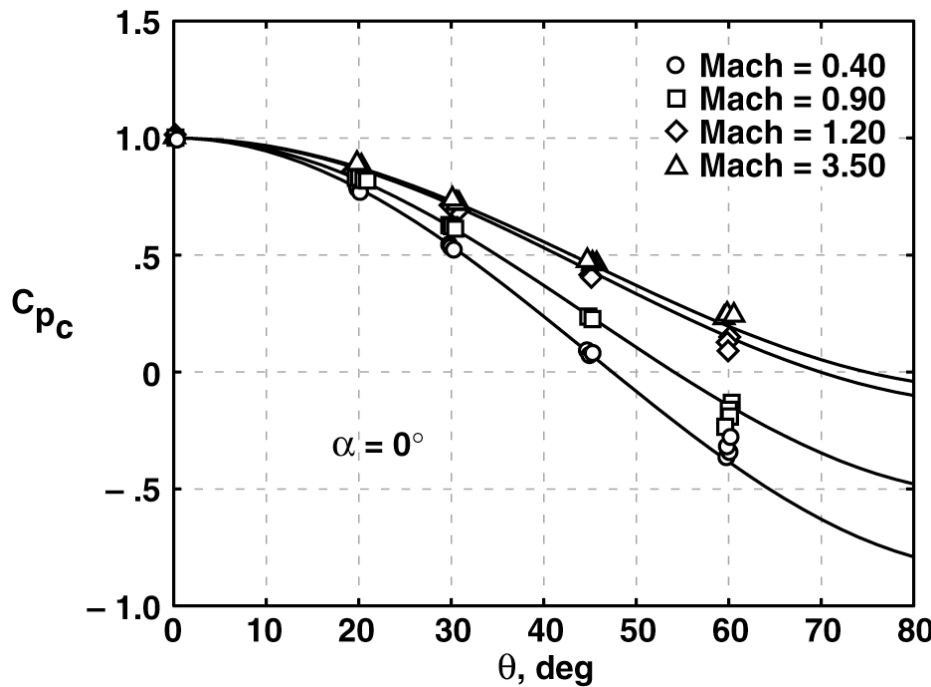
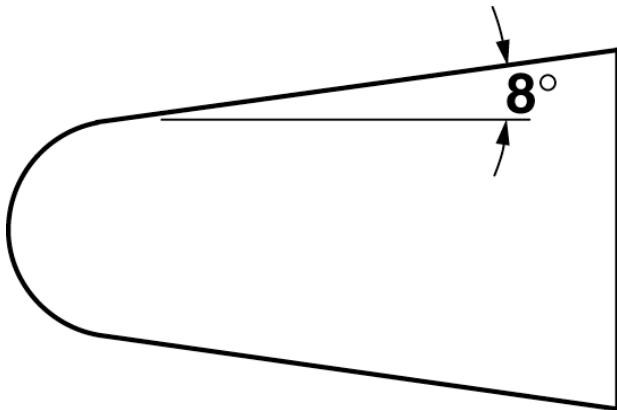
And 2-D blunt bodies ... accurate

For both sonic and supersonic regions

Behind detached shock wave



Calibration Examples: 8-deg Cone



More Calibration Examples

Analytical

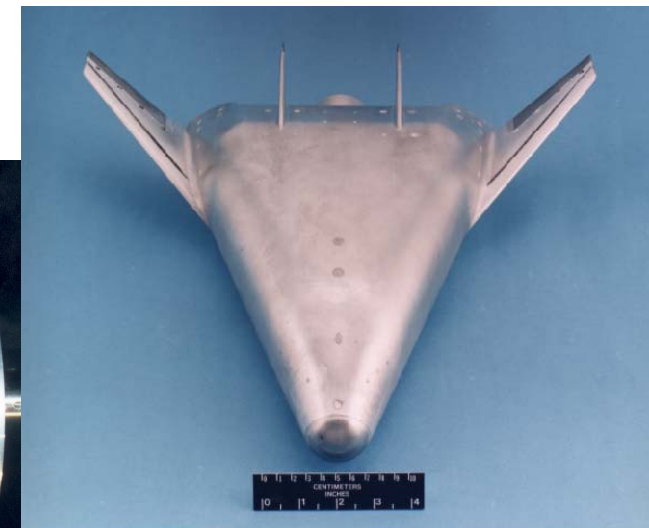
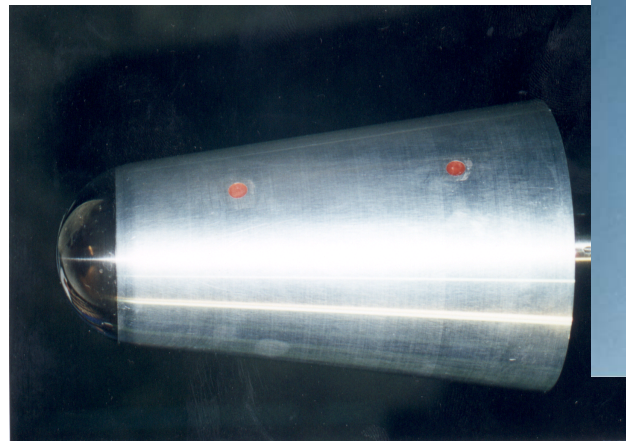
- Potential solutions: sphere, cylinder, arbitrary ellipsoid

Wind Tunnel

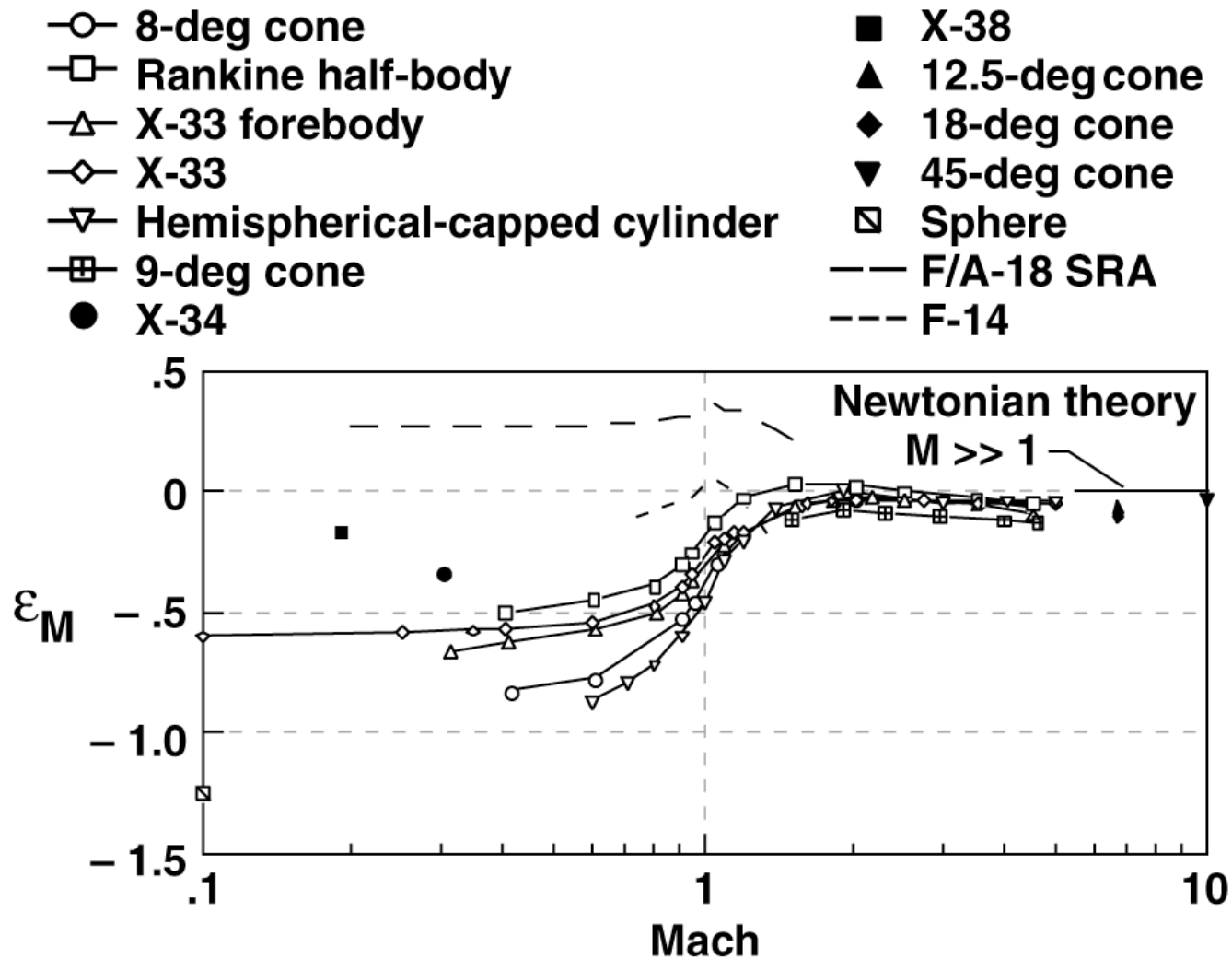
- 8-deg sphere-cone, Rankine half-body, X-33 forebody ($M=.3 - 4.75$)
- 9, 12.5, 18, and 45-deg sphere cones
- X-33
- X-34
- X-38
- Sphere

Flight Data

- F/A-18 SRA
- F-14



Mach Effect on Calibration (ϵ):

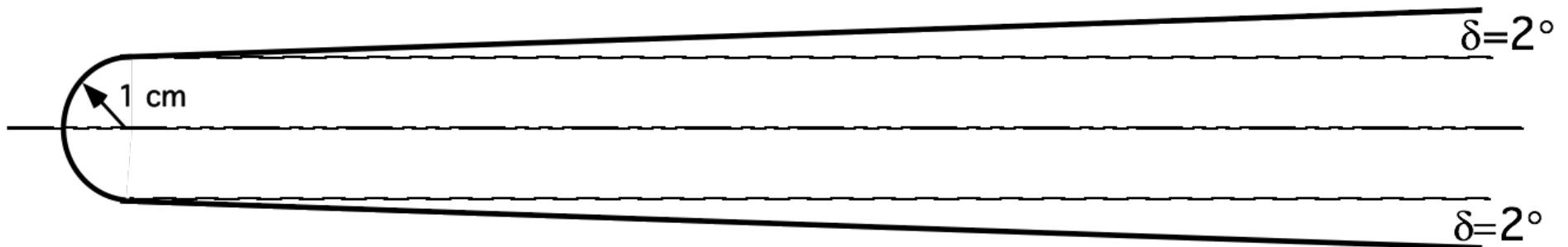


Bottom Line

- Even though flow across detached shock wave is extremely complex and is difficult to model theoretically, it turns out that simple engineering models do a good job with the pressure distribution
- Allow the drag due to detached shock wave to be estimated using very simple tools

Homework 7.1, Blunt Edge Drag

- Consider a 2° angle (δ) diamond-wedge wing, 2 meter chord (c),
With A spherically blunted leading edge with a 1 cm radius (R)



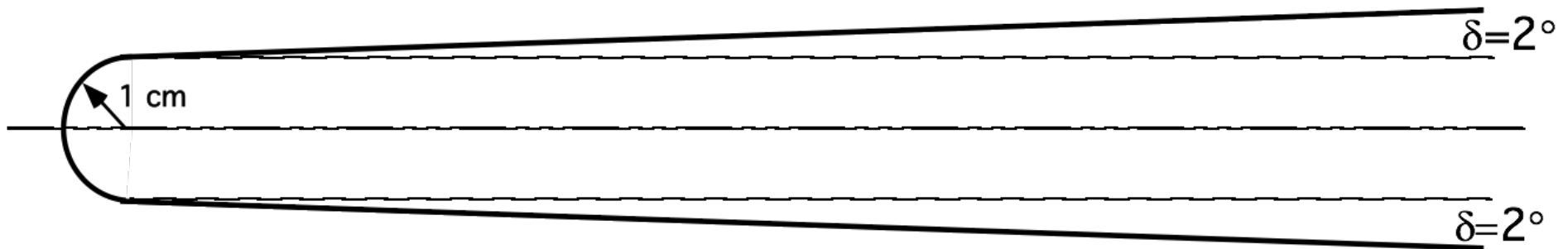
- Show that in general, the drag coefficient due to the the blunt leading edge is:

$$C_{D_{LE}} = \int_{-\left(\frac{\pi}{2}-\delta\right)}^{\left(\frac{\pi}{2}-\delta\right)} C_p(\Theta) \cos(\Theta) \frac{R}{c} d\Theta$$

Homework 7.1, Blunt Edge Drag (cont'd)

- Use the calibrated Newtonian Model

$$C_p(\Theta) = C_{p_{\max}} \left[\cos^2(\Theta) + \varepsilon \sin^2(\Theta) \right] = C_{p_{\max}} \cdot \left[(1 - \varepsilon) \cdot \cos^2 \Theta + \varepsilon \right]$$



... calculate the leading edge drag coefficient
at $M_\infty = 3.0$ ($\varepsilon \sim 0.074$) AND $M_\infty = 10.0$ ($\varepsilon \sim 0.00$)

- Compare to wave drag coefficient and skin drag coefficient (referenced to plan area) for the same conditions at 25 km altitude

Questions??

